

AMSU-A VERIFICATION TEST REPORT

TEST ITEM:

AMSU- A1 ANTENNA DRIVE SUBSYSTEM
PART OF P/N: 1331720-2
SERIAL NUMBER : 105

LEVEL OF ASSEMBLY:

SUBASSEMBLY AND COMPLETE INSTRUMENT
ASSEMBLY

TYPE HARDWARE:

FLIGHT

VERIFICATION:
PROCEDURE NO.

AE-26002/1D

TEST DATE:

SUBSYSTEM:

START DATE: 06 June 1998
FINISH DATE: 15 June 1998

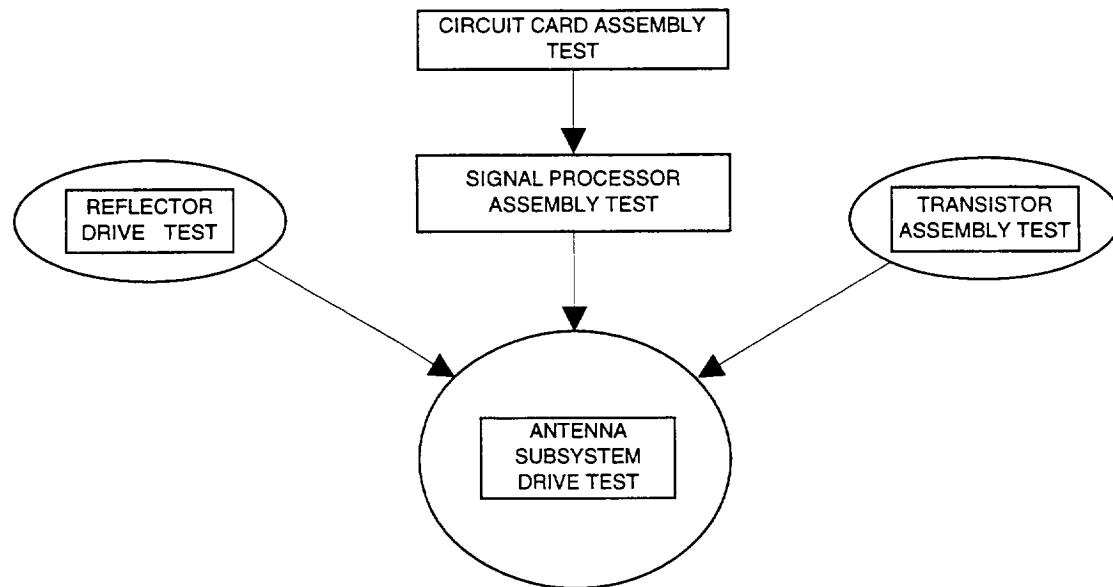
1.0 INTRODUCTION

An antenna drive subsystem test was performed on the METSAT AMSU-A1, S/N 105 instrument. The objective of the test was to demonstrate compliance with applicable paragraphs of AMSU-A specifications S-480-80. Tests were conducted at both the subassembly and instrument level.

2.0 SUMMARY

The antenna drive subsystem of the METSAT AMSU-A1, S/N105, P/N 1331720-2 completed acceptance testing per AES Test Procedure AE-26002/1D. The test included: Scan Motion and Jitter, Pulse Load Bus Peak Current and Rise Time, Resolver Reading and Position Error, Gain/ Phase Margin, and Operational Gain Margin.

The drive motors and electronic circuitry were also tested at the component level. The drive motor test includes: Starting Torque Test, Motor Commutation Test, Resolver Operation/ No-Load Speed Test, and Random Vibration. The electronic circuitry was tested at the Circuit Card Assembly (CCA) level of production; each test exercised all circuit functions. The transistor assembly was tested during the W3 cable assembly (1356424-1) test. Refer to Figure 1 for test flow.



Antenna Subsystem and Subsystem Component Test Flow
Figure 1.

The antenna drive subsystem satisfactorily passed all of the performance requirements. There were no failures in any of the antenna drive components during subsystem testing.

The results of the subsystem and component level testing are discussed in more detail in the following sections:

Reflector Drive Assembly	5.1
Circuit Card Assemblies.....	5.2
Signal Processor	5.3
Transistor Assembly	5.4
Antenna Drive Subsystem....	5.5

3.0 TEST CONFIGURATION

The **Reflector Drive Assembly Tests** confirm the operability of the motor under test. The test configuration includes, the motor, motor shaft, bearings, and a supporting housing.

The **Circuit Card Assembly (CCA) Tests** confirm the operability of each CCA. Each test includes the CCA under test, electronic test fixtures, and the necessary loads.

A segment of the **Signal Processor Tests** ensures the scan drive electronics are functioning properly prior to it's assembly into the instrument. The test configuration includes:

- Timing and Control CCA
- Scan Control Interface CCA
- Mux/ Relay Control CCA
- Interface Converter CCA
- Resolver Data Isolator CCA
- R/D Converter CCA
- Motor Driver CCA
- Test fixture and cabling to interrogate and analyze positional data
- Test motor and inertia wheel

The **Transistor Assembly Test** verifies the correct wiring of the transistor assembly and associated cabling. Test configuration includes the CKT 1000 (continuity and Hi-Pot tester), and test fixtures.

The Antenna Drive Subsystem Tests:

- Are configured with the same motor control CCA's used in the signal processor test, interconnecting wiring, the power transistor assembly, and the drive assembly with reflector.
- The antenna drive subsystem components were all installed in the instrument when the subsystem test was performed.
- DC power for the motor control circuit cards was provided by a DC/DC converter simulator P/N: 1359322-1. The simulator operates on 120VAC facility supplied

- **Reflector Drive Motors (A1-1) and (A1-2)**- were both observed to have the thermisters wired in reverse order causing the resistance and voltage readings to be 14.6 Kohms and 19.6 Vdc respectively instead of the required 2.66 to 3.24 Kohms and 3.9 to 4.77 Vdc. The terminal boards were repaired and re-tested satisfactorily. The process planning was altered to reduce the risks of recurrence.

All other components designated for use in the METSAT AMSU-A1 instrument (pertaining to the scan drive circuitry) passed on the first time through component testing.

5.1 REFLECTOR DRIVE ASSEMBLIES

The tests performed on this unit are: Starting Torque Test, Motor Commutation Test, Resolver Operation/ No-Load Speed Test, and Random Vibration. The Motor Commutation and Resolver Operation tests are performed both pre and post-vibration.

Starting Torque

The starting torque test is performed on the rotating segment of the drive assembly to verify the torque associated with bearing friction. Reflector drive assemblies (F06 & F07) passed the starting torque test at ambient temperature as well as at the colder plateaus first time through testing.

Motor Commutation Test

This test is performed to determine the commutation characteristics of the motor under test. Both reflector drive assemblies (F06 & F07) passed the motor commutation test both pre- and post-vibration tests without incident.

Resolver Operation/ No-Load Speed Test

This test is performed to verify resolver operation as well as speed characteristics and back electromotive force of the motor. Both reflector drive assemblies (F06 & F07) passed the resolver operation/ no-load speed test both pre- and post-vibration tests without incident.

Random Vibration

Reflector drive assemblies (F06 & F07) passed vibration testing first time through. The motor assembly also passed the pre- and post-vibration electronic tests as well as the post-vibration visual inspection without incident.

5.2 CIRCUIT CARD ASSEMBLIES

Test procedures were prepared for each motor control circuit card; document revision status is controlled by reference in the shop order. The cards were individually tested to the procedures and results were recorded on data sheets found in Appendix A. The following list indexes the CCA Test Data Sheets:

- *Appendix A1* *Resolver Data Isolator Assembly (A1-1)*
- *Appendix A2* *Resolver Data Isolator Assembly (A1-2)*
- *Appendix A3* *Interface Converter Assembly (A1-1)*
- *Appendix A4* *Interface Converter Assembly (A1-2)*
- *Appendix A5* *Motor Driver Assembly (A1-1)*
- *Appendix A6* *Motor Driver Assembly (A1-2)*
- *Appendix A7* *R/D Converter/ Oscillator Assembly (A1-1)*
- *Appendix A8* *R/D Converter/ Oscillator Assembly (A1-2)*

All circuit card assemblies passed testing the first time through. The assembly build shop orders contain the part number and accept tag record the of test and select resistors.

5.3 SIGNAL PROCESSOR

For the first time, the entire antenna drive motor electronics is mated together. The test instrumentation commands and interrogates the electronics during this segment of testing. The instrumentation sends position commands to the Interface Converter CCA. The Interface Converter D/A's the command and provides inputs to the Motor Driver CCA. The test motor (instrumentation) responds to the drive signal and feeds back positional data via resolver outputs. The instrumentation then interrogates the Resolver Data Isolator CCA for position data. A comparison is made in the instrumentation between the position command sent and the actual position received. The pass/ fail indication is presented to the operator for test data sheet recording.

The signal processor assembly (F01) failed one segment of the test procedure relating to the A1-2 scan drive. The failure (-15V to +10V power supply short) was attributed to a loose, bare wire found in the backplane. The bare wire was removed and another power distribution check was conducted; no further failures were found. The test procedure for the A1-2 scan drive was re-performed without incident.

5.4 TRANSISTOR ASSEMBLY

All transistor assemblies are tested along with their respective W3 cable. The cable is continuity, then hi-pot tested prior to attaching the transistor circuitry. Each transistor pair is exercised validating the turn on voltage, current drawn, and cable wiring as well. The W3 cable and transistor assembly underwent component testing and passed without incident.

5.5 ANTENNA SUBSYSTEM DRIVE TESTS

The antenna drive motor electronics mates with the instrument microprocessor for the first time during this segment of testing. The microprocessor sends position commands from the memory CCA to the Interface Converter CCA. The Interface Converter D/A's the command and provides inputs to the Motor Driver CCA. The Reflector Drive Motor responds to the drive signals and feeds back positional data via the resolver outputs. The microprocessor then interrogates the Resolver Data Isolator CCA for position data.. The microprocessor in turn communicates with the spacecraft interface.

During other segments of the test, positional data is monitored via a potentiometer attached to the shaft of each reflector drive assembly. This provides scan characteristic information in regard to overshoot, jitter, and beam position transition timing for each motor assembly.

The remaining paragraphs in this section discuss tests that ensures the instrument complies with specific operating parameters. Prior to conducting these tests there is a series of preliminary checks that are run to select component values that customize the operating parameters of each motor. These checks perform the following functions:

- Program “on board” memory with Beam Position Pointing Angles for each reflector drive assembly
- Adjust for peak Motor Current Limits on both A1-1 and A1-2 motor drive circuits
- Observe Preliminary Scan Dynamics on both A1-1 and A1-2 motor drive circuits
- Identify Mechanical Resonant Frequencies of each reflector drive assembly

Beam Position Pointing Angles are calculated from Nadir pointing direction which is determined on the antenna range. The instrument’s EPROMs (EPROMs for testing; PROMs for final configuration) are programmed to reflect the position commands. The initial programming may require fine tuning; fine tuning is determined during the remaining segments of the test procedure.

Motor Current Limits were adjusted, via selecting “test and select” resistors, to comply with the specification requirement; less than 1 amp peak current.

Preliminary Scan Dynamics looked good; transition times, overshoot and jitter were all acceptable at the sampled pointing directions (5).

The **Mechanical Resonant Frequencies** were identified; notch filters were calculated and installed to compensate for these resonant frequencies.

5.5.1 SCAN MOTION AND JITTER

In this test, the antenna position was measured in a series of five 8-sec full scans. The measurement was made with a 1-turn test potentiometer temporarily affixed to the rear end of the motor shaft. A Dynamic Signal Analyzer (DSA) was connected to the pot wiper to record the antenna position data. Five scans of each A1-1 and A1-2 were captured and stored on the AMSU-A1 Test Data File disc. One representative waveform from each subassembly is presented in Appendix B1 (A1-1) and Appendix B34 (A1-2).

Each 3.33 degrees scene step was expanded and checked for both a 35 msec max step time, and a 165 msec integration period. Expanded waveforms were plotted and are presented in Appendix B2 thru B31 for the A1-1 subassembly and Appendix B35 thru B64 for the A1-2 subassembly. All of the scene steps meet the step response requirement for transition time, overshoot, and jitter.

Slew periods to the cold and warm calibration stations were measured and met requirements. A time of 0.21 sec is allocated for the 35.0 degree slew to cold cal, and 0.40 sec for the 96.67 degree slew to warm cal. Calibration station jitter was less than the $\pm 5\%$ maximum permitted. Expanded waveforms for each subassembly were plotted and are presented in Appendix B32 and B33 (A1-1) and Appendix B65 and B66 (A1-2). The waveforms are also stored on the AMSU-A1 Test Data File disc. The test data sheets are presented in Appendix B67 (A1-1) and B68 (A1-2); as an extension of these data sheets, more detailed data (concerning rise time, overshoot and jitter) is presented on Appendix page B67-E and B68-E.

5.5.2 PULSE LOAD BUS PEAK CURRENT AND RISE TIME

The Pulse Load pulse load bus peak current and the rate of change of current were measured. The peak current must be less than 1A at any beam position along the scan. Peak current along the scan is .996A. The current rate of change while transitioning from one beam position to the next (including the transition to the cold calibration and warm calibration targets) should be greater than 35 microseconds. A random 3.33° step was selected; the transition to the next step was 1.2 ms. The transition to the warm cal position start and stop was significantly longer than the required 35 ms; 1.2 and 5.5 ms respectively.

The peak bus current was measured across the entire scan and met the requirement. The full scan waveform was plotted and is presented in Appendix C1. The waveform is also stored on the AMSU-A1 Test Data File disc. The test data sheet is presented in Appendix C2.

5.5.3 RESOLVER READING AND POSITION ERROR

The 14-bit command position word is stored in the “on-board” memory and is read to the motor drive circuitry under microprocessor program control. The microprocessor also reads the resolver output at each of the thirty scene stations, and at the cold and warm calibration positions. The readings are made at the start of integration (LOOK 1), and halfway into the integration period (LOOK 2). The resolver data is sent to the spacecraft interface for subsequent transmission to the STE.

The purpose of this portion of the test is to demonstrate that the antenna is meeting beam pointing requirements.

If the antenna is out of the pointing tolerance of $> \pm 10$ counts at LOOK 1 or $> \pm 5$ counts at LOOK 2, the EPROM is reprogrammed to bring the pointing direction to within the prescribe tolerances. A copy of the STE computer print out showing the pointing direction is shown in Figure 2 for the A1-1 subassembly and Figure 3 for the A1-2 subassembly.

BP	Command	Actual		Difference*	
		Look 1	Look2	Look 1	Look2
1	26	27	27	-1	-1
2	178	182	177	-4	1
3	330	337	329	-7	1
4	481	485	481	-4	0
5	633	639	633	-6	0
6	785	792	785	-7	0
7	936	942	936	-6	0
8	1088	1094	1088	-6	0
9	1240	1249	1240	-9	0
10	1391	1398	1391	-7	0
11	1543	1547	1543	-4	0
12	1695	1701	1695	-6	0
13	1846	1851	1845	-5	1
14	1998	2005	1998	-7	0
15	2150	2156	2149	-6	1
16	2301	2306	2300	-5	1

BP	Command	Actual		Difference*	
		Look 1	Look2	Look 1	Look2
17	2453	2459	2452	-6	1
18	2605	2612	2604	-7	1
19	2756	2762	2756	-6	0
20	2908	2913	2908	-5	0
21	3060	3068	3060	-8	0
22	3211	3212	3210	-1	1
23	3363	3369	3362	-6	1
24	3515	3523	3514	-8	1
25	3666	3672	3666	-6	0
26	3818	3824	3817	-6	1
27	3970	3977	3969	-7	1
28	4121	4129	4120	-8	1
29	4273	4277	4273	-4	0
30	4425	4432	4425	-7	0
CC 1	6019	6021	6021	-2	-2
WC	10418	10420	10420	-2	-2

* Difference between Command and Actual

Figure 2. Beam Position Pointing Directions and Error Calculation for A1-1

BP	Command	Actual		Difference*	
		Look 1	Look2	Look 1	Look2
1	16211	16212	16212	-1	-1
2	16363	16368	16362	-5	1
3	131	134	128	-3	3
4	282	288	281	-6	1
5	434	439	433	-5	1
6	586	593	585	-7	1
7	737	743	736	-6	1
8	889	895	888	-6	1
9	1041	1048	1040	-7	1
10	1192	1197	1192	-5	0
11	1344	1350	1343	-6	1
12	1496	1502	1496	-6	0
13	1647	1653	1646	-6	1
14	1799	1804	1799	-5	0
15	1951	1959	1950	-8	1
16	2102	2107	2101	-5	1

BP	Command	Actual		Difference*	
		Look 1	Look2	Look 1	Look2
17	2254	2260	2253	-6	1
18	2406	2412	2405	-6	1
19	2557	2562	2556	-5	1
20	2709	2715	2708	-6	1
21	2861	2867	2860	-6	1
22	3012	3018	3011	-6	1
23	3164	3170	3163	-6	1
24	3316	3324	3315	-8	1
25	3467	3473	3466	-6	1
26	3619	3626	3618	-7	1
27	3771	3778	3771	-7	0
28	3922	3928	3921	-6	1
29	4074	4079	4073	-5	1
30	4226	4229	4222	-3	4
CC 1	5820	5820	5820	0	0
WC	10219	10220	10220	-1	-1

* Difference between Command and Actual

Figure 3. Beam Position Pointing Directions and Error Calculation for A1-2

5.5.4 GAIN/PHASE MARGIN

A gain/phase margin test was performed on the antenna drive subsystem. The test was performed by obtaining a Bode plot of the control loop and measuring the gain at 180° phase differential and the phase margin at the 0db crossover point.

The Dynamic Signal Analyzer (DSA) was used to make the measurement operating in the swept sine mode. Three separate Bode plots were made on the antenna and the gain and phase margins were determined from each plot. The gain margin measured was 13.08 db (average of three) for the A1-1 subsystem and 12.78 db (average of three) for the A1-2 subsystem. The phase margin measured was 64.7° (average of three) for the A1-1 subsystem and 64.1° (average of three) for the A1-2 subsystem. These margins exceed the specification requirements of 9.2 db and 25 degrees and therefore are acceptable. The three Bode waveforms were plotted and are presented in Appendix D1 thru D3 for the A1-1 subsystem and Appendix D4 thru D6 for the A1-2 subsystem. The waveforms are also stored on the AMSU-A1 Test Data File disc. The test data sheets are presented in Appendix D7and D8 for A1-1 and A1-2 respectively.

5.5.5 OPERATIONAL GAIN MARGIN

An operational gain margin test was performed on the instrument three times. This test consists of increasing the gain of the control loop until oscillation occurs. The gain increase and frequency of oscillation are measured. An increase in gain greater than 8 db is required; the frequency of oscillation is an observation.

A 50K pot was connected in series with the R58 feedback resistor on amplifier AR8. The resistance of the test pot was slowly added to the feedback resistor while observing the reflector for oscillations.

The reflector begins to produce an audible sound as gain is increased. The following added resistance values are calculated to have the following gain margins for the A1-1 and A1-2 subsystems:

Resistance (ohms)	Gain
35.93 K	9.0 db
37.34 K	9.2 db
37.39 K	9.2 db

A1-1

Resistance (ohms)	Gain
38.90 K	9.4 db
37.56 K	9.2 db
37.61 K	9.2 db

A1-2

The first mode mechanical resonance of the shaft and reflector is about 161 Hz for the A1-1 subsystem. The power spectrum waveform was plotted and is presented in Appendix E1. The first mode mechanical resonance of the shaft and reflector is about 172 Hz for the A1-2 subsystem. The power spectrum waveform was plotted and is presented in Appendix E2. These waveforms are also stored on the AMSU-A1 Test Data File disc. The test data sheets are presented in Appendix E3 and E4 for the A1-1 and A1-2 subsystems respectively.

6.0 CONCLUSION

Based on the test results, it can be concluded that the METSAT AMSU-A1 S/N 105 antenna drive subsystem meets the AMSU-A specification requirements.

7.0 TEST DATA

Test data for the METSAT AMSU-A1 S/N 105 obtained in the antenna drive subsystem test is attached. Data sheet number and type of test is shown in the following Appendix Index.

APPENDIX INDEX

- Appendix A1 Resolver Data Isolator CCA TDS (A1-1)*
Appendix A2 Resolver Data Isolator CCA TDS (A1-2)
Appendix A3 Interface Converter CCA TDS (A1-1)
Appendix A4 Interface Converter CCA TDS (A1-2)
Appendix A5 Motor Driver CCA TDS (A1-1)
Appendix A6 Motor Driver CCA TDS (A1-2)
Appendix A7 R/D Converter/ Oscillator CCA TDS (A1-1)
Appendix A8 R/D Converter/ Oscillator CCA TDS (A1-2)
- Appendix B1 Full Scan Step Response (A1-1)*
Appendix B2 thru B31 Single Step Responses (A1-1)
Appendix B32 Cold Calibration Step Response (A1-1)
Appendix B33 Warm Calibration Step Response (A1-1)
Appendix B34 Full Scan Step Response (A1-2)
Appendix B35 thru B64 Single Step Responses (A1-2)
Appendix B65 Cold Calibration Step Response (A1-2)
Appendix B66 Warm Calibration Step Response (A1-2)
Appendix B67 Scan Motion Jitter Test TDS (A1-1)
Appendix B68 Scan Motion Jitter Test TDS (A1-2)

Appendix C1 Peak Pulse Load Bus Current Waveform

Appendix C2 Pulse Load Bus Current TDS

Appendix D1 thru D3 Gain/ Phase Margin Bode Plots (A1-1)

Appendix D4 thru D6 Gain/ Phase Margin Bode Plots (A1-2)

Appendix D7 Gain/ Phase Margin TDS (A1-1)

Appendix D8 Gain/ Phase Margin TDS (A1-2)

Appendix E1 Operational Gain Margin Power Spectrum (A1-1)

Appendix E2 Operational Gain Margin Power Spectrum (A1-2)

Appendix E3 Operational Gain Margin TDS (A1-1)

Appendix E4 Operational Gain Margin TDS (A1-2)

APPENDIX A

***TEST DATA SHEETS FOR SCAN DRIVE CIRCUIT
CARD ASSEMBLIES***

TEST DATA SHEET B-6 (Sheet 1 of 2)

RESOLVER DATA ISOLATOR CCA (P/N 1334972) (Paragraph 6.6.7)

Date: 4/14/97
S/N: F-20
1334972-1

6.6.7.1 Supply Voltages

Supply*	Measured Value (V)	Limits (Vdc)	Pass/Fail
+5 V (I)	5.00	± 0.25	P
+5 V (U)	5.03	± 0.25	P

6.6.7.2 Supply Currents

Steps 1 and 2:

Supply*	Measured Value (mA)	Limits (mA)	Pass/Fail
+5 V (I)	53.13	100 max	F
+5 V (U)	329.00	400 max	P

Steps 3 and 4:

Supply*	Measured Value (mA)	Limits (mA)	Pass/Fail
+5 V (I)	83.03	150 max	P
+5 V (U)	11.99	30 max	P

* I = Isolated, U = Unisolated

6.6.7.3 Resolver Data

Bit No.	Pass/Fail
API 0 - AP Bit 0	P
API 1 - AP Bit 1	P
API 2 - AP Bit 2	P
API 3 - AP Bit 3	P
API 4 - AP Bit 4	P
API 5 - AP Bit 5	P
API 6 - AP Bit 6	P
API 7 - AP Bit 7	P
API 8 - AP Bit 8	P
API 9 - AP Bit 9	P
API 10 - AP Bit 10	P
API 11 - AP Bit 11	P
API 12 - AP Bit 12	P
API 13 - AP Bit 13	P

6.6.7.4 Converter Busy Pulse

Converter Busy Pulse	Measured Value (μsec)	Limits (μsec)	Pass/Fail
15.0	14.9 14.75 plus	± 3.0	P

4/16/97

TEST DATA SHEET B-6 (Sheet 2 of 2)

RESOLVER DATA ISOLATOR CCA (P/N 1334972) (Paragraph 6.6.7)

Comments:

NONE

Conducted by:

Dennis Linn

Test Engineer

4/14/97

Date

Verified by:

Judie H. Herren

Quality Control Inspector

4/16/97

Date

Approved by:

DMC

4/16/97

Date

TEST DATA SHEET B-6 (Sheet 1 of 2)

RESOLVER DATA ISOLATOR CCA (P/N 1334972) (Paragraph 6.6.7)

Date: 4/15/97
S/N: F36

6.6.7.1 Supply Voltages

Supply*	Measured Value (V)	Limits (Vdc)	Pass/Fail
+5 V (I)	5.00	± 0.25	P
+5 V (U)	5.01	± 0.25	P

6.6.7.2 Supply Currents

Steps 1 and 2:

Supply*	Measured Value (mA)	Limits (mA)	Pass/Fail
+5 V (I)	53.54	100 max	P
+5 V (U)	326.00	400 max	P

Steps 3 and 4:

Supply*	Measured Value (mA)	Limits (mA)	Pass/Fail
+5 V (I)	83.39	150 max	P
+5 V (U)	11.06	30 max	P

* I = Isolated, U = Unisolated

6.6.7.3 Resolver Data

Bit No.	Pass/Fail
API 0 - AP Bit 0	P
API 1 - AP Bit 1	P
API 2 - AP Bit 2	P
API 3 - AP Bit 3	P
API 4 - AP Bit 4	P
API 5 - AP Bit 5	P
API 6 - AP Bit 6	P
API 7 - AP Bit 7	P
API 8 - AP Bit 8	P
API 9 - AP Bit 9	P
API 10 - AP Bit 10	P
API 11 - AP Bit 11	P
API 12 - AP Bit 12	P
API 13 - AP Bit 13	P

6.6.7.4 Converter Busy Pulse

Converter Busy Pulse	Measured Value (μsec)	Limits (μsec)	Pass/Fail
15.0	14.15	± 3.0	P

TEST DATA SHEET B-6 (Sheet 2 of 2)

RESOLVER DATA ISOLATOR CCA (P/N 1334972) (Paragraph 6.6.7)

Comments:

None

Conducted by:

Dennis Lien
Test Engineer

4/14/97
Date

Verified by:

Suzanne Harvey
Quality Control Inspector

4-14-97
Date

Approved by:

DCMC

4/14/97
Date

TEST DATA SHEET B-13 (Sheet 1 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

Date: 8/12/97
CCA S/N: F28
133 1697-1

6.13.7.1 Supply Voltages

Supply	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
+5V (U)	5.02	+5V± 0.05	P
+15V (I)	15.01	+15V± 0.15	P
-15V (I)	-14.97	-15V± 0.15	P
+5V (I)	5.02	+5V± 0.05	P

6.13.7.2 Supply Currents

Step 1 (CP and API Low):

Supply	Measured Value (mA)	Limits (mA)	Pass/Fail
+5V (U)	86.61	70 - 110	P
+5V (I)	3.41	1.5 - 5.5	P
+15V (I)	18.33	15 - 23	P
-15V (I)	21.10	18 - 26	P

Step 2 (CP and API High):

Supply	Measured Value (mA)	Limits (mA)	Pass/Fail
+5V (U)	56.67	40 - 70	P
+5V (I)	23.98	18 - 30	P
+15V (I)	18.34	15 - 23	P
-15V (I)	21.09	18 - 26	P

6.13.7.3 Amplifier Offsets

Amplifier	Measured Value (mV)	Limits (mV)	Pass/Fail
AR1	+0.13	0.0±0.15	P
AR2	+0.50	0.0±2.0	P

TEST DATA SHEET B-13 (Sheet 2 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

6.13.7.4 Subtraction and D-A Conversion

unfunneled
9-10-97
 ± 0.00015
 ± 0.00060
 ± 0.00030

Step 1:

Actual Position (API) MSB LSB	Command Position (CP) MSB LSB	AR1 Output Voltage Required (Vdc)	Test Result (Vdc)	Pass/Fail
0000000000000000	0000000000000000	0.00000	0.00013	P
0000000000000001	0000000000000000	-0.00061	-0.000373	P
0000000000000010	0000000000000000	-0.00122	-0.001005	P
0000000000000011	0000000000000000	-0.00184	-0.001650	P
00000000000000100	0000000000000000	-0.00245	-0.002286	P
0000000000001000	0000000000000000	-0.00490 *	-0.004830	P
0000000001000000	0000000000000000	-0.00979 *	-0.009916	P
0000000001000000	0000000000000000	-0.01958 *	-0.020083	P
0000000010000000	0000000000000000	-0.03917 *	-0.040416	P
0000000100000000	0000000000000000	-0.07834 *	-0.081095	P
0000001000000000	0000000000000000	-0.15667 *	-0.16244	P
0000100000000000	0000000000000000	-0.31334 *	-0.32512	P
0001000000000000	0000000000000000	-0.62669 *	-0.65057	P
0010000000000000	0000000000000000	-1.25338 *	-1.3015	P
0100000000000000	0000000000000000	-2.50675 *	-2.6032	P
1000000000000000	0000000000000000	-5.01350 *	-5.2065	P

* Tolerance on output voltage is $\pm 10\%$

Step 2:

Actual Position (API) MSB LSB	Command Position (CP) MSB LSB	AR1 Output Voltage Required (Vdc)	Test Result (Vdc)	Pass/Fail
0000000000000000	0000000000000000	0.00000	0.000122	P
0000000000000001	0000000000000001	0.00061	0.000746	P
0000000000000010	0000000000000010	0.00122	0.001388	P
0000000000000011	0000000000000011	0.00184	0.002012	P
00000000000000100	00000000000000100	0.00245	0.002656	P
000000000000001000	000000000000001000	0.00490 *	0.005200	P
0000000000000010000	0000000000000010000	0.00979 *	0.010319	P
00000000000000100000	00000000000000100000	0.01958 *	0.020482	P
000000000000001000000	000000000000001000000	0.03917 *	0.040323	P
0000000000000010000000	0000000000000010000000	0.07834 *	0.08154	P
00000000000000100000000	00000000000000100000000	0.15667 *	0.16287	P
000000000000001000000000	000010000000000000000000	0.31334 *	0.32563	P
0000000000000010000000000	001000000000000000000000	0.62669 *	0.65115	P
00000000000000100000000000	01000000000000000000000000	1.25338 *	1.3017	P
000000000000001000000000000	100000000000000000000000000	2.50675 *	2.6033	P
		-5.01350 *	-5.2065	P

* Tolerance on output voltage is $\pm 10\%$

TEST DATA SHEET B-13 (Sheet 3 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

6.13.7.5 Strobe Function

Step 1: Strobe Low

No E11 Change
with Input CP Changes

Pass/Fail
P

Step 2: Strobe High

E11 Change
with Input CP Changes

Pass/Fail
P

6.13.7.6 Amplifier Gain

	<u>Measured Value (Vdc)</u>	<u>Limits (Vdc)</u>	<u>Pass/Fail</u>
E11	<u>0.32563</u>		<u>P</u>
E10	<u>3.5768</u>		<u>P</u>
E10 Voltage	<u>11.0</u>	10.7 - 11.3	<u>P</u>
E11 Voltage			

6.13.7.7 Ground Isolation

	<u>Measured Value (MΩ)</u>	<u>Limits (MΩ)</u>	<u>Pass/Fail</u>
Pin 91 to Pin 7 DC Resistance	<u>larger than 200 MΩ</u>	>20	<u>P</u>

Comments:

NONG

Conducted by:

Dennis Lewis

8/12/97

Date

OCT 10 '97

Verified by:

Rich Stein 7A
190

Date

Approved by:

Ronald Thomas
DCMC

10/14/97

Date

TEST DATA SHEET B-13 (Sheet 1 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

Date: 8/13/97
CCA S/N: F29
1331697-1

6.13.7.1 Supply Voltages

Supply	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
+5V (U)	5.01	+5V± 0.05	P
+15V (I)	15.01	+15V± 0.15	P
-15V (I)	-14.97	-15V± 0.15	P
+5V (I)	5.02	+5V± 0.05	P

6.13.7.2 Supply Currents

Step 1 (CP and API Low):

Supply	Measured Value (mA)	Limits (mA)	Pass/Fail
+5V (U)	86.52	70 - 110	P
+5V (I)	3.40	1.5 - 5.5	P
+15V (I)	17.63	15 - 23	P
-15V (I)	20.29	18 - 26	P

Step 2 (CP and API High):

Supply	Measured Value (mA)	Limits (mA)	Pass/Fail
+5V (U)	56.54	40 - 70	P
+5V (I)	23.97	18 - 30	P
+15V (I)	17.63	15 - 23	P
-15V (I)	20.29	18 - 26	P

6.13.7.3 Amplifier Offsets

Amplifier	Measured Value (mV)	Limits (mV)	Pass/Fail
AR1	0.147	0.0±0.15	P
AR2	0.800	0.0±2.0	P

TEST DATA SHEET B-13 (Sheet 2 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

6.13.7.4 Subtraction and D-A Conversion

unfunneled
9-10-97

± 0.00015
 ± 0.00060
 ± 0.00030

Step 1:

Actual Position (API) MSB LSB	Command Position (CP) MSB LSB	AR1 Output Voltage Required (Vdc)	Test Result (Vdc)	Pass/Fail
0000000000000000	0000000000000000	0.00000	0.00014	P
0000000000000001	0000000000000000	-0.00061	-0.000500	P
0000000000000010	0000000000000000	-0.00122	-0.001134	P
0000000000000011	0000000000000000	-0.00184	-0.001766	P
00000000000000100	0000000000000000	-0.00245	-0.002390	P
0000000000010000	0000000000000000	-0.00490 *	-0.004893	P
0000000000100000	0000000000000000	-0.00979 *	-0.009890	P
0000000001000000	0000000000000000	-0.01958 *	-0.019892	P
0000000010000000	0000000000000000	-0.03917 *	-0.039891	P
0000001000000000	0000000000000000	-0.07834 *	-0.079881	P
0000010000000000	0000000000000000	-0.15667 *	-0.15986	P
0000100000000000	0000000000000000	-0.31334 *	-0.31985	P
0001000000000000	0000000000000000	-0.62669 *	-0.63990	P
0010000000000000	0000000000000000	-1.25338 *	-1.2800	P
0100000000000000	0000000000000000	-2.50675 *	-2.5602	P
1000000000000000	0000000000000000	-5.01350 *	-5.1208	P

* Tolerance on output voltage is $\pm 10\%$

Step 2:

Actual Position (API) MSB LSB	Command Position (CP) MSB LSB	AR1 Output Voltage Required (Vdc)	Test Result (Vdc)	Pass/Fail
0000000000000000	0000000000000000	0.00000	0.000146	P
0000000000000001	0000000000000001	0.00061	0.000755	P
0000000000000010	0000000000000010	0.00122	0.001386	P
0000000000000011	0000000000000011	0.00184	0.001998	P
00000000000000100	00000000000000100	0.00245	0.002632	P
000000000000001000	000000000000001000	0.00490 *	0.005133	P
0000000000000010000	0000000000000010000	0.00979 *	0.010160	P
00000000000000100000	00000000000000100000	0.01958 *	0.020162	P
000000000000001000000	000000000000001000000	0.03917 *	0.040150	P
0000000000000010000000	0000000000000010000000	0.07834 *	0.080151	P
00000000000000100000000	00000000000000100000000	0.15667 *	0.16020	P
000000000000001000000000	0000100000000000	0.31334 *	0.32024	P
0000000000000010000000000	0010000000000000	0.62669 *	0.64038	P
00000000000000100000000000	0100000000000000	1.25338 *	1.2803	P
000000000000001000000000000	1000000000000000	2.50675 *	2.5604	P
0000000000000010000000000000	1000000000000000	-5.01350 *	-5.1208	P

* Tolerance on output voltage is $\pm 10\%$

TEST DATA SHEET B-13 (Sheet 3 of 3)

INTERFACE/CONVERTER CCA (P/N 1331697) (Paragraph 6.13.7)

6.13.7.5 Strobe Function

Step 1: Strobe Low

No E11 Change
with Input CP Changes

Pass/Fail
P

Step 2: Strobe High

E11 Change
with Input CP Changes

Pass/Fail
F

6.13.7.6 Amplifier Gain

	<u>Measured Value (Vdc)</u>	<u>Limits (Vdc)</u>	<u>Pass/Fail</u>
E11	<u>0.32024</u>	-	<u>P</u>
E10	<u>3.5173</u>	-	<u>P</u>
E10 Voltage	<u>11.0</u>	10.7 - 11.3	<u>P</u>
E11 Voltage			

6.13.7.7 Ground Isolation

	<u>Measured Value (MΩ)</u>	<u>Limits (MΩ)</u>	<u>Pass/Fail</u>
Pin 91 to Pin 7 DC Resistance	<u>larger than 20MΩ</u>		<u>F</u>

Comments:

NONG

Conducted by:

David Lunn
Test Engineer

8/13/97

Date

7A
190

Verified by:

Michael J. Stumpf
Quality Control Inspector

OCT 10 97

Date

Approved by:

Ronald L. Horner
DCMC

10/14/97

Date

TEST DATA SHEET B-4 (Sheet 1 of 2)

MOTOR DRIVER 3-HALL SENSOR CCA (P/N 1331694) (Paragraph 6.4.3)

S/N: F08
 Date: 8/21/97
1331694-3

6.4.3.2 Input Signal Offset

Step No.	Test Results	Limits
4	1.45 mV	0.0 ±1 mVdc
6	1.59 mV	0.0 ±1 mVdc
8	1.46 mV	0.0 ±1 mVdc

Step No.	Test Resistor	Resistance Measured
13	E7-E8 (R25)	3.4K
	E9-E10 (R52)	5.62K
	E11-E12 (R33)	3.16K
	E13-E14 (R53)	5.62K
	E15-E16 (R42)	3.16K
	E17-E18 (R54)	5.23K

Step No.	Resistors	Selected Trim Resistors
14	R25	RNC55J3401FS
	R52	RNC55J5621FS
	R33	RNC55J3161FS
	R53	RNC55J5621FS
	R42	RNC55J3161FS
	R54	RNC55J5231FS

Step No.	E Point	Test Results	Limits	Pass/Fail
19	E19	0.059 mV	0.0 ±1 mVdc	PASS
	E20	-0.042 mV	0.0 ±1 mVdc	PASS
	E21	+0.040 mV	0.0 ±1 mVdc	PASS

6.4.3.3 Motor Driver Operation

Clockwise Rotation:

Step No.	Test Results	Limits	Pass/Fail
2	5.01V	+5V ±0.05Vdc	PASS
	52.78mA	70mAdc max	PASS
	15.61V	+15V ±0.15Vdc	PASS
	1.57mA	3.0mAdc max	PASS
	-14.98V	-15V ±0.15Vdc	PASS
	18.54mA	25mAdc max	PASS
	28.00V	+28V ±0.5Vdc	PASS
	5.66mA	8mAdc max	PASS
3	240 mV	400mVdc max	PASS
4	40 mA	50mAdc max	PASS
5	48 mA	50mAdc max	PASS

TEST DATA SHEET B-4 (Sheet 2 of 2)

MOTOR DRIVER 3-HALL SENSOR CCA (P/N 1331694) (Paragraph 6.4.3)

Counter Clockwise Rotation:

Step No.	Test Results	Limits	Pass/Fail
3	297 mV	400mVdc max	PASS
4	37 mA	50mAdc max	PASS
5	40 mA	50mAdc max	PASS

6.4.3.4 Current Limit Test

Step No.	Test Results	Limits	Pass/Fail
3	450 mA	350-500mAdc	PASS

Comments:

NONE

Conducted by:

Dennis Lew
Test Engineer

8/21/97
Date

Verified by:

Judie Hersey (269)
Quality Control Inspector

09/03/97
Date

Approved by:

Dave Stora
DCMC

9/3/97
Date

TEST DATA SHEET B-4 (Sheet 1 of 2)

MOTOR DRIVER 3-HALL SENSOR CCA (P/N 1331694) (Paragraph 6.4.3)

S/N: F09
 Date: 8/20/97
1331694-3

6.4.3.2 Input Signal Offset

Step No.	Test Results	Limits
4	1.29 mV	0.0 ±1 mVdc
6	1.58 mV	0.0 ±1 mVdc
8	0.39 mV	0.0 ±1 mVdc

Step No.	Test Resistor	Resistance Measured
13	E7-E8 (R25)	3.4 k
	E9-E10 (R52)	5.23 k
	E11-E12 (R33)	3.16 k
	E13-E14 (R53)	5.62 k
	E15-E16 (R42)	N/A
	E17-E18 (R54)	N/A

Step No.	Resistors	Selected Trim Resistors
14	R25	RNC55J3461FS
	R52	RNC55J5231FS
	R33	RNC55J3161FS
	R53	RNC55J5621FS
	R42	N/A
	R54	N/A

Step No.	E Point	Test Results	Limits	Pass/Fail
19	E19	+0.093 mV	0.0 ±1 mVdc	PASS
	E20	-0.095 mV	0.0 ±1 mVdc	PASS
	E21	+0.858	0.0 ±1 mVdc	PASS

6.4.3.3 Motor Driver Operation

Clockwise Rotation:

Step No.	Test Results	Limits	Pass/Fail
2	5.01 V	+5V ±0.05Vdc	PASS
	52.43 mA	70mAadc max	PASS
	15.01 V	+15V ±0.15Vdc	PASS
	1.60 mA	3.0mAadc max	PASS
	-14.97 V	-15V ±0.15Vdc	PASS
	18.72 mA	25mAadc max	PASS
	28.00 V	+28V ±0.5Vdc	PASS
	5.61 mA	8mAadc max	PASS
3	2.80 mV	400mVdc max	PASS
4	42 mA	50mAadc max	PASS
5	47 mA	50mAadc max	PASS

AE-26693B
19 Jun 97

TEST DATA SHEET B-4 (Sheet 2 of 2)

MOTOR DRIVER 3-HALL SENSOR CCA (P/N 1331694) (Paragraph 6.4.3)

Counter Clockwise Rotation:

Step No.	Test Results	Limits	Pass/Fail
3	281mV	400mVdc max	PASS
4	37mA	50mAdc max	PASS
5	40mA	50mAdc max	PASS

6.4.3.4 Current Limit Test

Step No.	Test Results	Limits	Pass/Fail
3	450mA	350-500mAdc	PASS

Comments:

NONE

Conducted by:

David Lee
Test Engineer

8/20/97

Date

Verified by:

Judie Hervey
Quality Control Inspector

09/03/97

Date

Approved by:

Ruth Jones
DCMC

9/3/97

Date

TEST DATA SHEET B-5 (Sheet 1 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

Date 5/14/97
 CCA S/N F18
1337739-1

6.5.7.1 UUT Pre-Test

Step 2:

Supply Currents (Without UUT)

Supply (Vdc)	(Baseline) Measured Value (mA) (Without UUT)	Limits (mA)	Pass/Fail
+15	0.06 mA	0-1	P
-15	-0.28 mA	-1-0	P
+5	0.06 mA	0-1	P

Supply Voltages (Without UUT)

Supply	Measured Value (V)	Limits (V)	Pass/Fail
+15V (I)	15.02 V	± 0.50	P
-15V (I)	-15.01 V	± 0.50	P
+5V (I)	5.03 V	± 0.25	P

Step 6:

Supply Currents (UUT Installed)

Supply (Vdc)	Measured Value (mA) (UUT Installed)	Difference (mA) (Measured - Baseline)	Limits (mA)	Pass/Fail
+15	31.85 mA	31.79 mA	20-40	P
-15	-41.21 mA	-40.93 mA	-30--50	P
+5	56.45 mA	56.39 mA	30-70	P

6.5.7.2 Supply Voltages (UUT Installed)

Supply	Measured Value (V)	Limits (V)	Pass/Fail
+15V (I)	15.01 V	± 0.50	P
-15V (I)	-14.96 V	± 0.50	P
+5V (I)	5.02 V	± 0.25	P

6.5.7.3 Oscillator Frequency, Duty Cycle, and Output Voltage

Parameter	Measured Value	Limits	Pass/Fail
Frequency	1596 Hz	1550-1650 Hz	P
Duty Cycle	52 %	45-55 %	P
Output Voltage	8.08 V	7.6-8.4 Vrms	P

TEST DATA SHEET B-5 (Sheet 2 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

6.5.7.4 R-D Converter Operation

Step 1:

Bit Number/ Test Fixture Label	CW Pass/Fail	CCW Pass/Fail
API 0/1	P	P
API 1/2	P	P
API 2/3	P	P
API 3/4	P	P
API 4/5	P	P
API 5/6	P	P
API 6/7	P	P
API 7/8	P	P
API 8/9	P	P
API 9/10	P	P
API 10/11	P	P
API 11/12	P	P
API 12/13	P	P
API 13/14	P	P
Converter Busy	P	P

Step 2: ~~writenummed~~ QC 16
3-4-97

PES-RS	Measured Value (Vdc)	Calculated Value (Vdc) * CCA -1 Assy	Calculated Value (Vdc) * CCA -2 Assy	Pass/Fail
RS (E10)	1.62V	+1.79V	N/A	P
CW Rotation**	-1.36V	-1.79V	N/A	P

* Signal level function of test and calibration gain resistors. Record calculated value and measured value. Measured value shall be within ± 10 percent of calculated value. *The equation is as follows:*

$$V = 0.155 \left(\frac{R_{20}}{R_{17}} \right) \pm 23\%$$

R₂₀ = 59K 5/14/97
R₁₇ = 5.11K

6.5.7.5 Amplifier Gain

PES-RS	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
PES = +0.300 Vdc	1.12V	1.00 to 1.30	P
PES = -0.300 Vdc	1.10V	1.00 to 1.30	P

6.5.7.6 Direction Control Signal

DIR CNTRL	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
CCW Rotation	5.00V	4.5 to 5.5	P
CCW Rotation	0.13V	0.0 to 0.4	P

~~writenummed~~ QC 229
5-15-97

TEST DATA SHEET B-5 (Sheet 3 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

6.5.7.7 Notch Filter Frequency Response

Frequency	Measured Value (Hz)	Calculated Value (Hz) * CCA -1 Assy	Calculated Value (Hz) * CCA -2 Assy	Pass/Fail
AR3 Notch	N/A	N/A	N/A	N/A
AR4 Notch				
AR5 Notch				

* Notch frequencies shall be within ± 3 percent of values determined by test and calibration resistors. Record calculated and measured values.

Comments:

NONENote

This test shall be performed at the system level during antenna drive subsystem ~~level~~ testing.

WST/Hummel

(C) 97

3-4-97

Conducted by:

Dennis Linn
Test Engineer

5/14/97

Verified by:

Judie Harvey
Quality Control Inspector

5-15-97

Approved by:

Frank L. Agnew
DEM/C

5-15-97

TEST DATA SHEET B-5 (Sheet 1 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

Date 8/27/97
 CCA S/N E19
1337739-1
 6.5.7.1 UUT Pre-Test

Step 2:

Supply Currents (Without UUT)

Supply (Vdc)	(Baseline) Measured Value (mA) (Without UUT)	Limits (mA)	Pass/Fail
+15	0.06	0-1	P
-15	-0.28	-1 - 0	P
+5	0.06	0-1	P

Supply Voltages (Without UUT)

Supply	Measured Value (V)	Limits (V)	Pass/Fail
+15V (I)	15.02	± 0.50	P
-15V (I)	-15.01	± 0.50	P
+5V (I)	5.03	± 0.25	P

Step 6:

Supply Currents (UUT Installed)

Supply (Vdc)	Measured Value (mA) (UUT Installed)	Difference (mA) (Measured - Baseline)	Limits (mA)	Pass/Fail
+15	27.08	27.02	20-40	P
-15	-36.14	-35.86	-30 - -50	P
+5	52.12	52.06	30-70	P

6.5.7.2 Supply Voltages (UUT Installed)

Supply	Measured Value (V)	Limits (V)	Pass/Fail
+15V (I)	15.01	± 0.50	P
-15V (I)	-14.97	± 0.50	P
+5V (I)	5.02	± 0.25	P

6.5.7.3 Oscillator Frequency, Duty Cycle, and Output Voltage

Parameter	Measured Value	Limits	Pass/Fail
Frequency	1603 Hz	1550-1650 Hz	P
Duty Cycle	51.5%	45-55 %	P
Output Voltage	7.94 V	7.6-8.4 Vrms	P

TEST DATA SHEET B-5 (Sheet 2 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

6.5.7.4 R-D Converter Operation

Step 1:

Bit Number/ Test Fixture Label	CW Pass/Fail	CCW Pass/Fail
API 0/1	P	P
API 1/2	P	P
API 2/3	P	P
API 3/4	P	P
API 4/5	P	P
API 5/6	P	P
API 6/7	P	P
API 7/8	P	P
API 8/9	P	P
API 9/10	P	P
API 10/11	P	P
API 11/12	P	P
API 12/13	P	P
API 13/14	P	P
Converter Busy	P	P

Step 2:

RS (E10)	Measured Value (Vdc)	Calculated Value (Vdc) * CCA -1 Assy	Calculated Value (Vdc) * CCA -2 Assy	Pass/Fail
CW Rotation**	1.554	(+) 1.790	(+) N/A	P
CCW Rotation**	-1.649	(-) 1.790	(-) N/A	P

* Signal level function of test and calibration gain resistors. Record calculated value and measured value. Measured value shall be within ± 10 percent of calculated value. The equation is as follows:

$$V = \pm 0.155 \left(\frac{R20}{R17} \right) \pm 10\% = 0.155 \left(\frac{5.9k}{5.11k} \right) = 1.79V$$

8-26-97

6.5.7.5 Amplifier Gain

PES-RS	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
PES = +0.300 Vdc	1.066	1.00 to 1.30	P
PES = -0.300 Vdc	1.133	1.00 to 1.30	P

6.5.7.6 Direction Control Signal

DIR CNTRL	Measured Value (Vdc)	Limits (Vdc)	Pass/Fail
CW Rotation	5.000	4.5 to 5.5	P
CCW Rotation	0.116	0.0 to 0.4	P

TEST DATA SHEET B-5 (Sheet 3 of 3)

R-D CONVERTER/OSCILLATOR CCA (P/N 1337739) (Paragraph 6.5.7)

6.5.7.7 Notch Filter Frequency Response

Frequency	Measured Value (Hz)	Calculated Value (Hz) * CCA -1 Assy	Calculated Value (Hz) * CCA -2 Assy	Pass/Fail
AR3 Notch	N/A	N/A	N/A	N/A
AR4 Notch				
AR5 Notch				

* Notch frequencies shall be within ± 3 percent of values determined by test and calibration resistors. Record calculated and measured values.

Comments:

No NG

Conducted by:

Dennis Lien

8/21/97

Test Engineer

Date

Verified by:

Judie Terrey

8/24/97

Quality Control Inspector

Date

Approved by:

Richard Starks

9/2/97

DCMC

Date

APPENDIX B

SCAN MOTION AND JITTER RESPONSE PLOTS

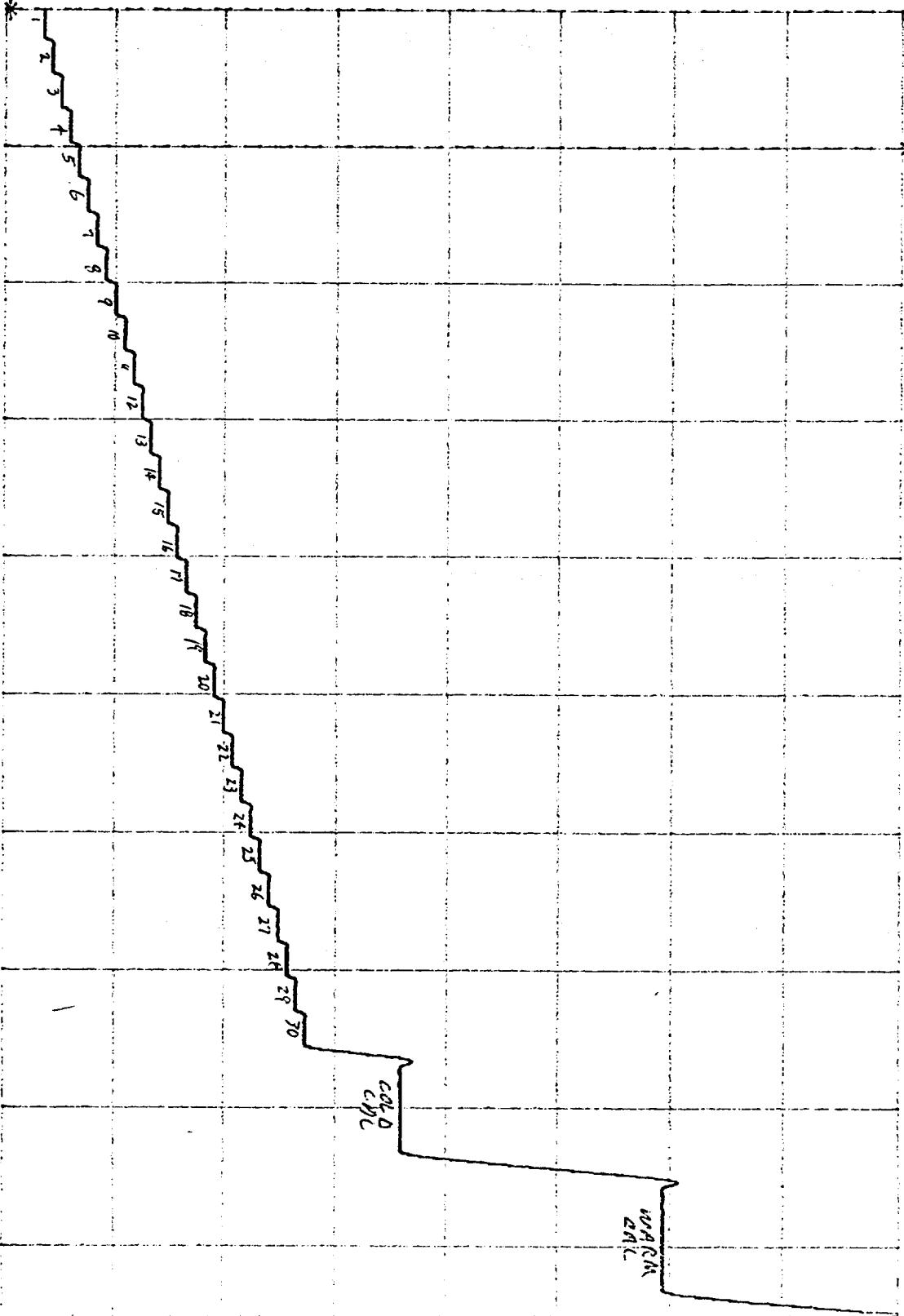
CAP TIM BUF
36.0

4.5

/D i \

Recl

\ V



EX-DXY D-D ALI ZAP-FSS/

Sec

8

SL : 436613

3.4.5

MN: 1331720-2-1T SN: 105

Test Eng: Jayantif Date: 6-12-98

Qualif: 7A (190) JUN 16 1998

X=2.734mS
Y_d=1.5829

ΔX=187.1mS
ΔY_d=313.0mV

Y=1.59419

ΔY=16.13mV

CAP TIM BUF

2.4

166

m

/Div

Real

V

1.07

FxdXY 2.73m Am Step 1

3445

5/0: 436613

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: Ray Chappell

Quality: JUN 16 1998 (7A 190)

190m

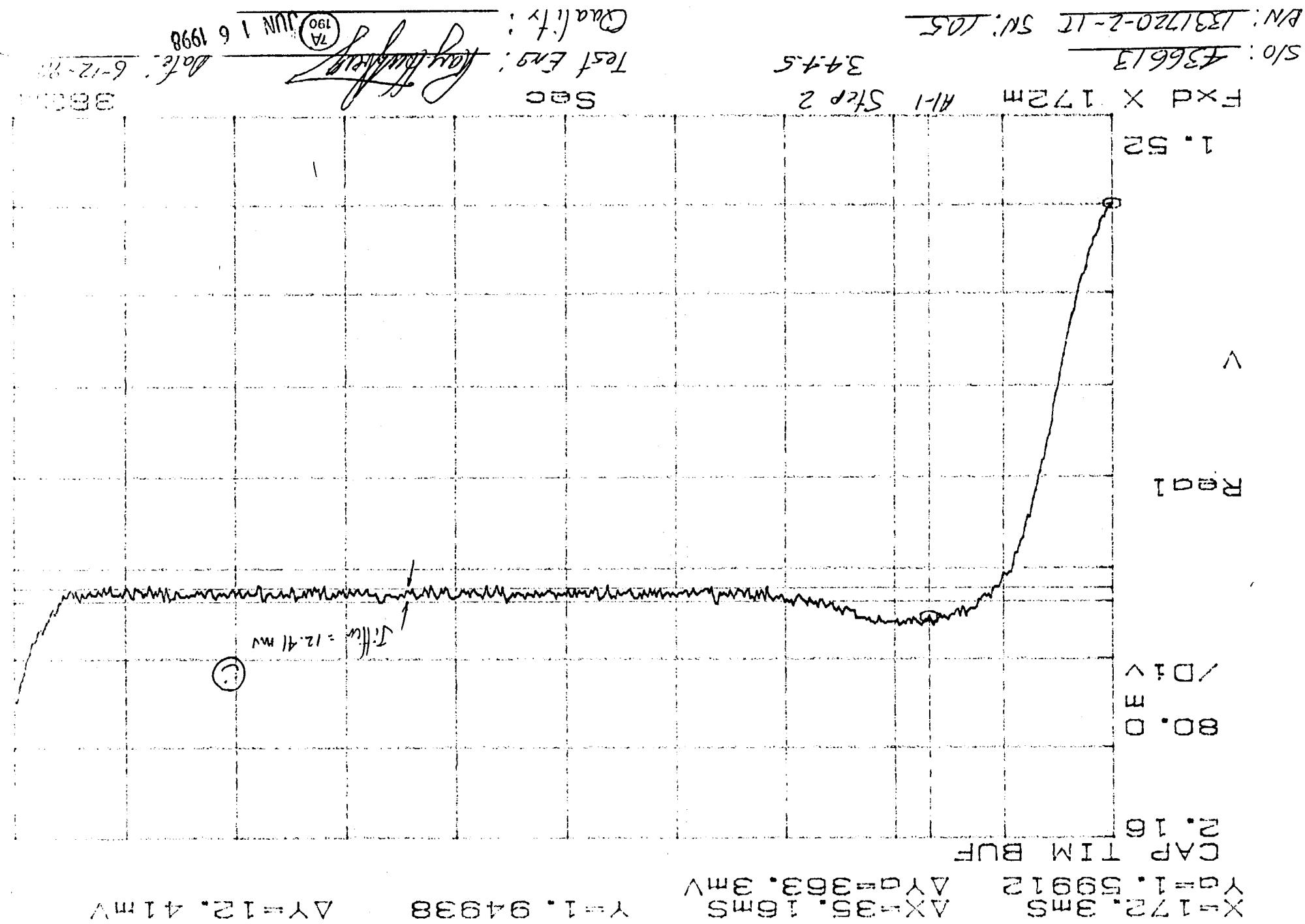
Date: 6-12-98

Jitter = 16.13 mV



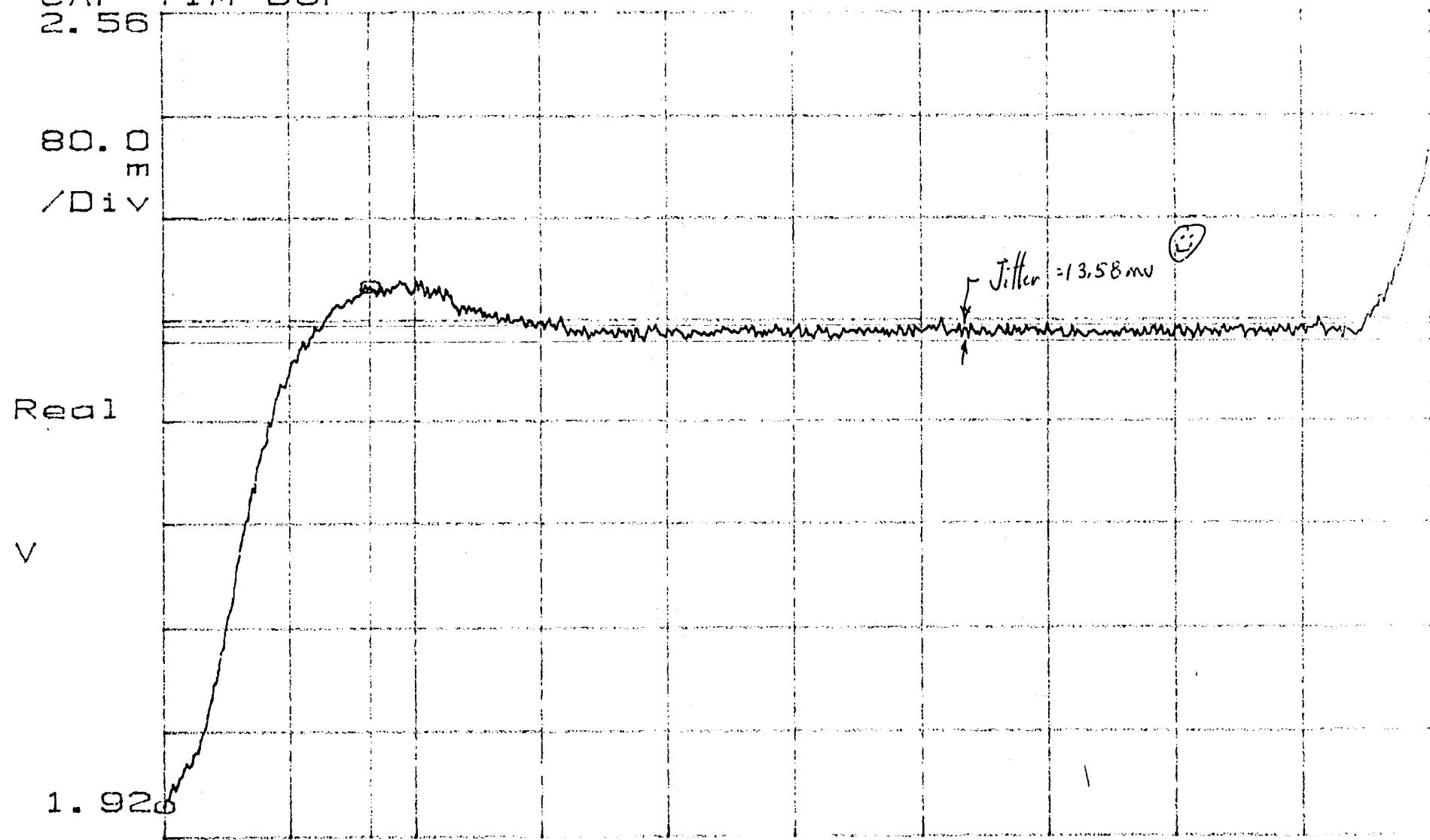
R7

R3



X=372.7mS $\Delta X=35.16\text{mS}$ Y=2.31564 $\Delta Y=13.58\text{mV}$
Y_d=1.94295 $\Delta Y_d=402.2\text{mV}$

CAP TIM BUF
2.56



S/N: 436613

3.4.1.5

PN: 1331720-2-1T SN: 105

Sec 586m
Test Eng: Payne/Hughes Date: 6-12-98
Quality: C JUN 16 1998 7A 190

X=575.4mS ΔX=35.55mS
Y=2.31434 ΔY=387.6mV
CAP TIM BUF

2.88

Y=2.69227 ΔY=13.58mV

80.0
/D i v



J_{ther} = 13.58 mV



Read

V

2.24

Fxd X 571m n/1 Step 4
3.4.1.5.

S/I: 436613

PN: 1331720-2-17 SN: 105

sec

785m

Date: 6-12-98

Test Eng: Hanifullah ^{TA} ₁₉₀ Date: Jun 16 1998

Dualts:

B5

$X = 778.5 \text{ ms}$ $\Delta X = 35.16 \text{ ms}$ $\gamma = 3.06279$

$\Delta Y_0 = 387.6 \text{ mV}$ $\Delta Y = 14.34 \text{ mV}$

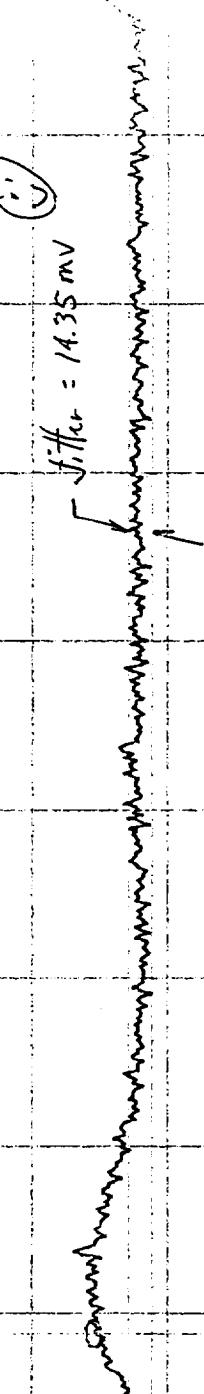
CAP TIM BUF
3. 28

80. 0
/ Div

Real

V

$$\sqrt{\text{Jitter}} = 14.35 \text{ mV}$$



2. 64
Fxd X 773m H-1 Step 5
S/N: 436613

34.1.5.
P/N: 1331220-2-1T SN: 105

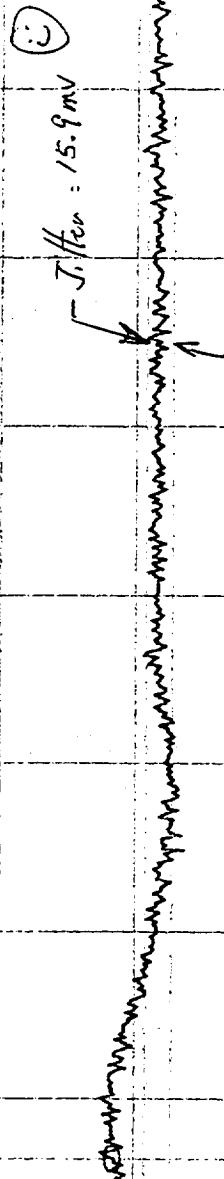
987 m
Sec
Test Eng: John Koenig Date: 6/22/98
Qualif: 74/100 JUN 15 1998

P10

X=980.5mS ΔX=35.16mS
Y=3.05714 ΔY=3.94.1mV
CAP TIM BUF

3.68

80.0
/DIV



V

Fwd X 980m A1 Step 6
3.4.1.5
S/N: 436613

P/N: 1331720-2-UT SN: 105
S/N: 1331720-2-UT SN: 105

Sec Test Eng: Parthasarathy Date: 0-12-¹⁹⁹⁸
Qualif: (74) (190) JUN 15 1998

1. 1. 1.

B7

X=1.186 S $\Delta X=35.16\text{mS}$ Y=3.80024 $\Delta Y=18.62\text{mV}$
Yd=3.44475 $\Delta Yd=369.8\text{mV}$

CAP TIM BUF

4.0

80.0

m

/Div

Real

V

3.36

Fxd X 1.18 At 1 Step 7

3.44.5

S/N: 436613

P/N: 1331720-2-1T SN: 105

Jitter = 18.62 mV



Sec

Test Eng:

Laythbury

Quality:

74
190

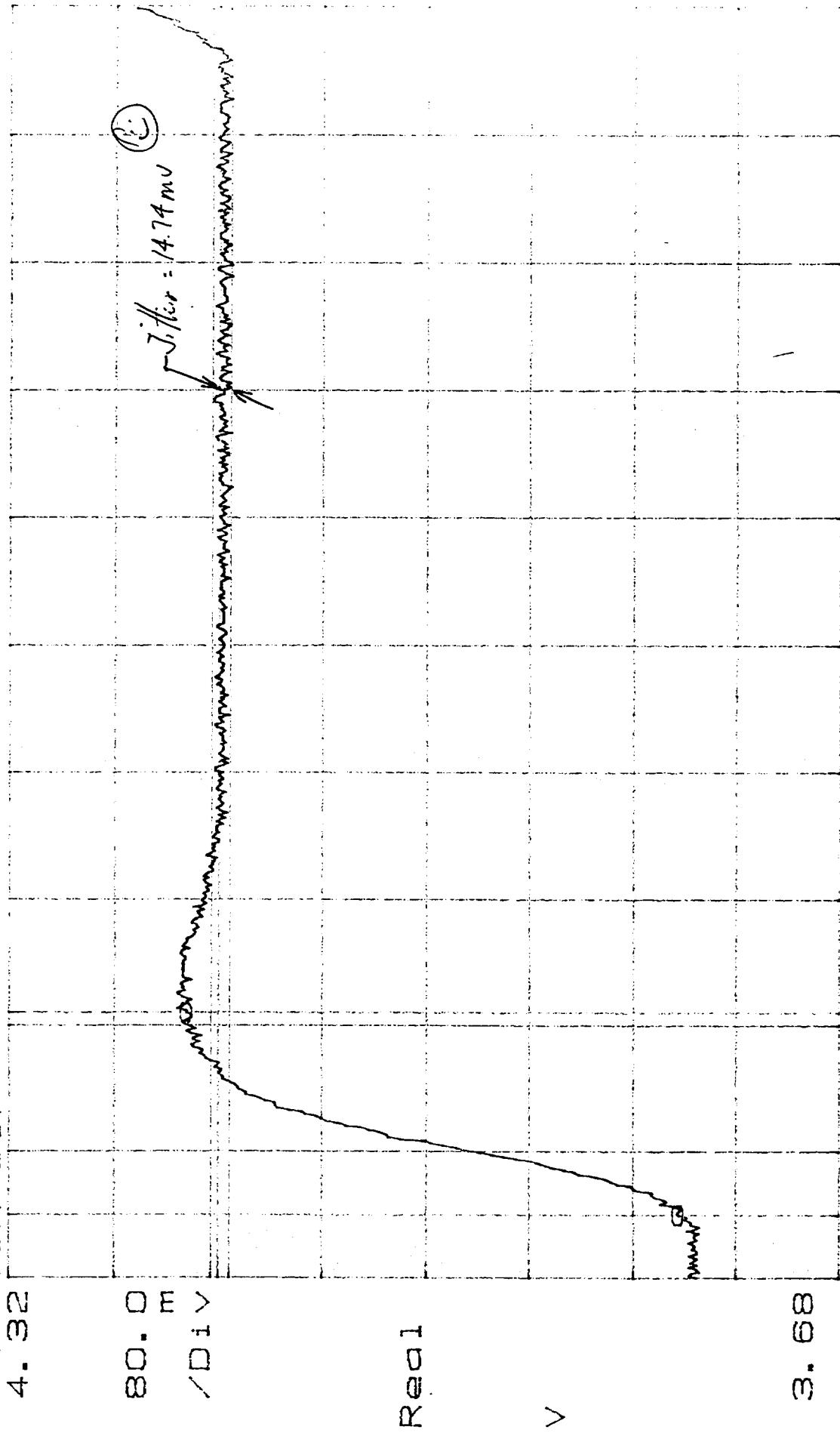
JUN 15 1998

1.

Date: 6-11-98

$X = 1.387.5$ $\Delta X = 35.16 \text{ mS}$ $\gamma = 4.16562$ $\Delta \gamma = 1.4.74 \text{ mV}$

$Y = 3.8048$ $\Delta Y = 379.5 \text{ mV}$
CAP TIM BUF
4. 32



Fixd X 1. 38 Al Step B
3.44.5
S/N: 936613
P/N: 1331720-2-1T SN: 105

Sec Test Exp: Laythoff Date: 6/12/98
Qualit: ^A ₁₉₀ Jun 15 1998

$X = 1.5888 S$ $\Delta X = 35.16 mS$
 $Y = 4.15836$ $\Delta Y = 399.0 mV$
CAP TIM BUF
4.72

$\Delta Y = 20. 17 mV$

80. 0

/D i V

(i)

Vitter = 20.17 mV

Recal

V

4. 08

Fwd X 1. 58 At-1 Step 9
3.1 x 5

5/0: 436613

P/N: 1331720-2-17 SW: 105

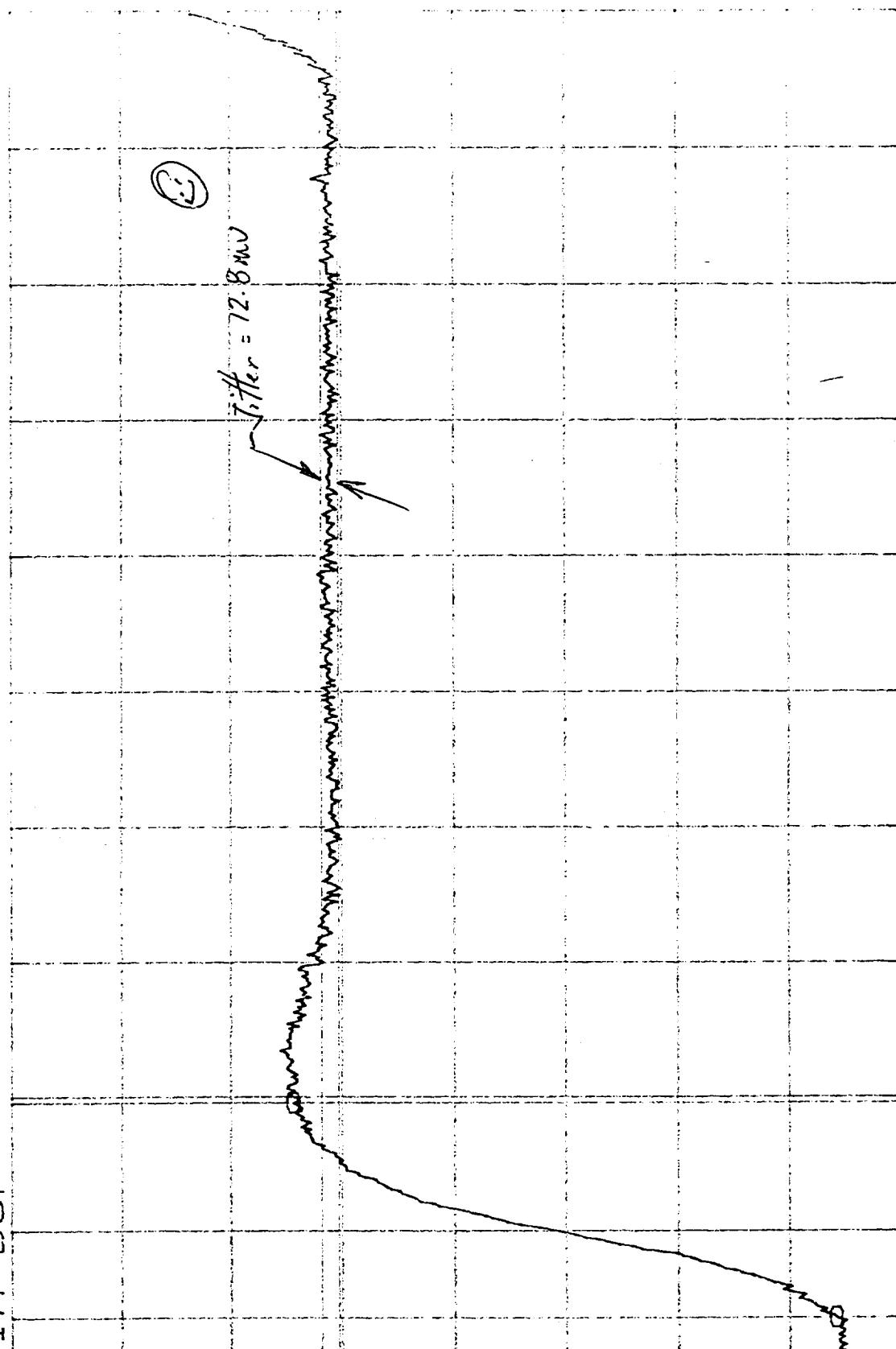
Sec

Test Eng: Gauthier Date: 6/11/98
Qualty: TA ¹⁸⁰ JUN 15 1998

B10

$X = 1.791 \text{ S}$ $\Delta X = 35.16 \text{ mS}$
 $Y = 4.52651$ $\Delta Y = 387.6 \text{ mV}$
CAP TIM BUF
5. 12

$\Delta Y = 4.89425$ $\Delta Y = 12.8 \text{ mV}$



V

Fx d X 1.78 At Step 10
5/4.4.5
S/N: 1331720-2-1 SW: 105
P/N: 436613

Sec
Test End: 1990-06-15 11:13
Qualitx:

RA JUN 1 5 1990

B11

$X = 1.994 \text{ S}$ $\Delta X = 35.16 \text{ mS}$
 $Y = 4.8898$ $\Delta Y = 395.7 \text{ mV}$

CAP TIM BUF
5.52

80. 0
/D i V

RECALL

V

4. 88

Fxd X 1. 99 A1 Step 11
S/N: 436613
Phi: 1331720-2-1T SN: 105

Sec

Test Eng: ~~John H. Hogg~~ Date: 6-12-98
Qual, Tr: ^{TA} ₍₁₉₀₎ JUN 1 5 1990

B12

$$\text{Jitter} = 15.52 \text{ mV}$$

$X_0=2.19629$ $\Delta X=35.16\text{mS}$ $V=5.64839$ $\Delta V=16.68\text{mV}$

$Y_0=5.26282$ $\Delta Y=40.7.1\text{mV}$

CAP TIM BUF
5.84

80.0

E

/D1\

Offset: 16.68 mV



Reel 1

✓

WFO

FxD X 2.19

Alt Step 12

3.4.4.5

Sec

Test Eng: John Date: 6-12-98

Qualif: 1990 JUN 15 1998

S/I: 4366/3
PN: 1331120-2-1T SV: 105

2.4.1

$X_g = 2.5$, 388 S $\Delta X = 35.16 \text{ mS}$ $\Delta Y_g = 389.2 \text{ mV}$

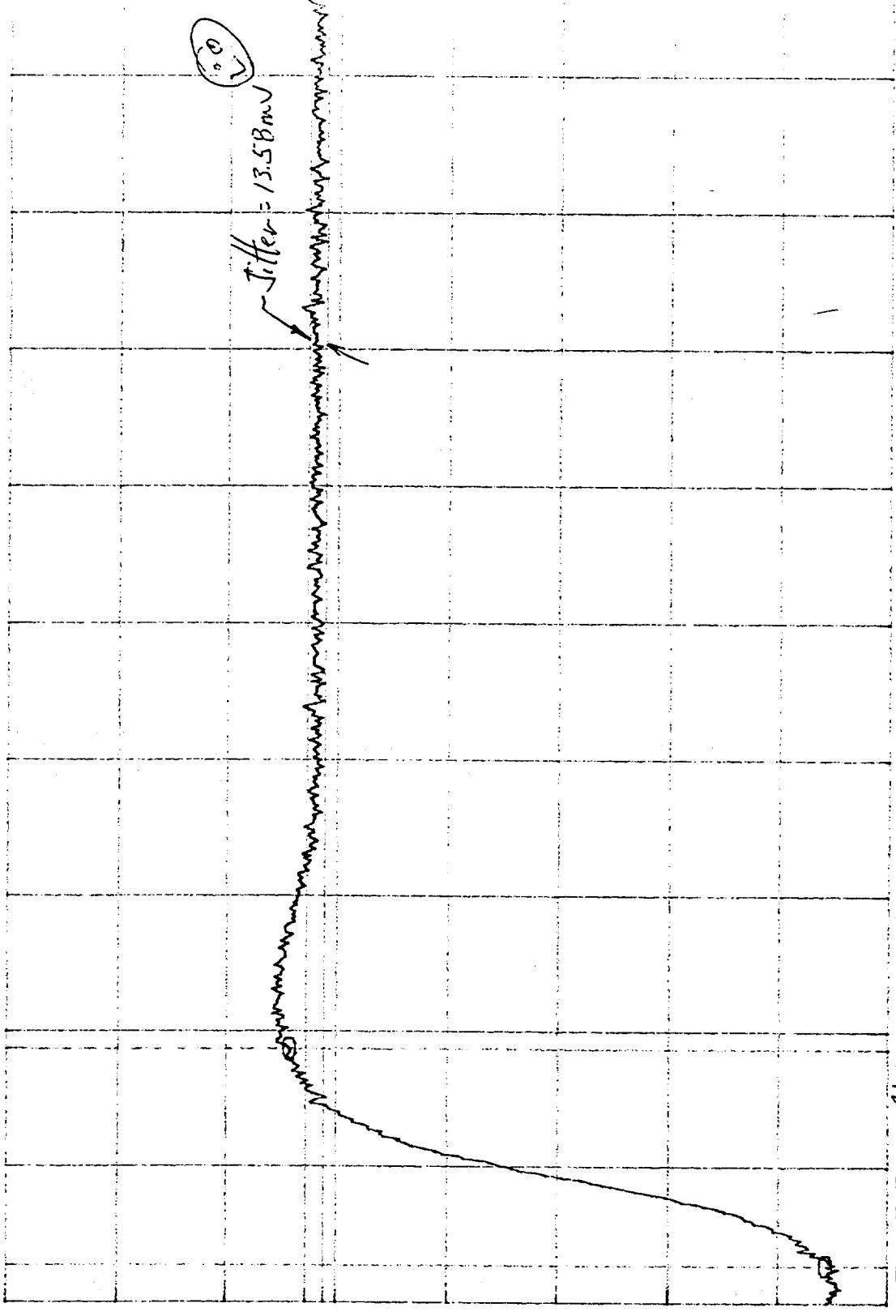
$\Delta Y = 6.02162$ $\Delta Y = 13.58 \text{ mV}$

CAP TIM BUF
6. 24

80. 0
/D i V

Recal

V



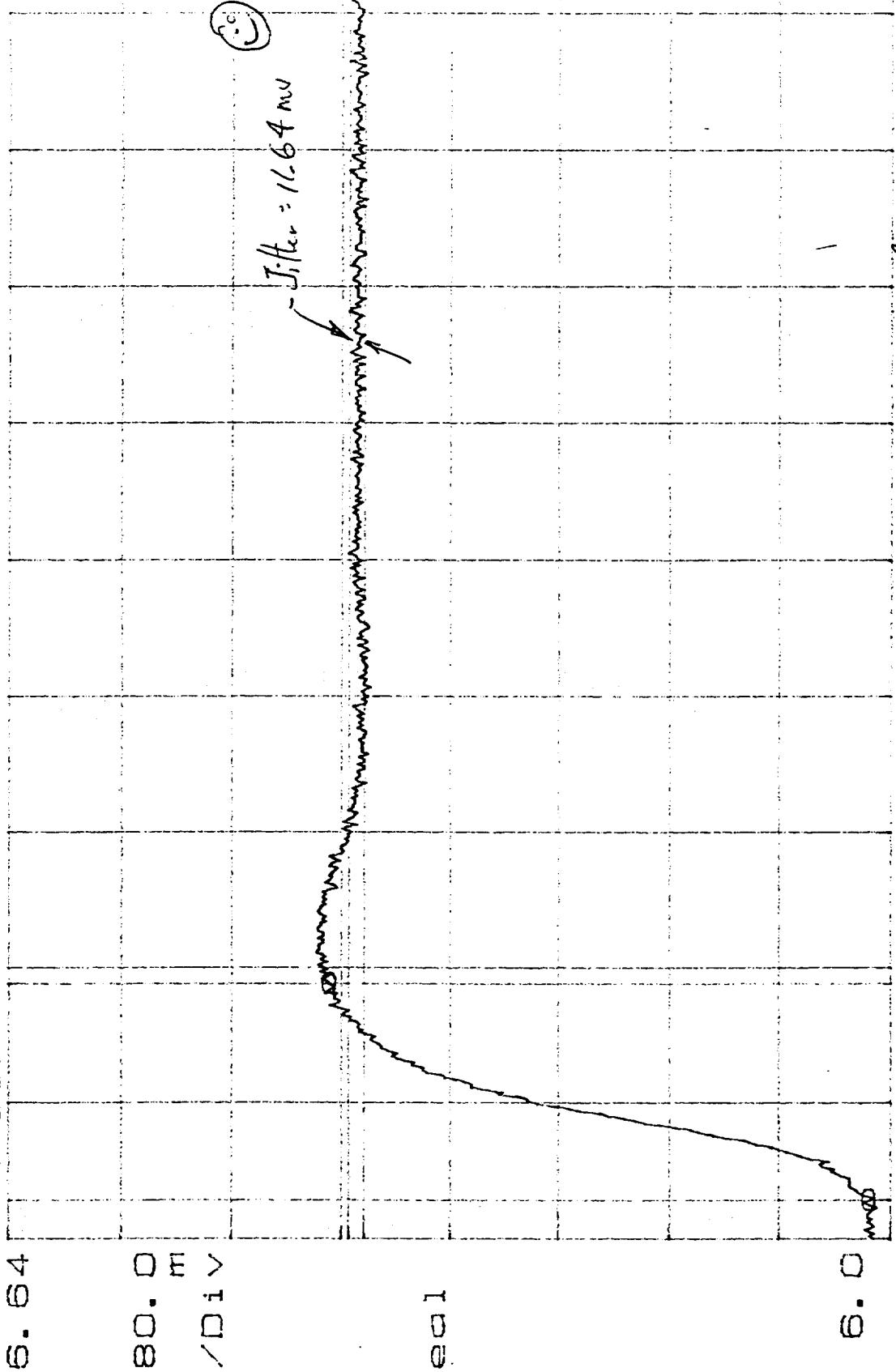
Fx'd X 2. 39 A1/ Step 13
5/0 : 4366/3
PN: 1331720-2-17 SN: 105

2. 61
Test Eng: P. H. Hwang Date: 6/12/98
Qualit: TA ISO 1 JUN 15 1998

RIL

$X=2.6$ $\Delta X=35.16 \text{ mS}$ $Y=6.39447$ $\Delta Y=1.1.64 \text{ mV}$

$\Delta Y_d=382.5 \text{ mV}$
CAP TIM BUF
6.64



Sec 2. 83
Test Eng' *John H. Johnson* Date: 6-12-98
Qualif: JUN 15 1998
SN: 1331120-2-1T SW: 105
PN: 1331120-2-1T

B15

$X = 2.804 \text{ S}$ $\Delta X = 35.16 \text{ mS}$
 $Y_0 = 6.39485$ $\Delta Y_0 = 384.4 \text{ mV}$
C.A.P. TIM BUF
6. 96

$\Delta Y = 16.68 \text{ mV}$

80. 0
/D i V

$$\text{Filter} = 16.68 \text{ mV}$$

Recal

V

6. 32
F x d X 2. 79 Ar-1 Step 15 14 15
S/N: 1331720-2-1T SN: 105

Sec
3. 0.0

R. Matthey

3. 4.5

Sec

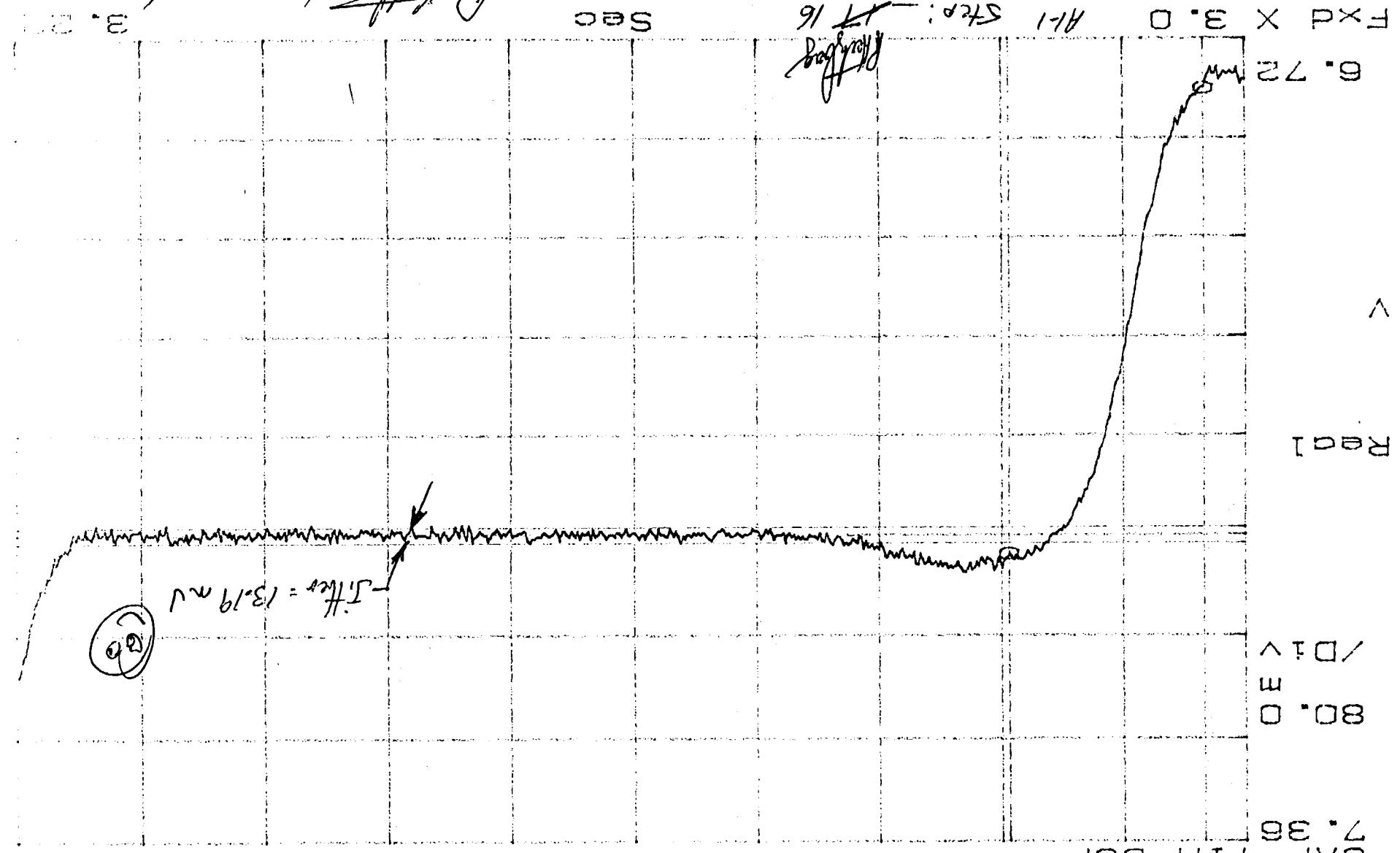
3. 0.0

Test End *12:12 PM* Date *6/12/98*
Qualif: *(7A)* *190* *15 1998*

Bill

B17

PA 1331720-2-1T SW: 105
 JUN 15 1998 1990
 Qulalif, Tcf La, Date: 6.12.98
 3.02.98



X=3.007 S

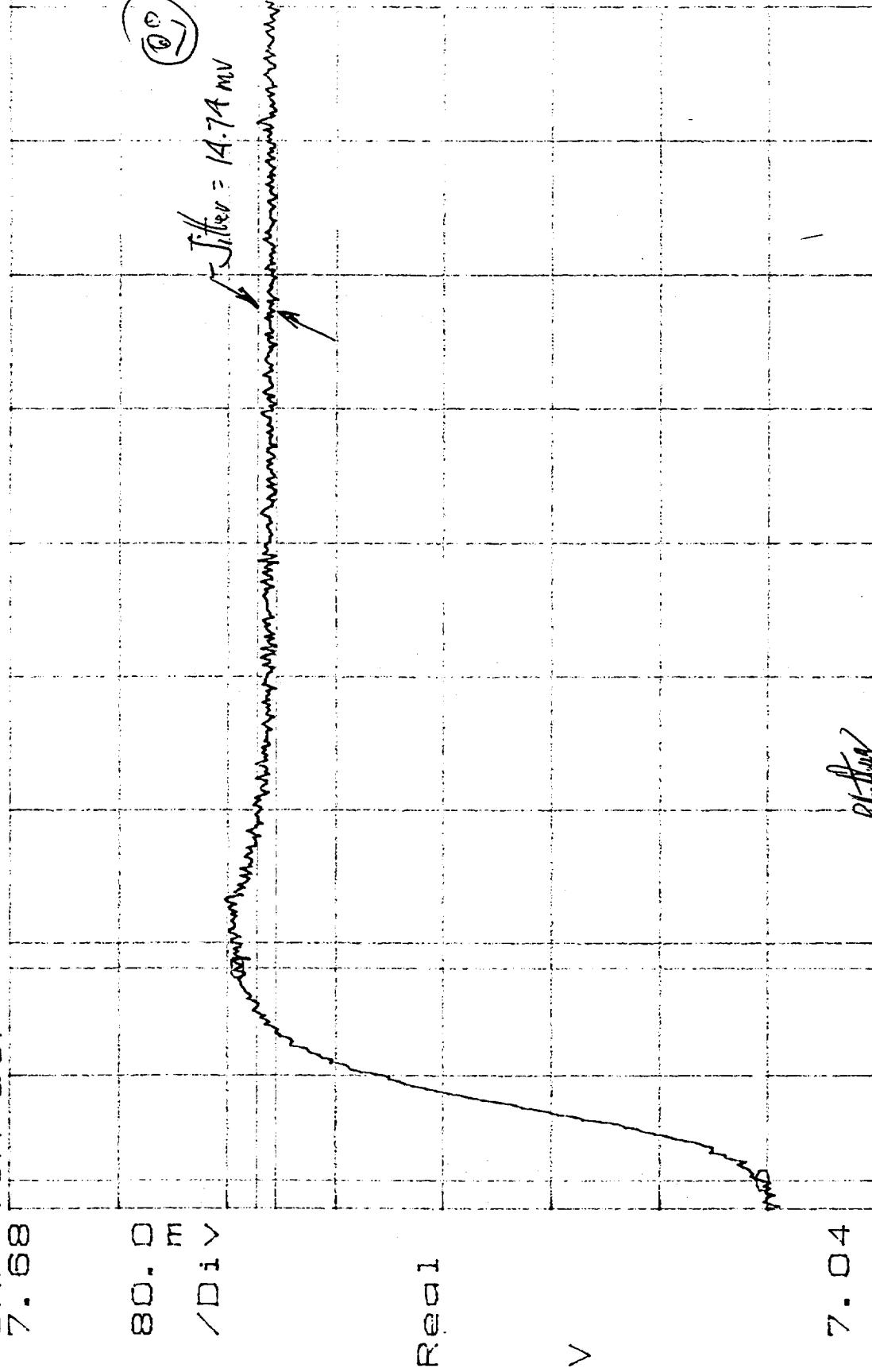
AX=35.16ms

AY=13.19mV

Y_D=6.75976 A_{YD}=374.6mV

X = 3.21 S 12305 $\Delta X = 35.16 \text{ mS}$
Y_G = 7.12305 $\Delta Y_G = 389.2 \text{ mV}$
CAP TIM BUF
7.68

$\gamma = 77.49847$ $\Delta \gamma = 14.74 \text{ mV}$



Fwd X 3.21 A-1 Step 17 3.4.4.5
S/N: 1331720-2-1T SW: 105

Sec Test Eng: ~~John H.~~ ^{TA} ~~John H.~~ Date: 6-14-98
Qual.: ^{RA} ~~180~~ JUN 15 1998

3. 4.4.5
R18

X=3.412 S AY=35.16mS Y=7.86938 AY=15.9mV

CAP TIM BUF
3.08

80.0
mV

100

Jitter = 15.9 mV

Real

V

7.44

Fx'd X 3.4

Notch

Sec

3.

56: A36613

3.44.5

PN: 1331720-2-1T SW: 105

Qual/fx: JUN 15 1998 (7A)

BIA

X=3.616 S 35.16mS
Y=7.87071 A YG=384.4mV

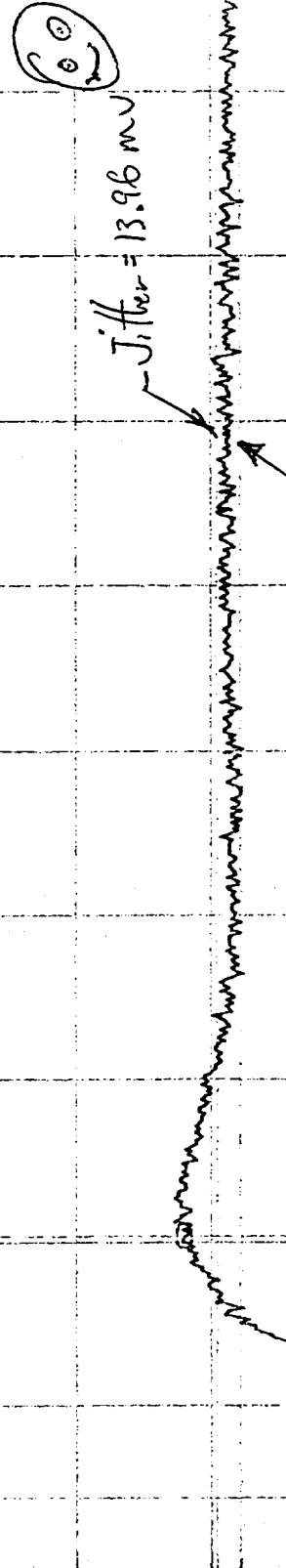
$\Delta Y = 13 \cdot 96 \text{ mV}$

CAP TIM BUF

8.4

80.0
/D i v

Jitter = 13.96 mV



Real

v

7.76

Fxd X 3.61 A-1 Step 20/9

3.4.1.5

SN: 105

S/N: 1331720-2-1T

5/6: 436613

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: John Hwang

3. 86

Date: 6/1/98

Qualif: JUN 15 1998 (TA)

(190)

B20

X=3.816S ΔX=35.16mS
Y=3.22914 ΔY=38.7.6mV

ΔY=17.84mV

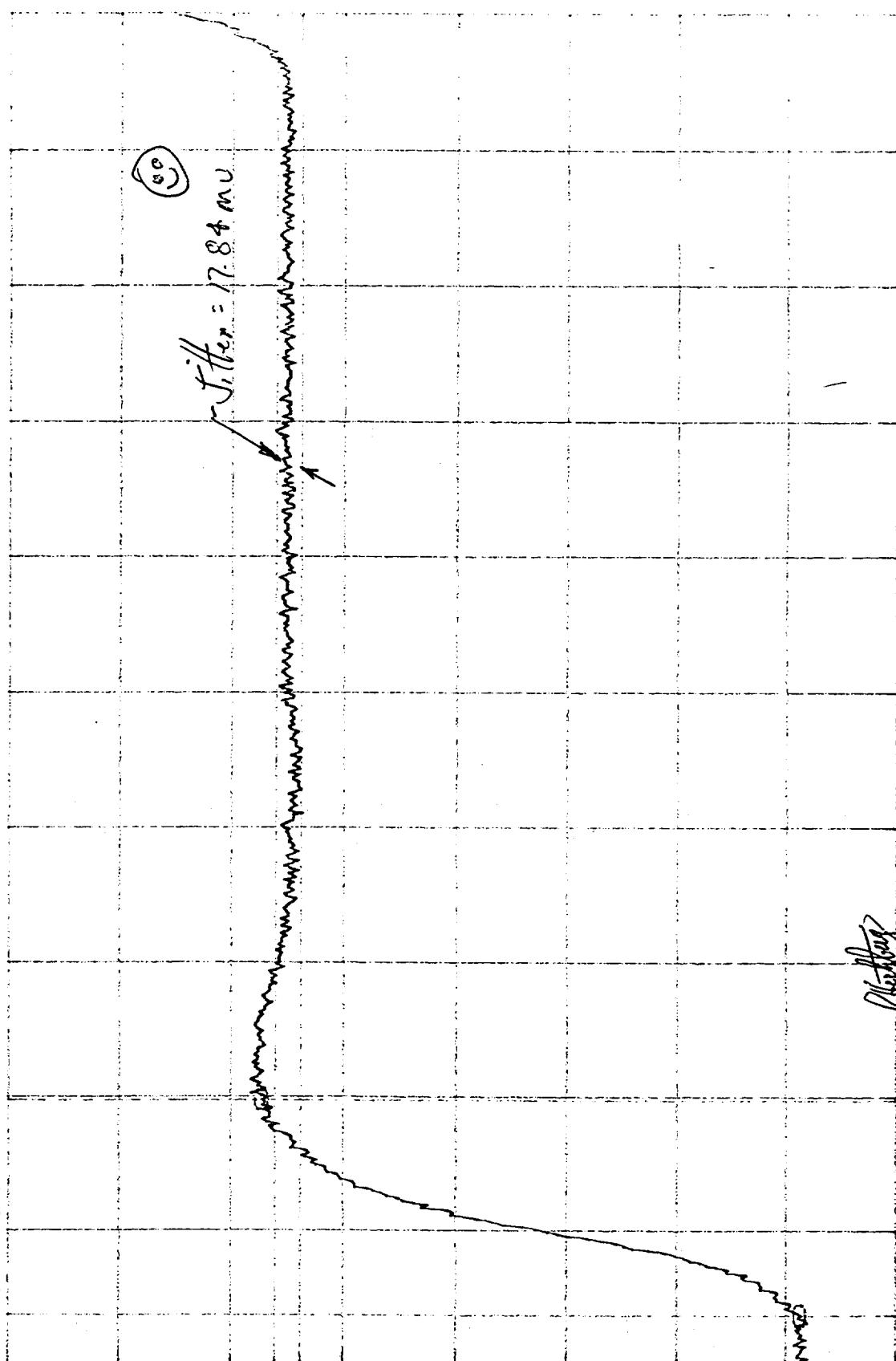
CAP TIM BUF

8.8

80.0
100 V

Real

V



8. 16
Fixed X 3. 81 Ar-1 5720 2720
S/N: 436613
P/N: 1331720-2-1T SW: 105

8. 16

4. 17.84 mV
Test Engr: John H. G. Date: 6/15/98
Quality: QA 190 JUN 15 1998

B21

X=4.02S Y=35.15mS
Yg=8.60378 Ay=382.7mV

CAP TIM BUF
9. 2

/D i

80. 0

m

/D i



Real

V

B. 56

Fixd X 4.01 Am 5Ker

Rutherford
22/21

Sec

4. 2. 2

S/0 136613

3.4.4.5

Test Eng: *Rutherford* Date: 6-12-1998
Qualif: JUN 15 1998 (TA)
C/N: 1331720-2-1C SN: 105

X=8.97231 ΔY=15.13mV

X=4.222 S ΔX=35.16mS
Y=8.97193 ΔY=381.1mV

CAP TIM BUF
G.52

Y=9.33692 ΔY=15.13mV

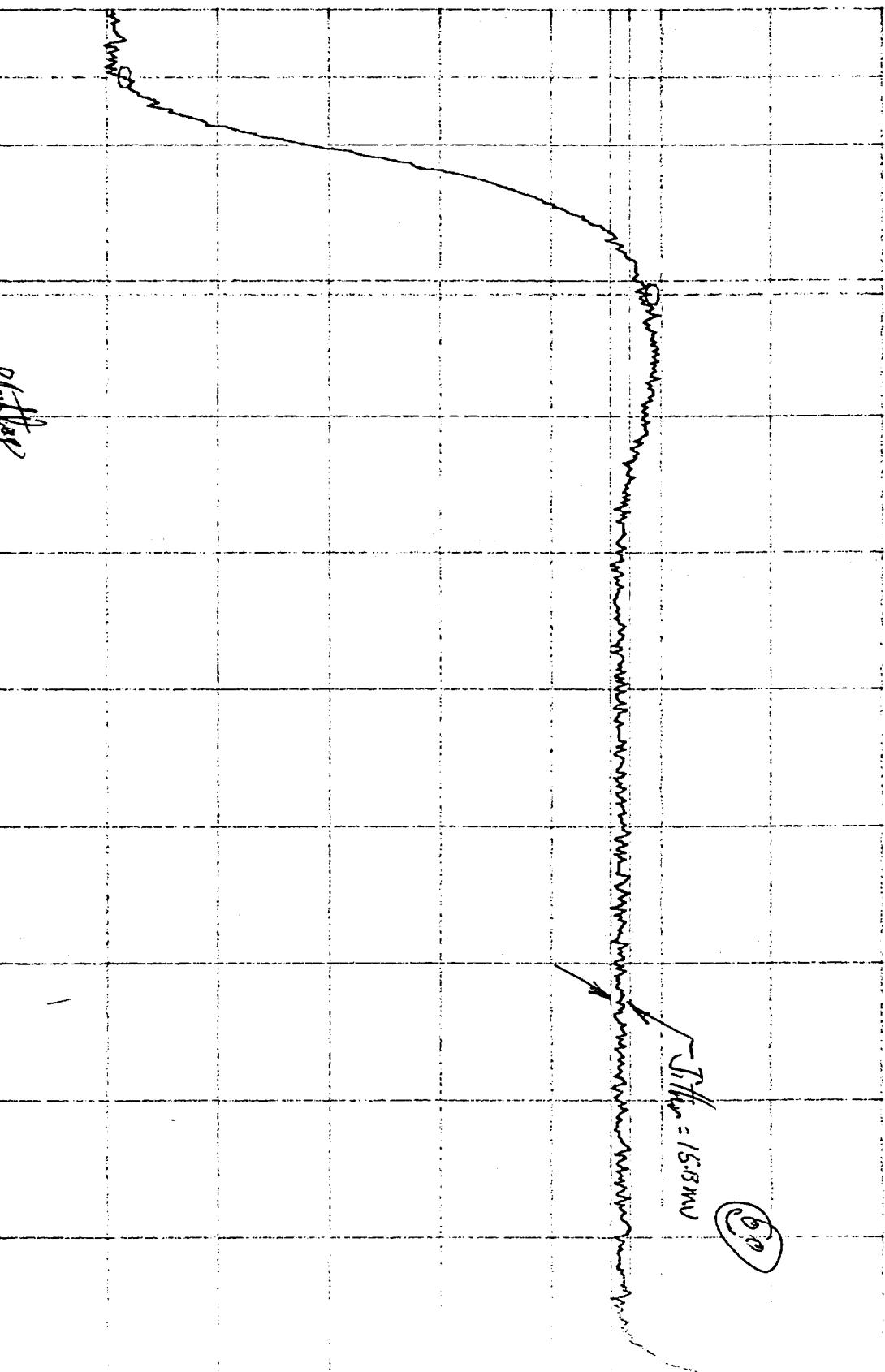
80.0
E
Div

-J_{Th} = 15.3mV

(60)

Reel 1

V



B. 88

FxD X 4.21 A1-1 Sto 23 22

Sec

4.43

S/O: 436613

3.4.1.5

MN: 133/720-2-1T SN: 105

Test Eng: Jayanthi

Date: 6-12-98

Qualif: QA 15

B23

X=4.425 S ΔX=35.16mS
Yd=9.33522 ΔYd=392.5mV

Y=9.70783 ΔY=16.29mV

CAP TIM BUF
9.92

80.0

m

✓D1 ✓

(C)

T_{eff} = 16.29mV

Real

✓

9.28

Fxd X 4.42 H-1

Sta 2423

Sec

4.63

Plotting

3.4.4.5

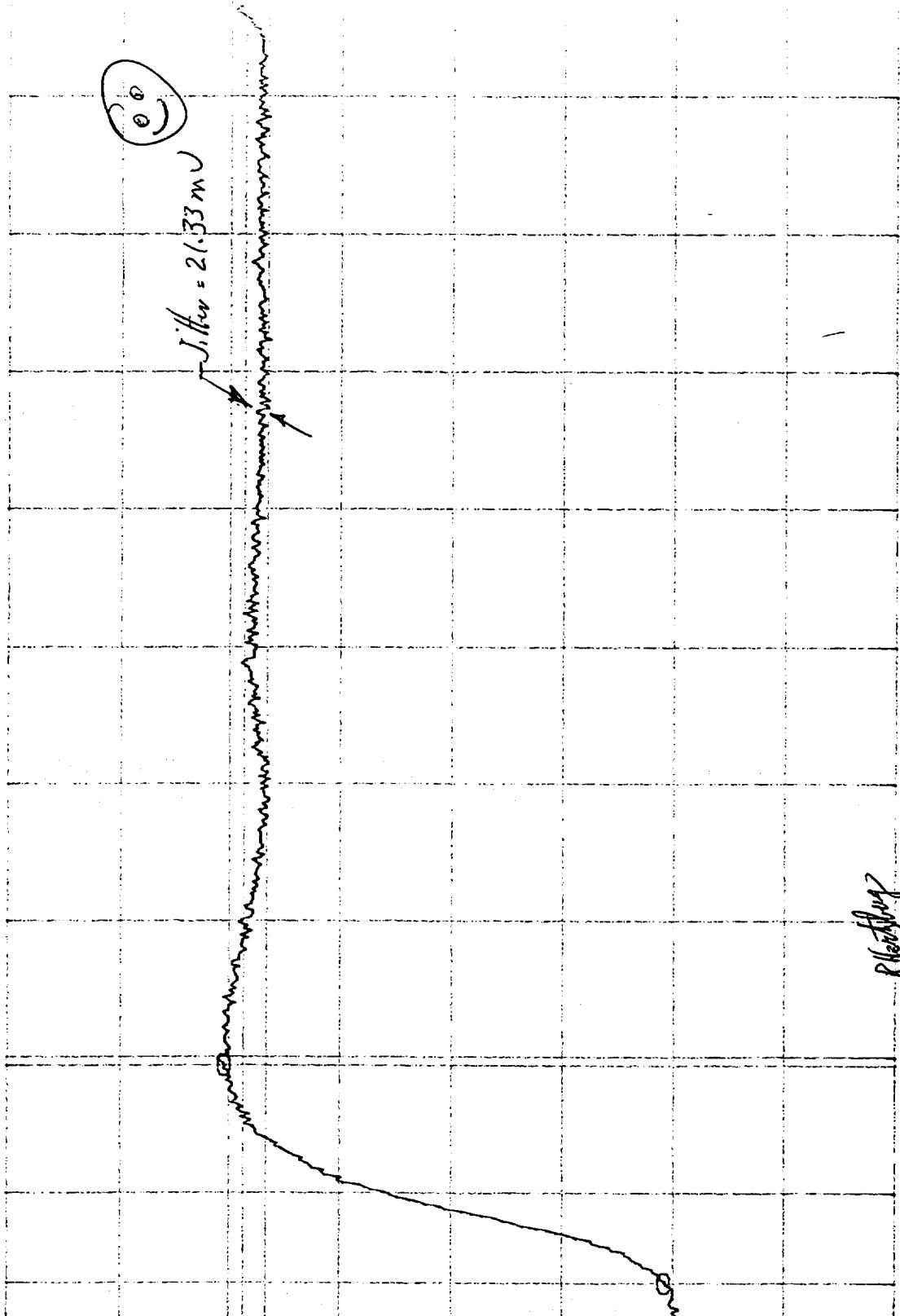
Test Eng *signature* Date: 6/12/98
Qualif: *signature* (180) JUN 15 1998

P/N: 1331720-2-1T SK: 105

B24

X=4.628 S $\Delta X=35.16$ ms
Y_a=9.70662 $\Delta Y_a=39.7$.3 mV
CAP TIM BUF
10.3

Y=10.0867 $\Delta Y=21.33$ mV



Real

V

9.5

Fix'd X 4.62 Sta 25/24
S/N: 436613
P/N: 1331720-2-1T SN: 105

Plotting

Sec

Test Eng:

Qualif:

7A
190

JUN 15 1998

4. 03 4.
Date: 6-12-98

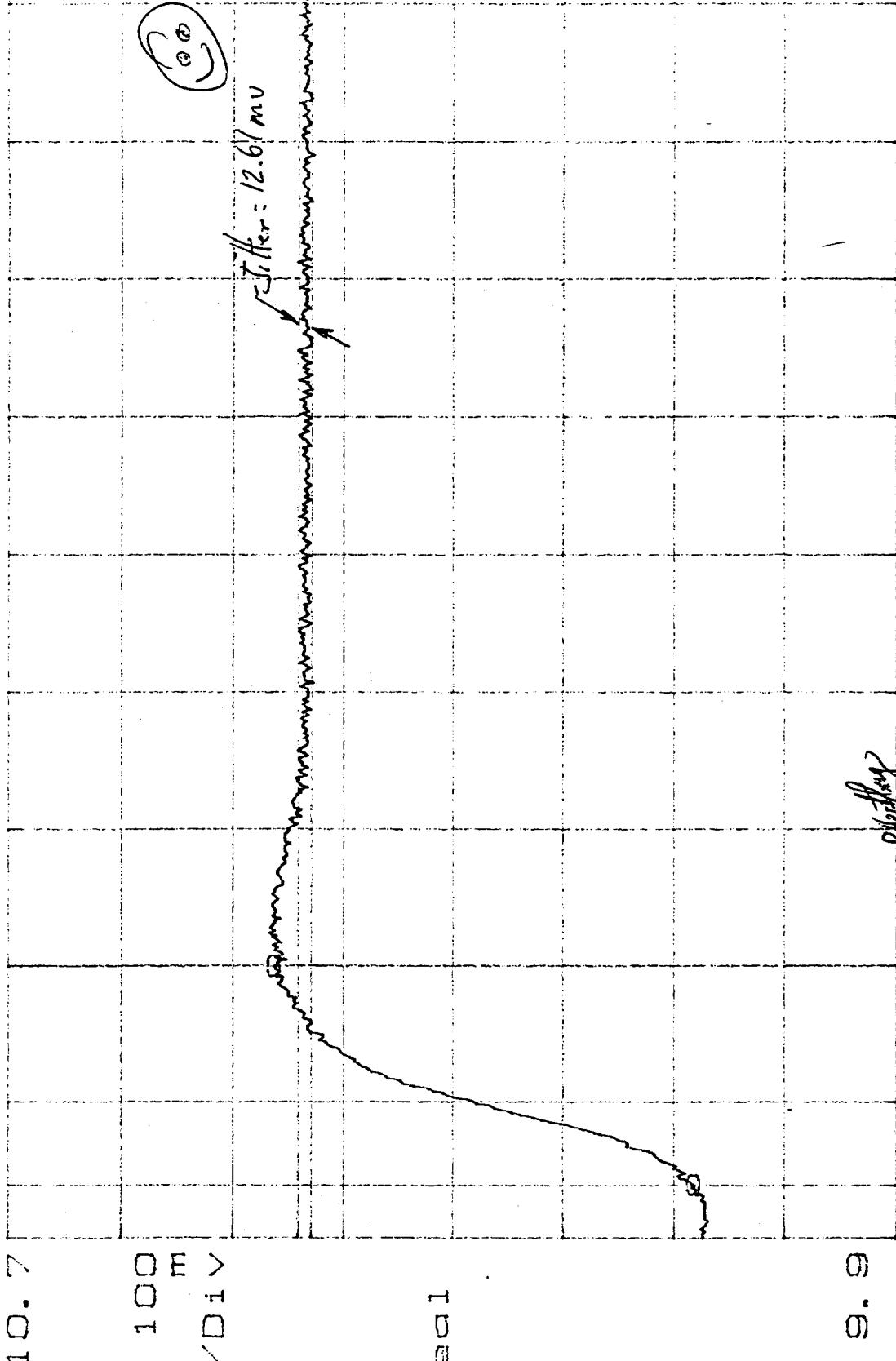
B25

$X = 4.831 \text{ S}$ $\Delta X = 35.16 \text{ mS}$

$Y = 10.081 \text{ V}$ $\Delta Y = 38.11 \text{ mV}$

CAP TIM BUF
10.7

$\Delta Y = 12.61 \text{ mV}$



9.9

Fxd X 4.82

Step 26 25

3.4.4.5

Test End: ~~May 25 1998~~

5/6: 436613

P/N: 1337720-2-1T SN: 105

Quality:

5.0

Date: 6-12-1998

7A 190

R710

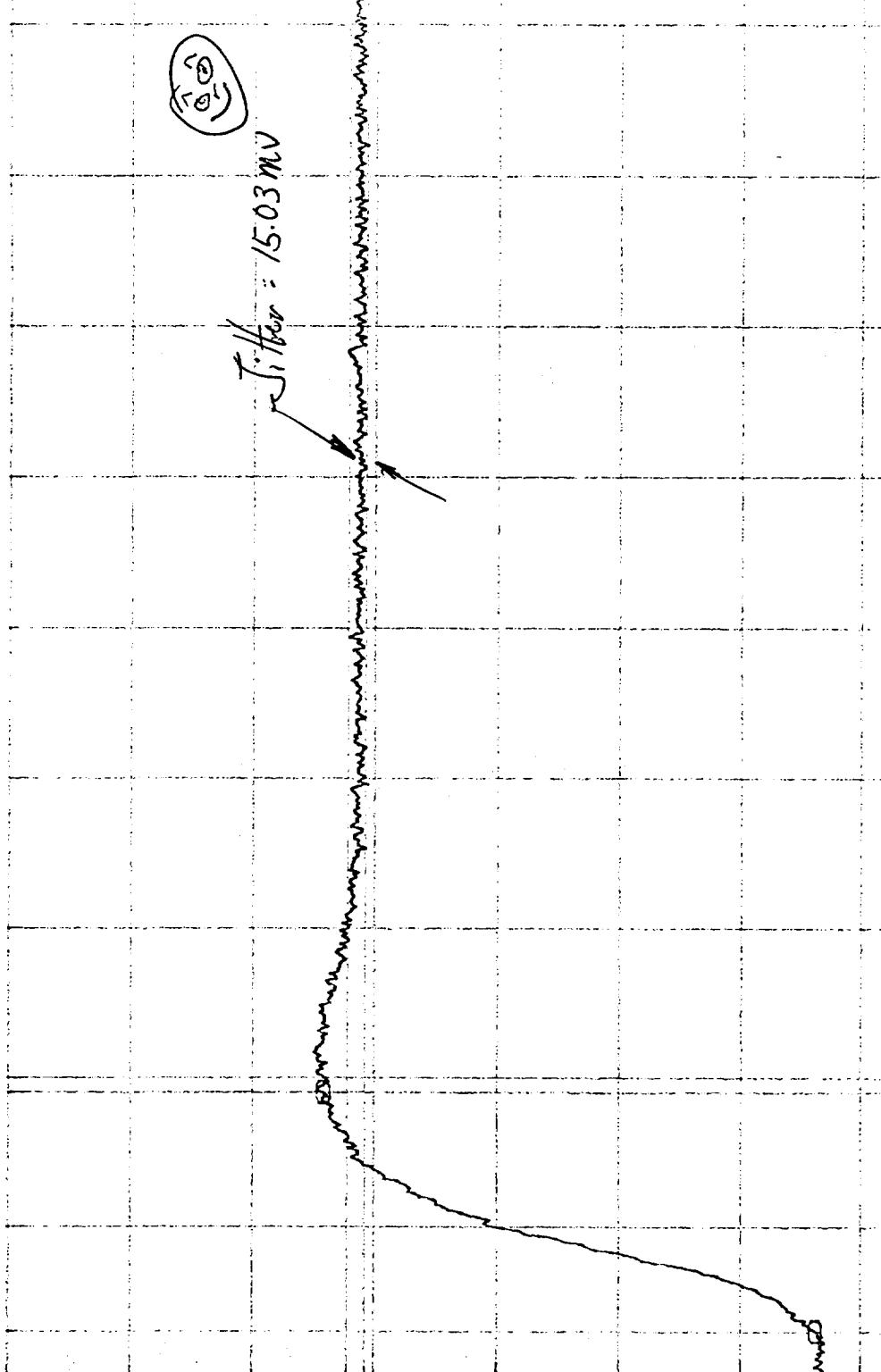
$X = 5.032 \text{ S}$ $\Delta X = 35.16 \text{ mS}$ $\gamma = 10.8217$ $\Delta \gamma = 15.03 \text{ mV}$

$\Delta Y = 4.364$ $\Delta Y = 40.3$ 3.8 mV
CAP TIN BUF
11.1

100
m
Div

Read 1

V



10.3

Fixed X 5.03 n-1 Step 2726
S/N: 436613

P/N: 1331120-2-17 SN: 105

Plotting
3.4A.5

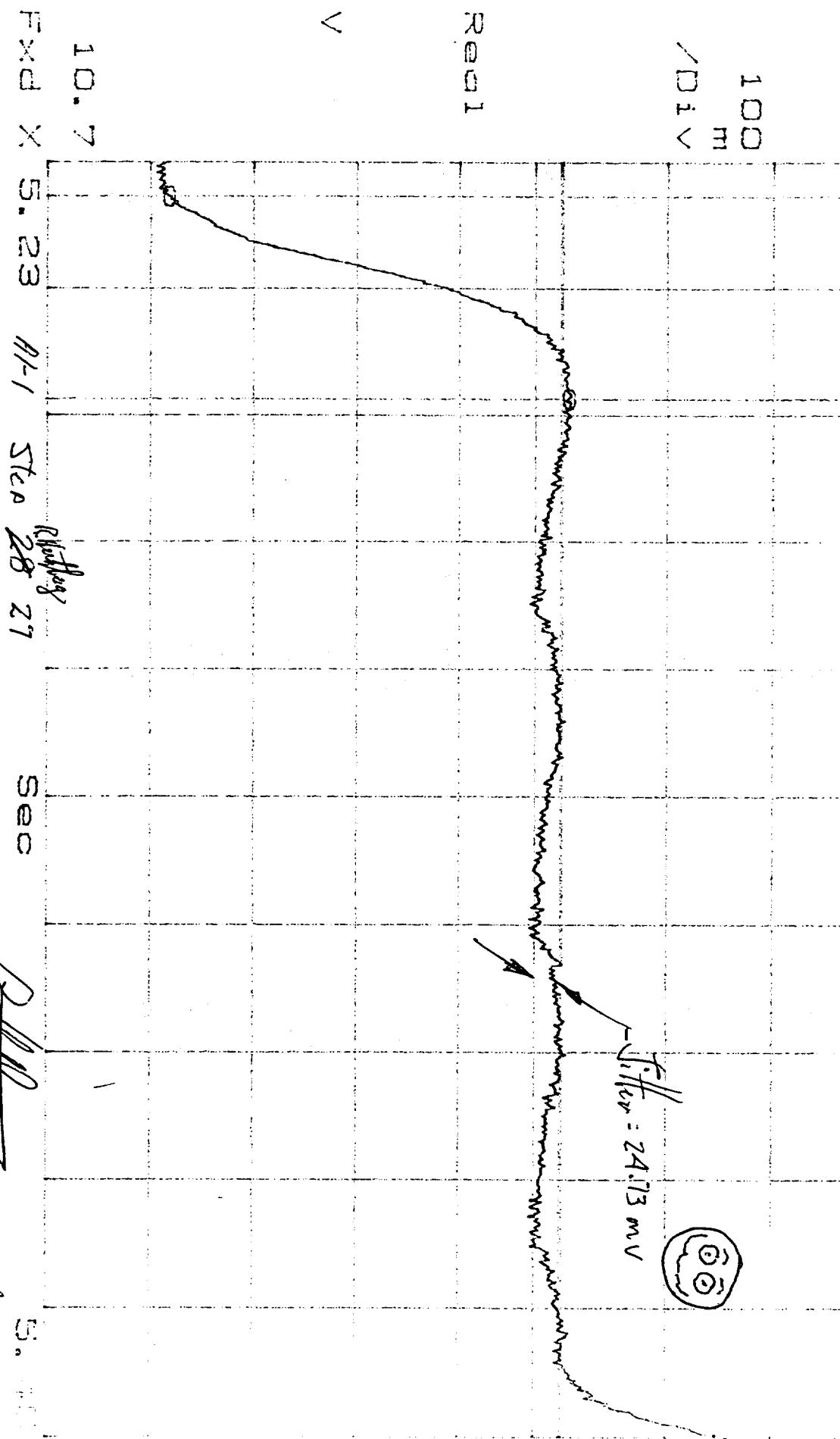
Sec
Test Eng: *Sayam* 7A
Qualif: *JM* 15-190

5. 22
Date: 13-12-93

B27

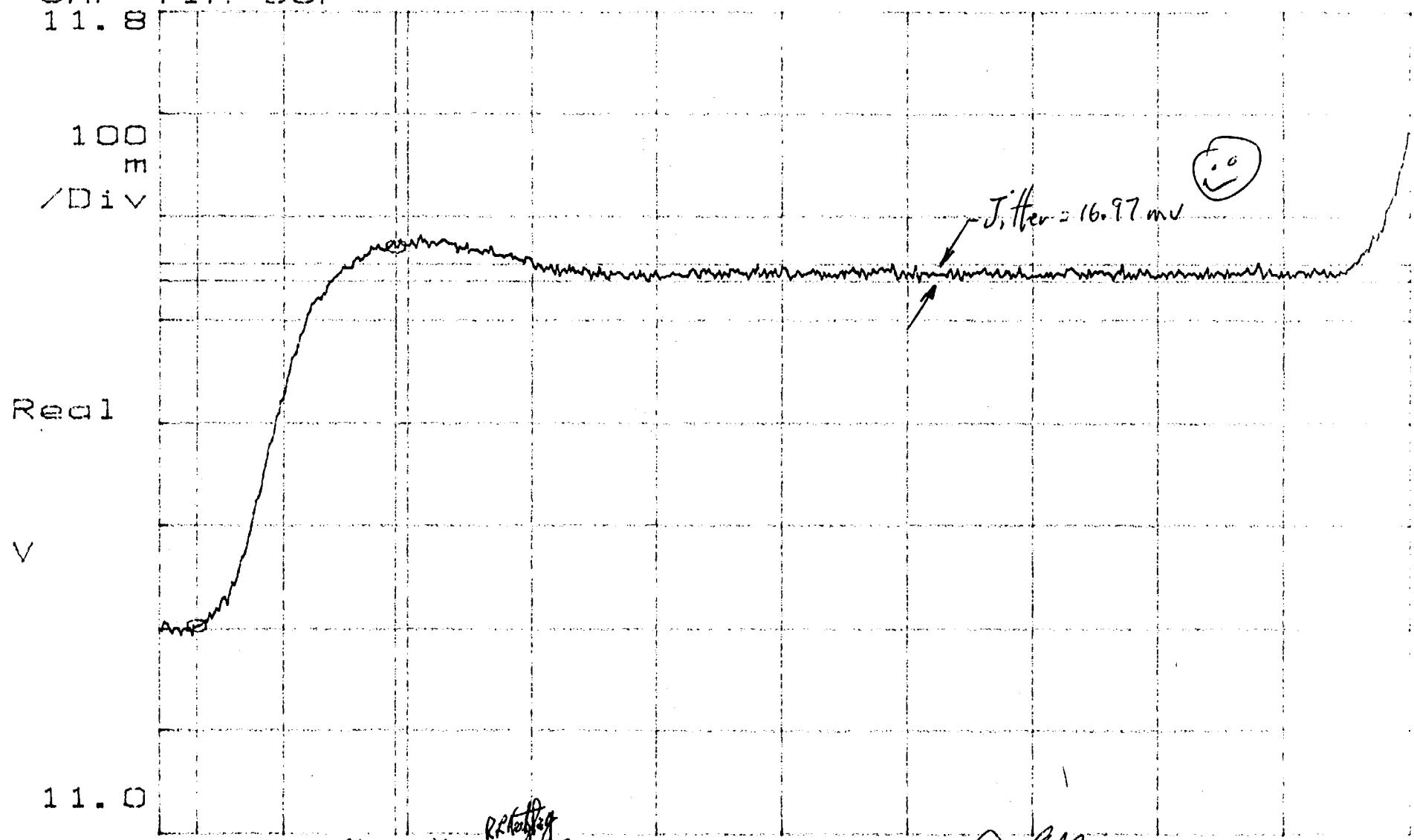
X=5.236 S AX=35.16mS Y=11.1979 ΔY=24.73mV

CAP TIM BUF
11.5



X=5.437 S AX=35.16mS Y=11.5542 AY=16.97mV
Yd=11.2019 AYd=368.2mV

CAP TIM BUF
11.8



S/N: 436613

P/N: 1331720-2-1T SN: 105

3.44.5

Sec

Test Eng: John H. Miller Date: 6/15/98

Quality:

7A
190 JUN 15 1998

B29

X=5.64 S
Y_d=11.549

ΔX=35.16mS
ΔY_d=377.9mV

Y=11.913

ΔY=12.61mV

CAP TIM BUF
12.2

100
m
/Div

Real

V

11.4

Fxd X 5.63

AI-1 Sca 30 29

R.P.Hanff

SO: 436613

3.4.5

PIN: 1331720-2-1T 50:105

Jitter = 12.61 mV



Sec

5.80

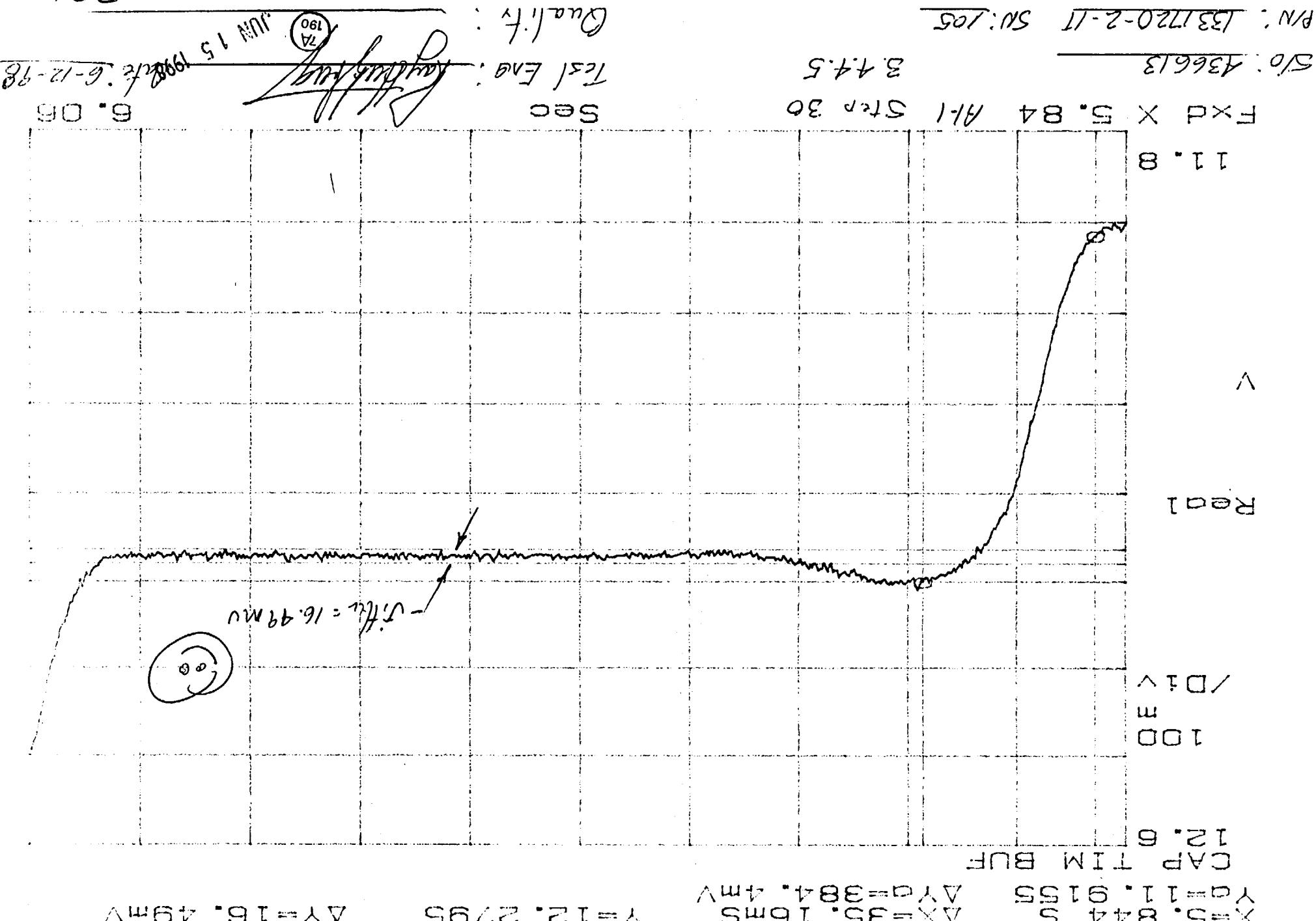
Test Eng: R.P.Hanff

Date: 6-14-98

Quality: JUN 15 1998 ^{TA} ₁₉₀

B30

B31



X=6.046 S
Yd=12.2788

AX=400.4mS
AYd=3.849 V

Y=16.0989

ΔY=34.91mV

CAP TIM BUF

17.6

800
m
/Div

Real

V

11.2

Fxd X 6.05 AM1 COLD CAL

S/N: 436613

3.44.5

P/N: 1331720-2-1T SN: 105

Sec

Test Eng:

Quality:

Ray Haffey

JUN 15 1998

7A
190

6.68

Date: 6-12-98

B32

Jitter: 34.71mV

68

X=6.5655 A=49.0ms V Y=26.6764

X=16.1599 A=16.5ms V

CAP TIM BUF
32.0

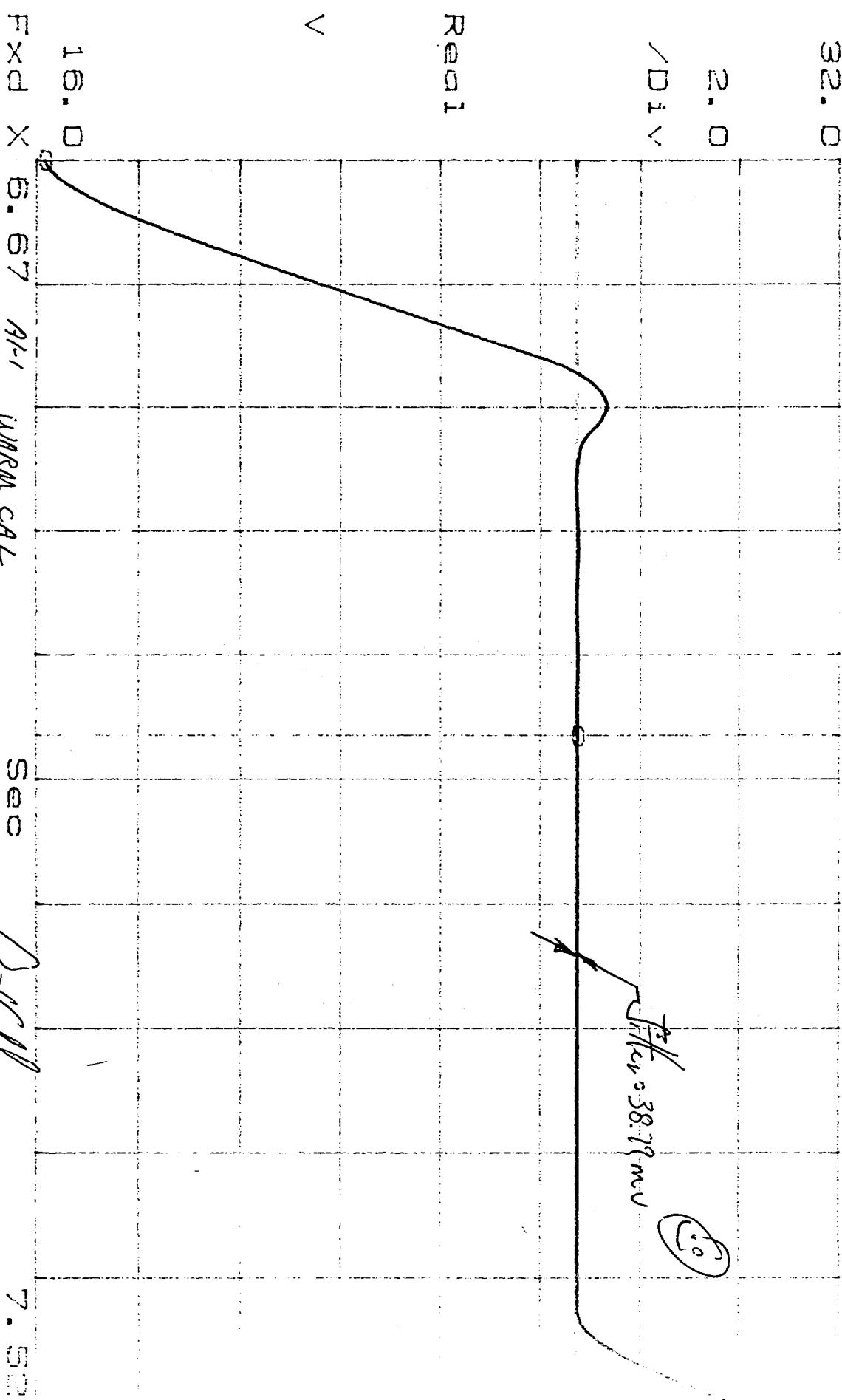
2.0
Div

Real

V

~~Th~~₂ = 38.79 mV

(∞)



Fxd X 6.67 ms

WARM CAL

Sec

7.52

S/N: 436613

P/N: 1331720-2-1T SW: 105

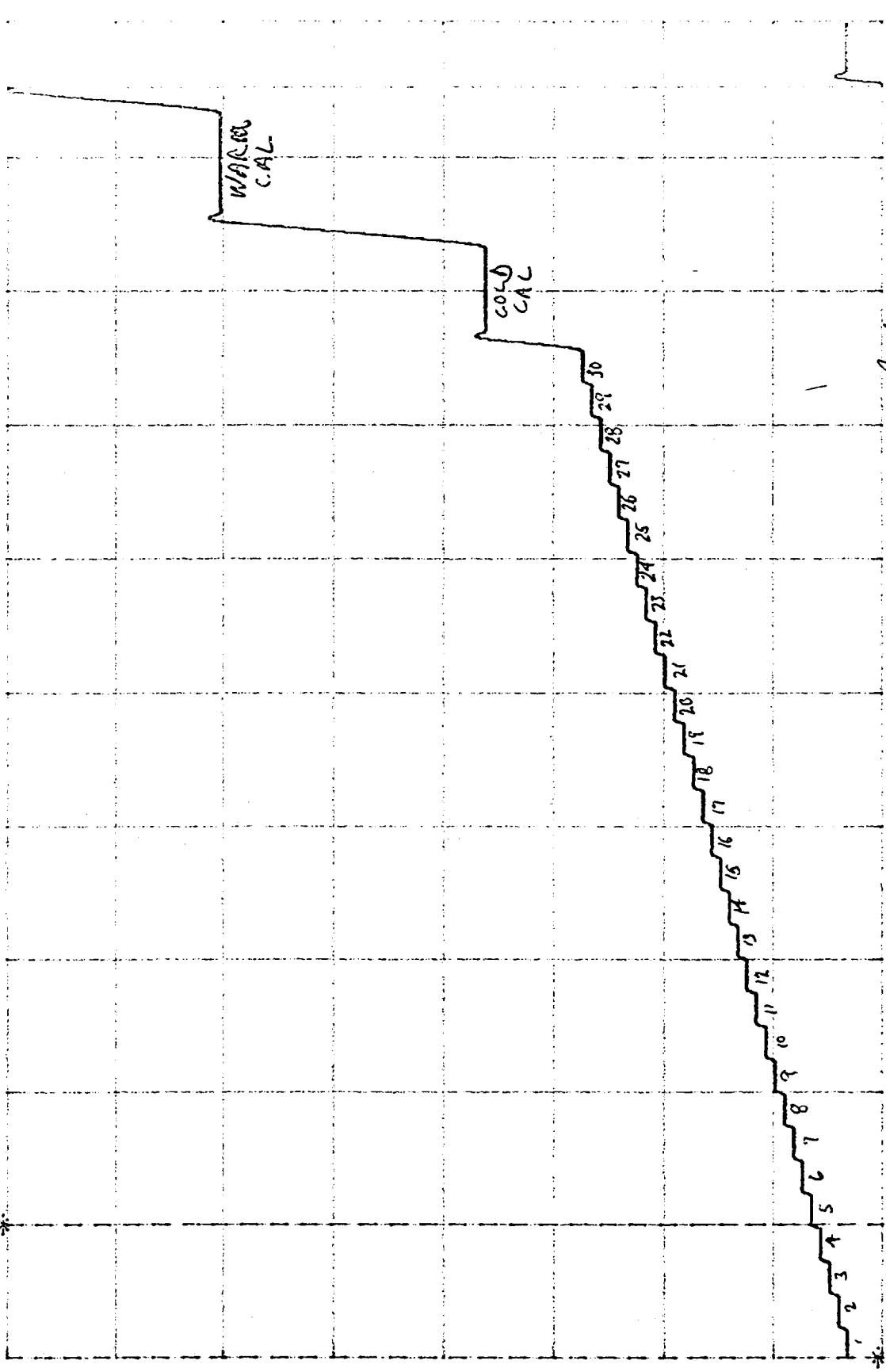
Test Eng: John H. Hwang Date: 6-12-98
Qualif: JUN 15 1998

CAP.TIM.BUF
36.0

4.5
1D i V

Recd.

v



Fx'd Y O. O Al-2 44 AP FS 5
S/N: 1331720-2-17 SU: 10⁵

S/N: 136615

P/N: JUN 15 1998 (74)
Date: 6-11-98
Quality:

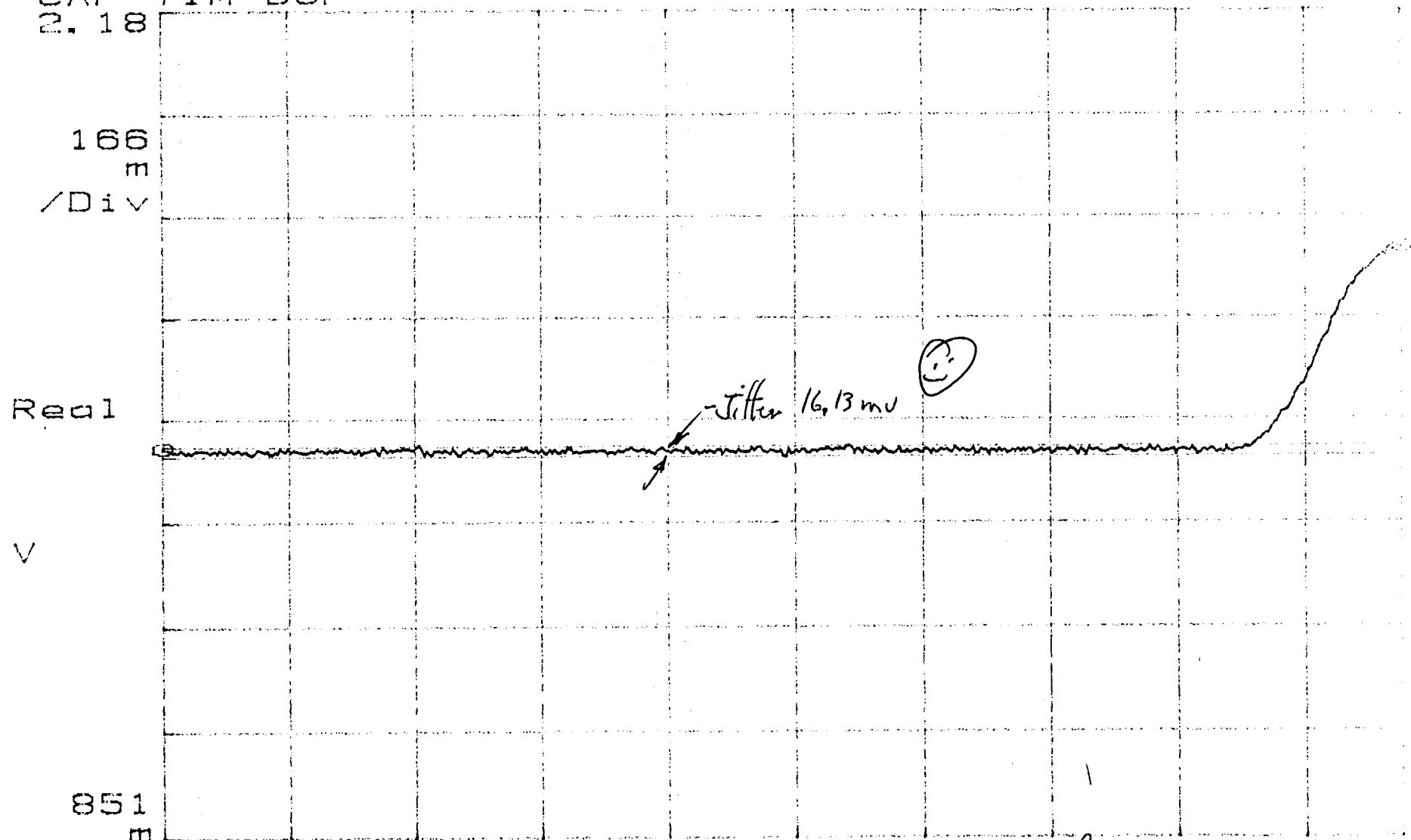
Test Eng: *Ramachandran*
Sec

JUN 15 1998
Qualit:

B34

$X=10.55\text{mS}$ $\Delta X=184.0\text{mS}$ $Y=1.45506$ $\Delta Y=16.13\text{mV}$
 $Y_0=1.46775$ $\Delta Y_0=327.6\text{mV}$

CAP TIM BUF
2.18



FxdXY 10.5m AI-2 Step 1
S/N: 936613 3.4.4.5
P/N: 1331720-2-1T SN: 105

Sec 199m
Test Eng: Rajesh Date: 6-12-98
Quality: JUN 15 1998 (7A 190))

B35

X=172.7mS $\Delta X=35.16\text{mS}$ Y=1.8177 $\Delta Y=13.19\text{mV}$
Y_d=1.47262 $\Delta Y_d=356.8\text{mV}$

CAP TIM BUF

2.0

80.0
m
/Div

Real

V

1.36

Fxd X 173m A1-2

Step 2

3.445

S/N: 436613

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: Ray Hulberg Date: 6-12-98

Quality: JUN 15 1998 7A 190

Jitter = 13.19 mV



B36

X=372. 3mS $\Delta X=35.16\text{mS}$ Y=2. 19753 $\Delta Y=21. 33\text{mV}$
Y_d=1. 81158 $\Delta Y_d=379. 5\text{mV}$

CAP TIM BUF

2. 4

80. 0

m

/Div

Real

V

1. 76

Fxd X 372m

AI-2

Step 3

56: 436613

PN: 1331720-2-1T SW: 105

Jitter = 21.33 mV



Sec

Test Eng: Ray Hergenrother Date: 6-12-98

Qualif: 7A 190 JUN 15 1998

B37

X=575.0ms
Y₀=2.18946 ΔX=35.16ms
ΔY₀=38.27.6mV
CAP TIM BUF
2.8

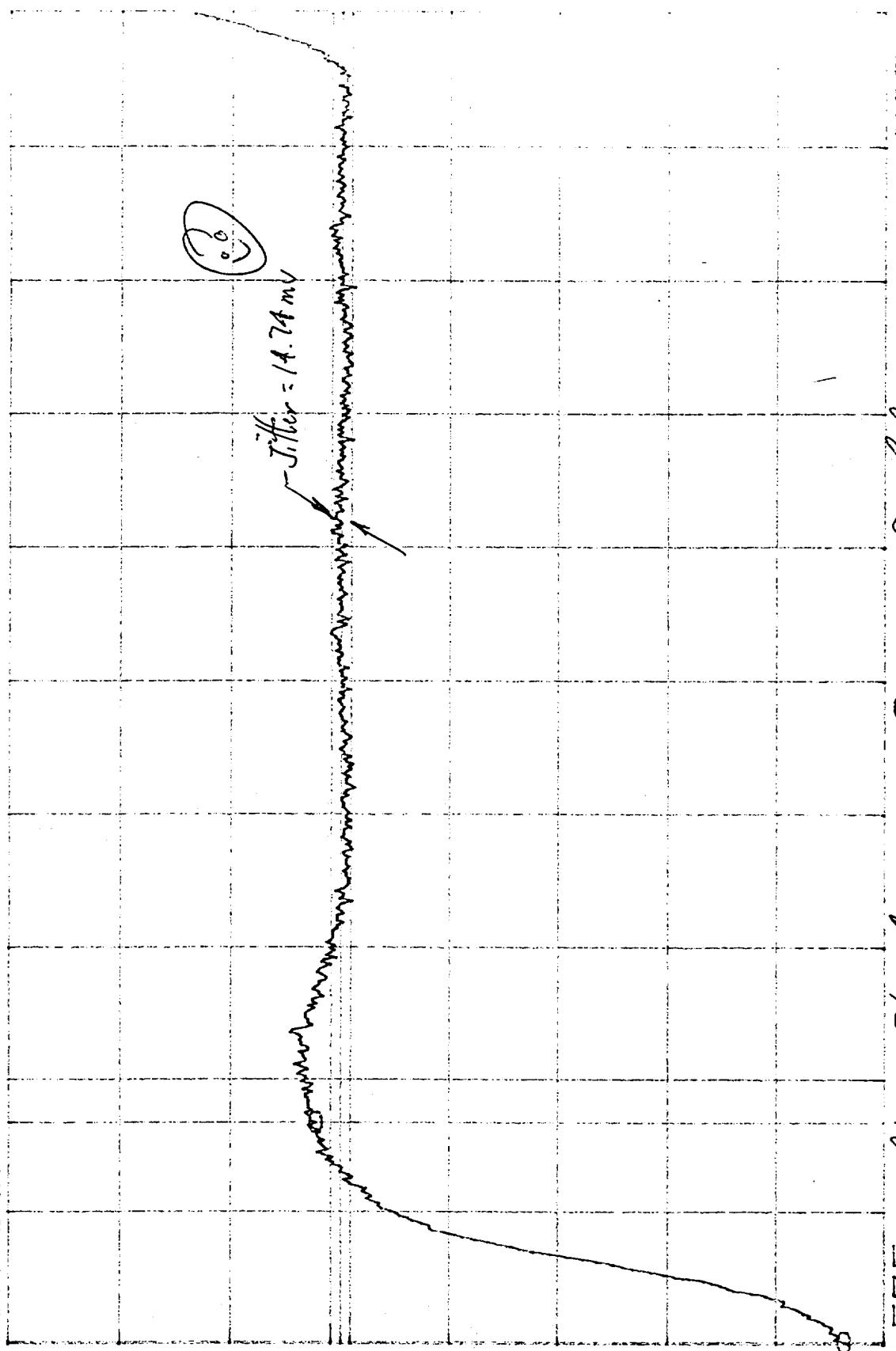
Y=2.566883

ΔY=14.74mV

80.0
/Div

Real

V



Fixd X 575m A1-2 Step +
S6: 436613
PH: 133720-2-1T Sd: 105

sec
Test Eng: Gilligan Date: 6-12-98
Qualit: JUN 15 1998 (7A)

78711
R3.8

$X_0 = 777.55762$ $\Delta X = 35.16mS$ $\gamma = 2.94274$ $\Delta \gamma = 3.97.3mV$
CAP TIM BUF
3.12

$\Delta Y_0 = 2.55762$ $\Delta Y = 13.58mV$ $\Delta Y = 13.58mV$

80. 0
101 V

Real

(19)

Jitter
- 13.58 mV

V

2. 48

5/6:

136613

Fixed X 777m Al-2 Step 5

3.44.5

sec

Test Eng: ~~Autotiming~~ Date: 6-15-98

PN: 1331720-2-1T SN: 105

Qualif.: Passing

7A
190

Run 15 1998

B39

X=980. 9mS
Yd=2. 94199

ΔX=35. 16mS
ΔYd=395. 7mV

Y=3. 32257

ΔY=13. 58mV

CAP TIM BUF
3. 52

80. 0
m
/Div

Real
V

2. 88

Fxd X 981m AI-2 Sta 6
S/N: 136613 3.4.15

P/N: 1331720-2-1T SN: 105

Jitter = 13.58 mV



Sec
Test Eng: Ray Tech Ray Date: 6/12/98
Quality: JUN 15 1998 7A
1. 15
190

RKHS

X=1.184 S
Y_a=3.31663 A
CAP TIM BUF
3.92

A X=35.16ms
A Y_a=389.2mV

Y=3.69348

$\Delta Y = 1.2 \cdot -4.1 \text{ mV}$

80.0
Div

(2)

-J_{fur} = 12.41 mV

Recal

V

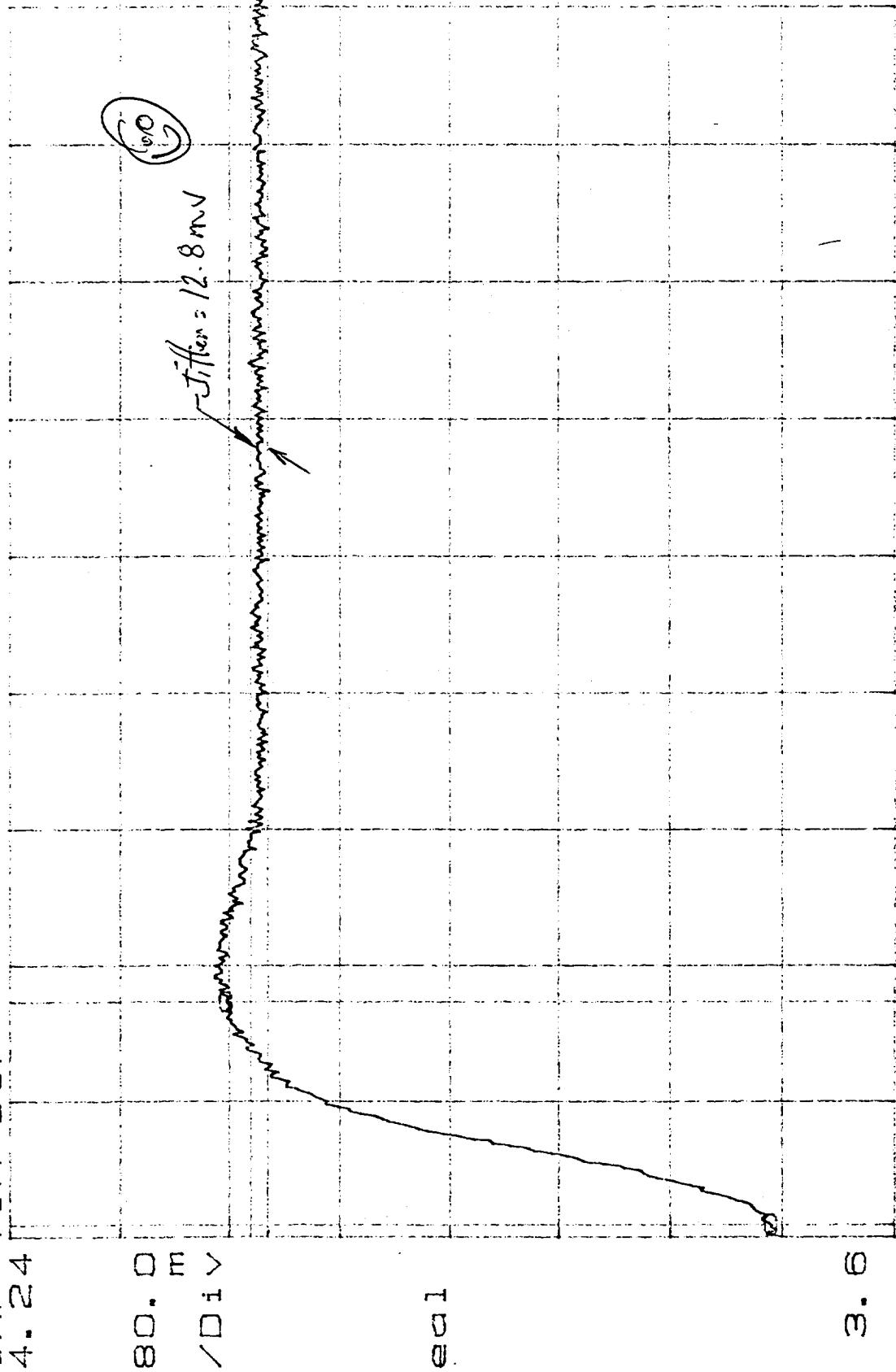
Fxd X 1.18 Al-2 Step 7
3.41.5
S/N: 1331720-2-11 SN: 105

1. 333
Sec

Test Eng. John Date: 6/12/98
Quality: 7A (190) JUN 15 1998
Butt

$X = 1.385 \text{ S}$ $\Delta X = 35.16 \text{ mS}$
 $Y_d = 3.68803$ $\Delta Y_d = 3.94.1 \text{ mV}$
C.A.P. TIM BUF
4. 24

$\Delta Y = 4.06429$ $\Delta Y = 12.8 \text{ mV}$



3. 6
Fixed X 1. 38 A1-2 Step 8
S/N: 13.3/120-2-1T SN: 105

Date: 6-12-98

Quality: JUN 15 1998 (TA 190)

B42

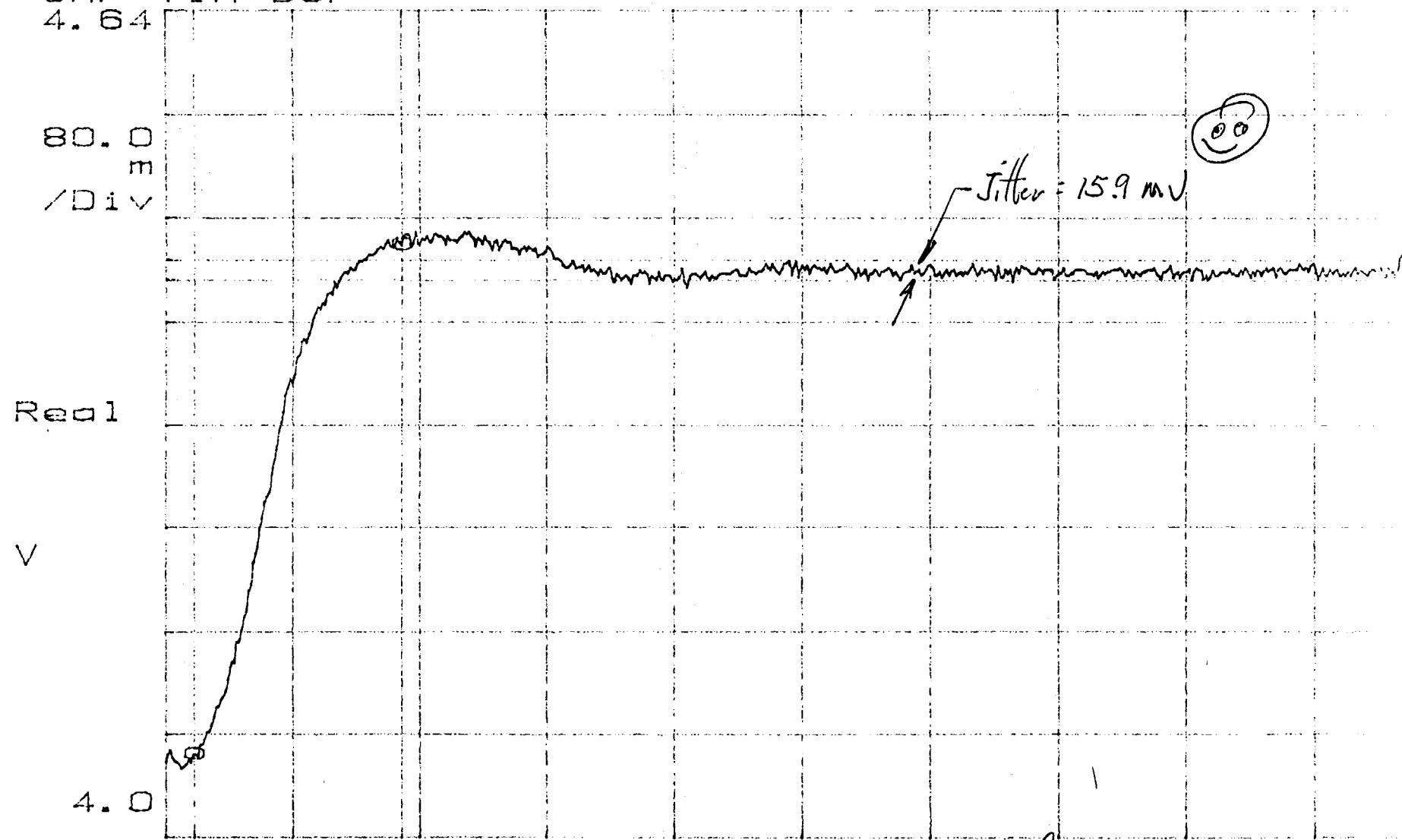
X=1.589 S
Yd=4.06429

$\Delta X=35.16\text{mS}$
 $\Delta Yd=395.7\text{mV}$

Y=4.44761

$\Delta Y=15.9\text{mV}$

CAP TIM BUF
4.64



SL: 436613

P/N: 1331720-2-1T SO: 105

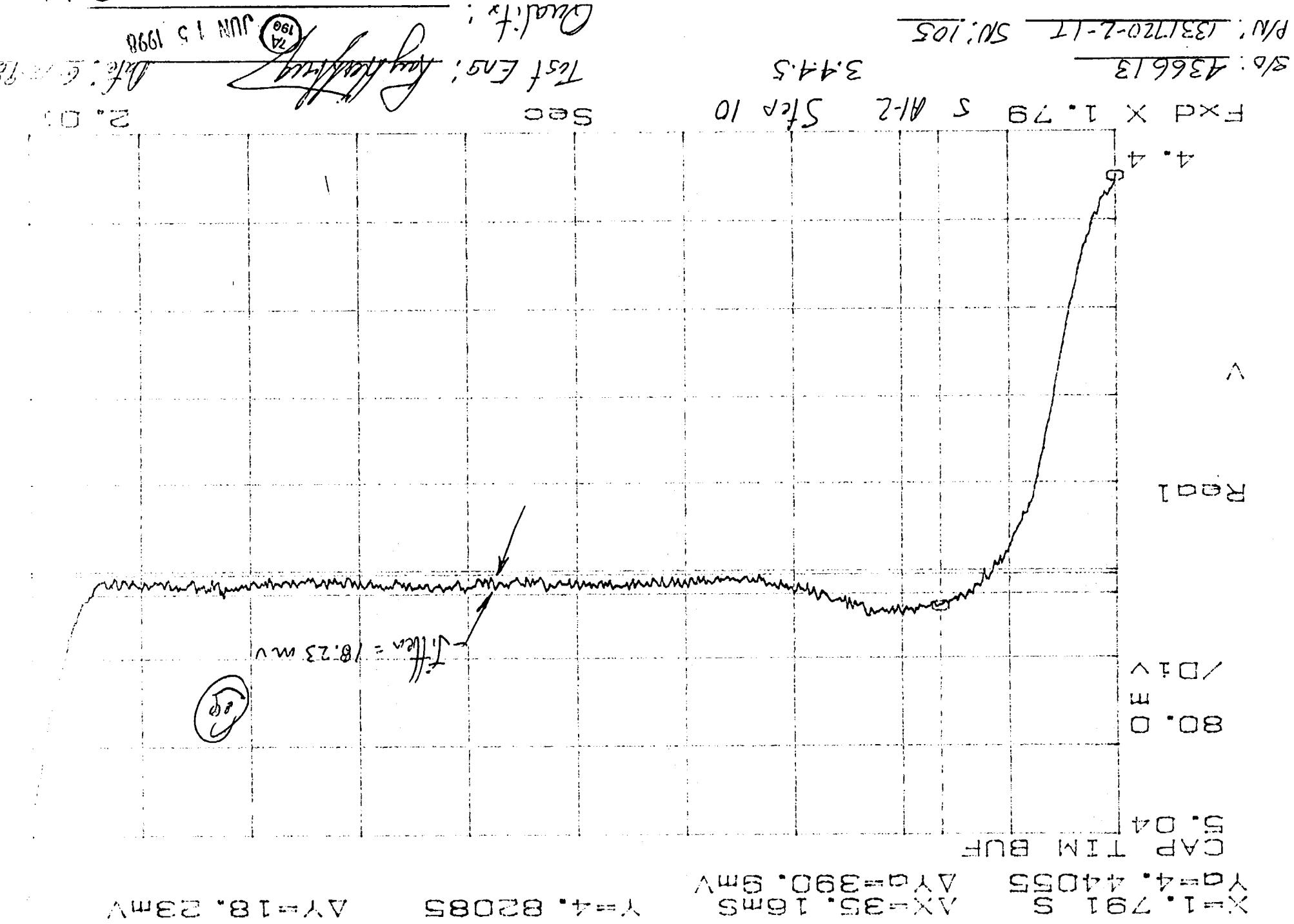
Sec
Test Eng: Ray Hulberg

Quality: JUN 15 1998 7A
190

1.8 Date: 6-12-98

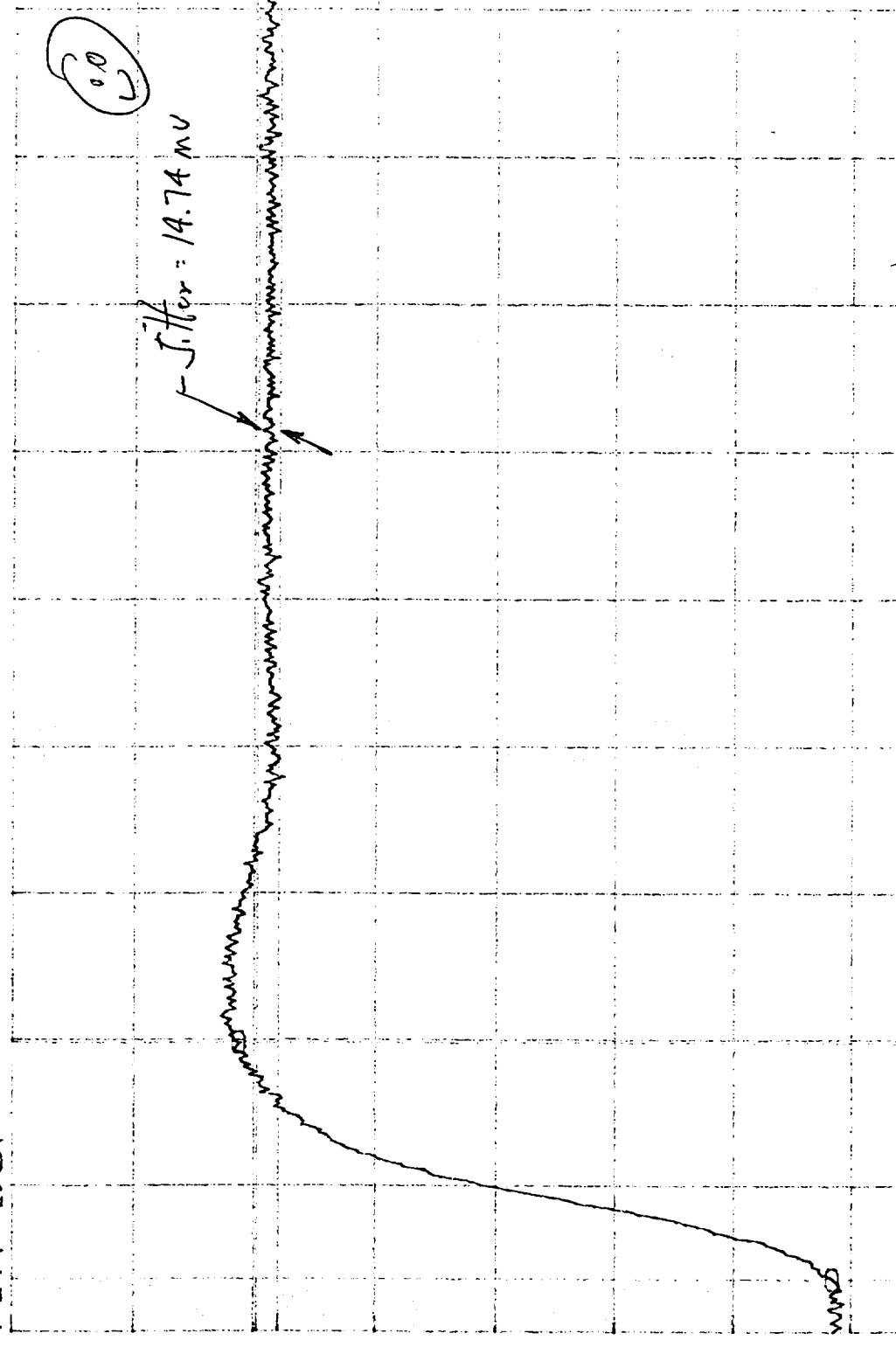
B43

R44



X=1.993 S ΔX=35.16mS Y=5.19787 ΔY=14.74mV

CAP TIN BUF
S. 36



Recd 1

V

4.72

Fwd X 1.99

A1-Z

Stc A 11

Sec

S/N: 136613

3.44.5

SN: 105

Test Eng: *Ray Haffey* Date: 6/13/98
Qualif: JUN 15 1998 (7A)
199

B45

X=2.196 S AX=35.16mS Y=5.5777 ΔY=14.35mV
Yd=5.19795 AYd=392.5mV

CAP TIM BUF
5.76

80.0
m
/Div

Real

V

5.12

Fxd X 2.19

AI-2

Sta 12

Sec

SO: 436613

3.44.5

P/N: 1331720-2-17

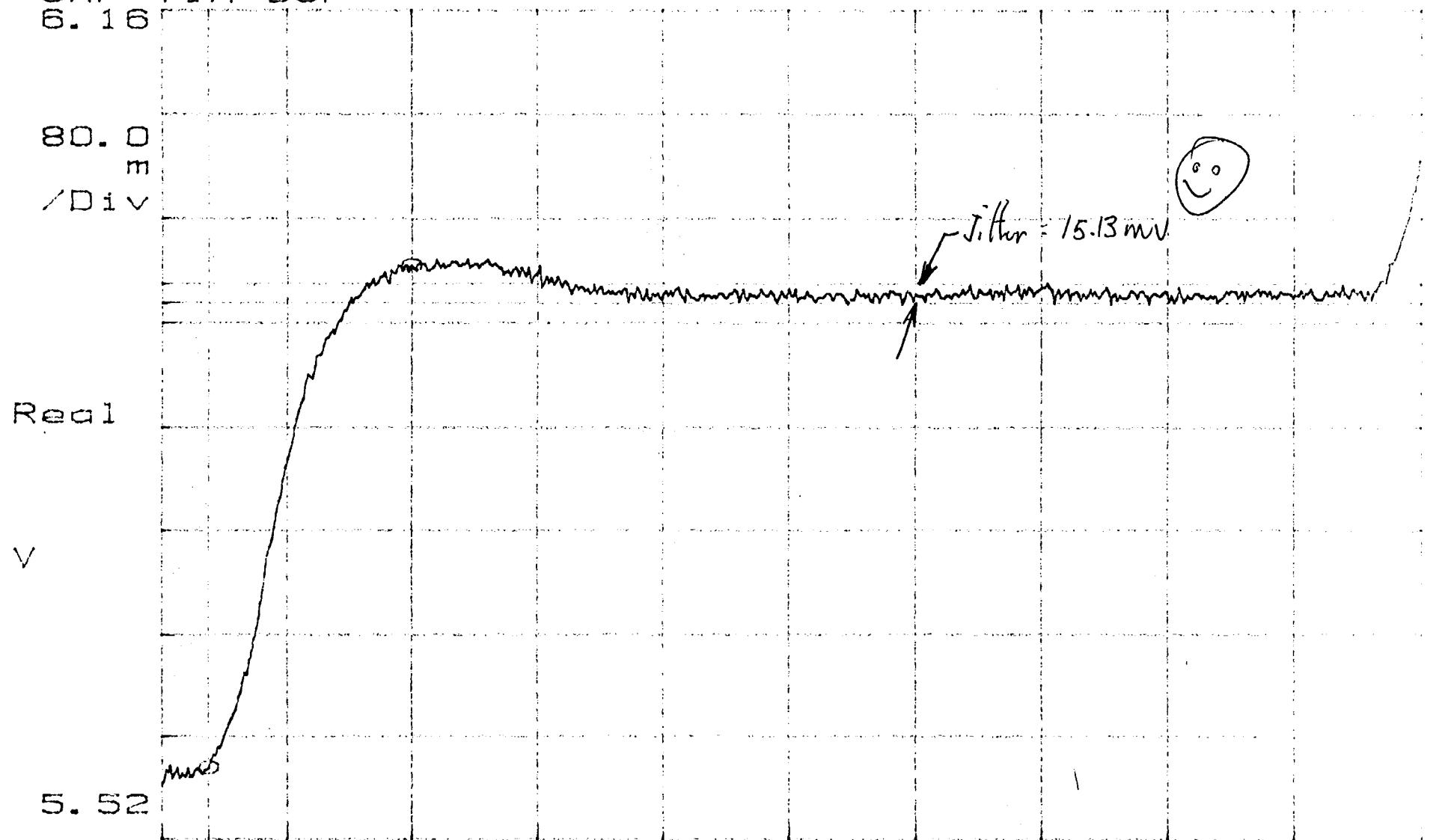
Test Eng: Payne/Han Date: 07-1998
Quality: JUN 15 1998
7A
190 B446

Jitter = 14.35mV



X=2.4 S AX=35.16mS Y=5.94977 ΔY=15.13mV
YA=5.57583 ΔYA=387.6mV

CAP TIM BUF
6.16



5.52

Fxd X 2.39

AI-2

Sta 13

Sec

2.0

SL: 436613

34.4.5

Test Eng: Ray Herting

Date: 6/1/98

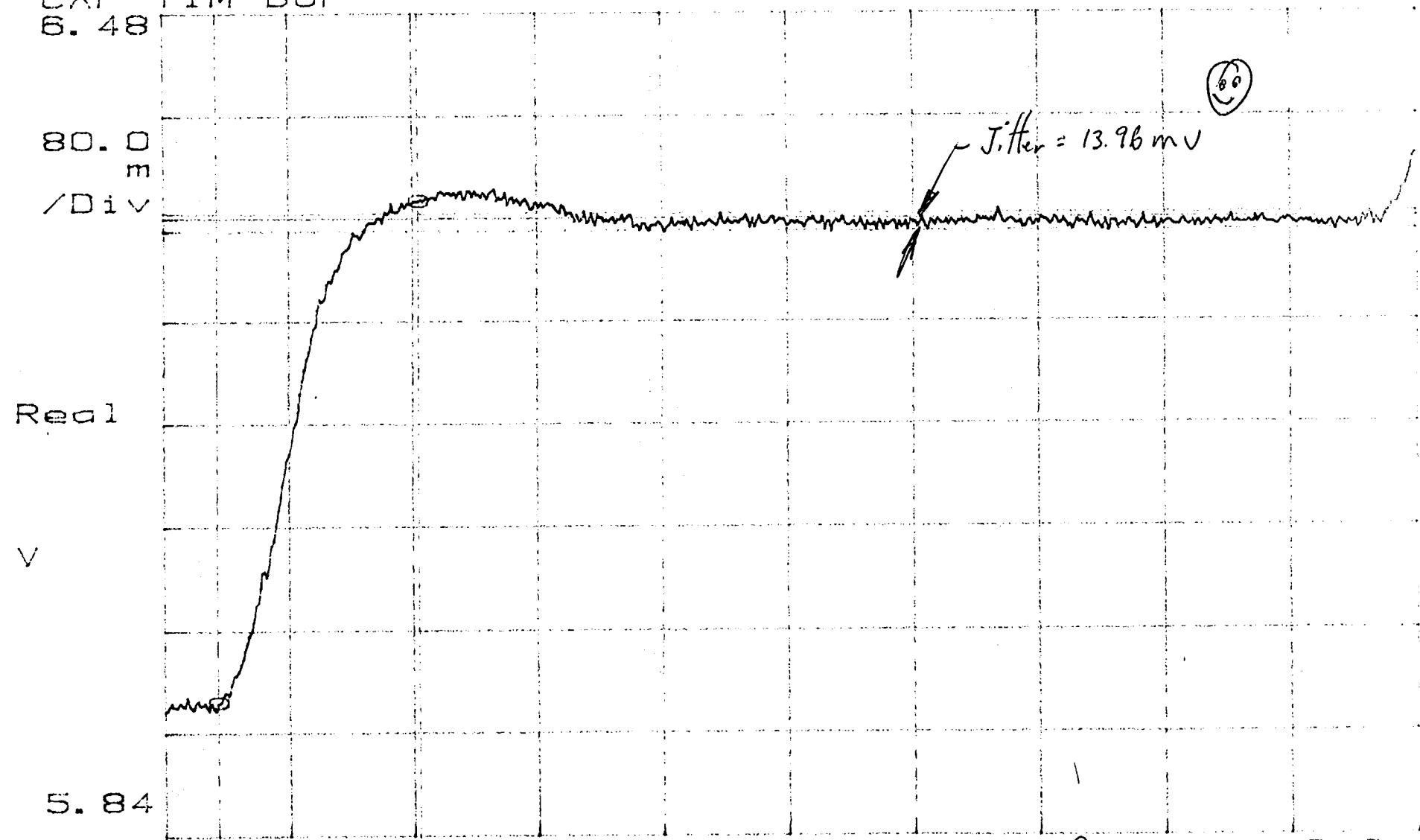
P/N: 1331720-2-17 SN: 105

Quality: JUN 15 1998 7A 190

B47

X=2.601 S AX=35.16mS Y=6.32368 ΔY=13.96mV
YA=5.94398 ΔYA=389.2mV

CAP TIM BUF
6.48



S/N: 436613

P/N: 1331720-2-1T SN: 105

Fxd X 2.59 AI-2 Step 14

3.4-4.5

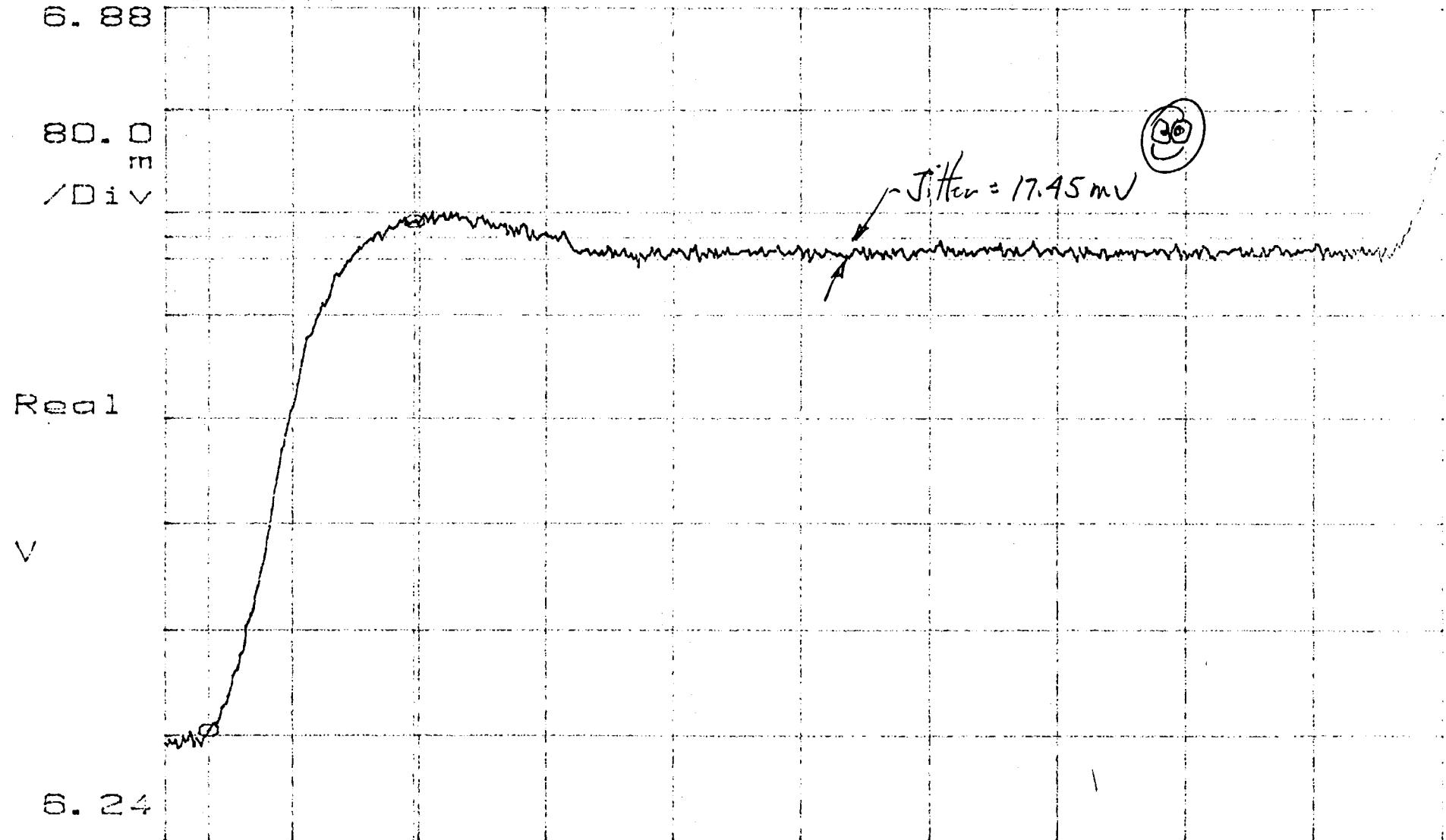
Sec

Test Eng: Ray Huppert Date: 6-14-98
Quality: 74/190 JUN 15 1998

B48

X=2.804 S AX=35.16mS Y=6.7008 ΔY=17.45mV
Yd=6.32349 ΔYd=389.2mV

CAP TIM BUF
6.88



Fxd X 2.8 Al-Z Step 15
S/N: 436613 3.14.5
P/N: B31720-2-1T SN: 105

Sec 3.01

Test Eng: Pay Bergman Date: 6-12-98

Quality: JUN 15 1998 74 190

R49

X=3.006 S
Y_d=6.69165

ΔX=35.16mS
ΔY_d=392.5mV

Y=7.07559

ΔY=15.52mV

CAP TIM BUF
7.28

80.0
m
/Div

Real

V

6.64

Fxd X 3.0

A1-2 Step 16

Slo: A36613

3.4.45

P/N: 1331720-2-1T

SN: 105

Sec

Test Eng: Kay H. Berg

Qualtr: JUN 15 1998 24/190

3.22

Date: 6/12/98

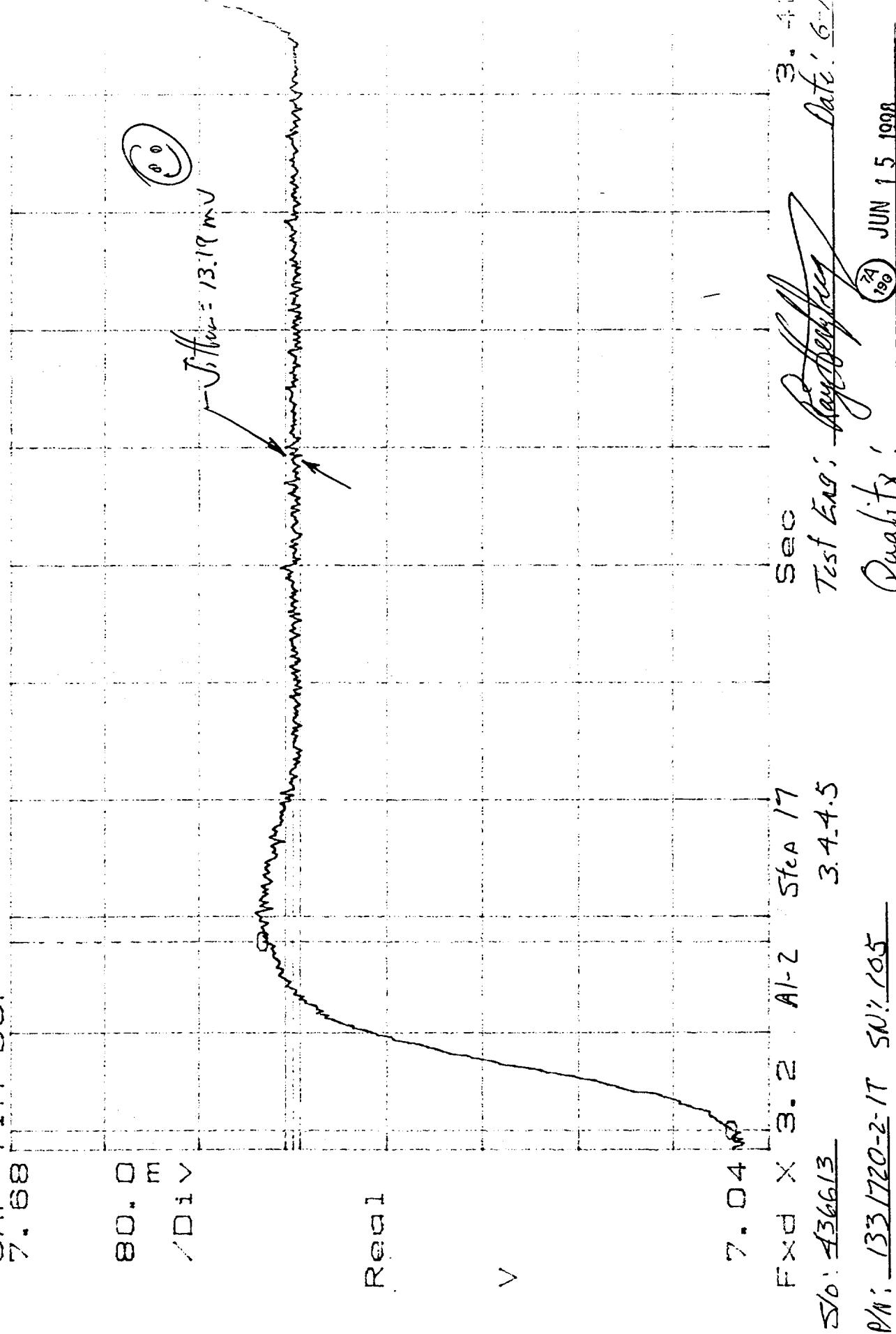
B50

Jitter: 15.52 mV



X=3.208 S $\Delta X=35.16 \text{mS}$
Y₀=7.07115 $\Delta Y_0=394.1 \text{mV}$
CAP TIM BUF
7.68

$\gamma = 7.4465$ $\Delta \gamma = 13.19 \text{mV}$



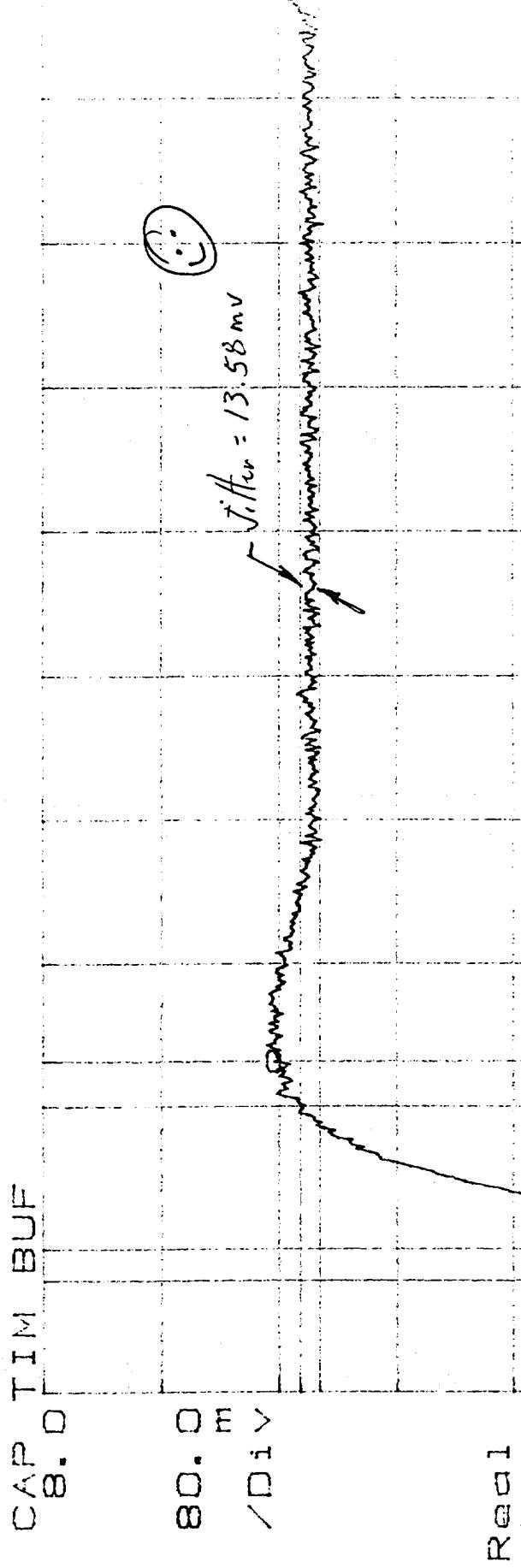
PN: 1331720-2-17 SN: 105

Quality: 7A/160 JUN 15 1998

R51

$X = 3.4115$ $\Delta X = 35.16 \text{ mS}$
 $Y = 7.4409$ $\Delta Y = 402.2 \text{ mV}$

$\gamma = 7.82623$ $\Delta \gamma = 13.58 \text{ mV}$



3. E.S.
Test Eng: Ray Hembree Date: 6-12-18
Qual. Tr.: JUN 15 1998 7A 150

S/N: 436613
PN: 1331720-2-1T SN: 105

R52

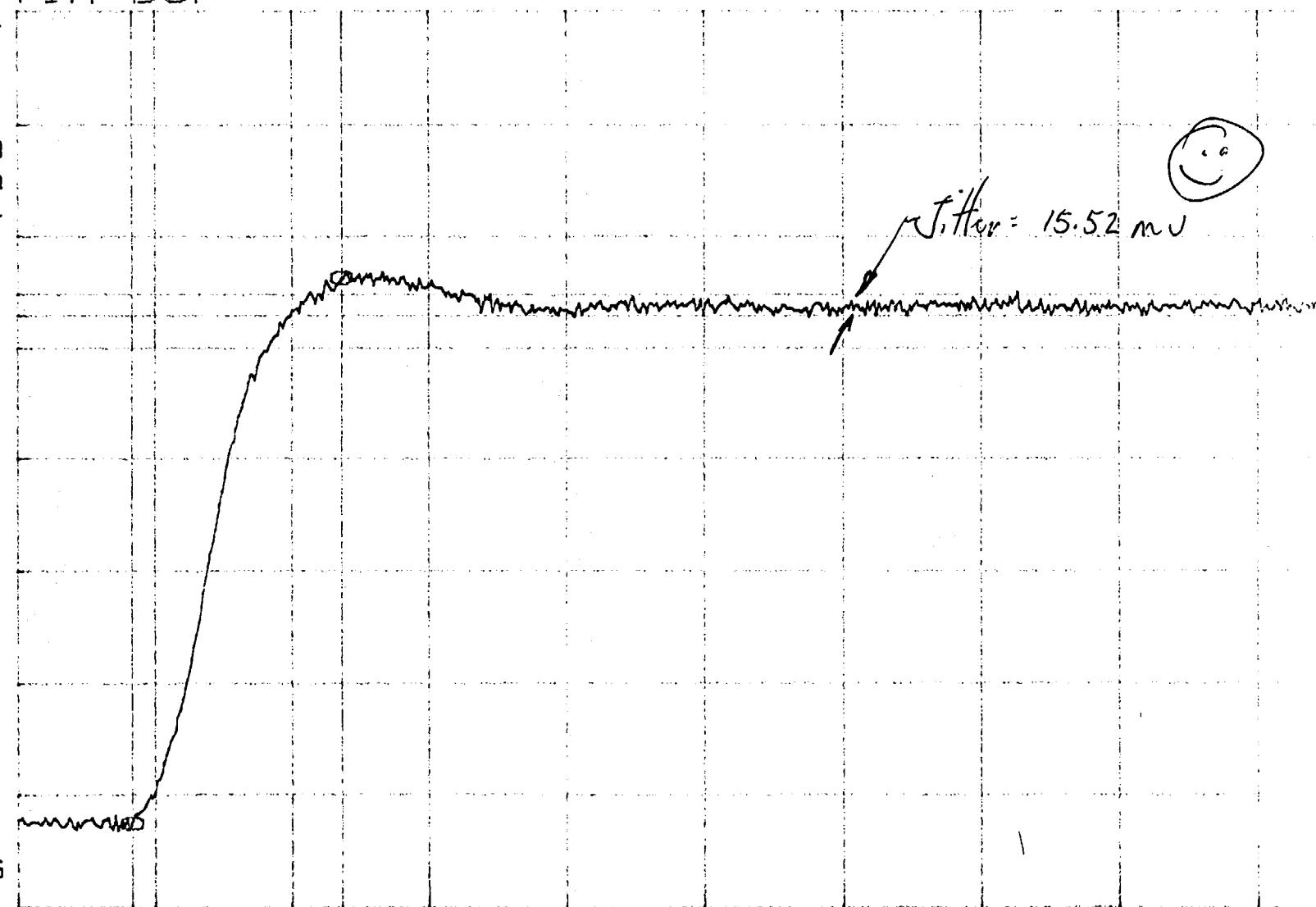
X=3.613 S AX=35.16mS Y=8.1983 ΔY=15.52mV
Yd=7.81881 ΔYd=390.9mV

CAP TIM BUF
8.4

80.0
m
/Div

Real

V



Fxd X 3.59

AI-2

Stc 19

S/N: 436613

3.44.5

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: Raytheon Date: 6/18/98

Qualtr: JUN 15 1998

74
190

B53

X=3.814 S $\Delta X=35.16\text{mS}$ Y=8.57852 $\Delta Y=16.68\text{mV}$
Y_a=8.19021 $\Delta Y_a=394.1\text{mV}$

CAP TIM BUF
8.8

80.0
m
/Div

Real

V

8.16

Fxd X 3.8 AI-2 Step 20

S/N: 436613

P/N: 1331720-2-1T SN: 105

3.44.5

Sec

Test Eng: Ray Lohberg Date: 6-16-98
Quality: JUN 15 1998 (24)

4.11

16

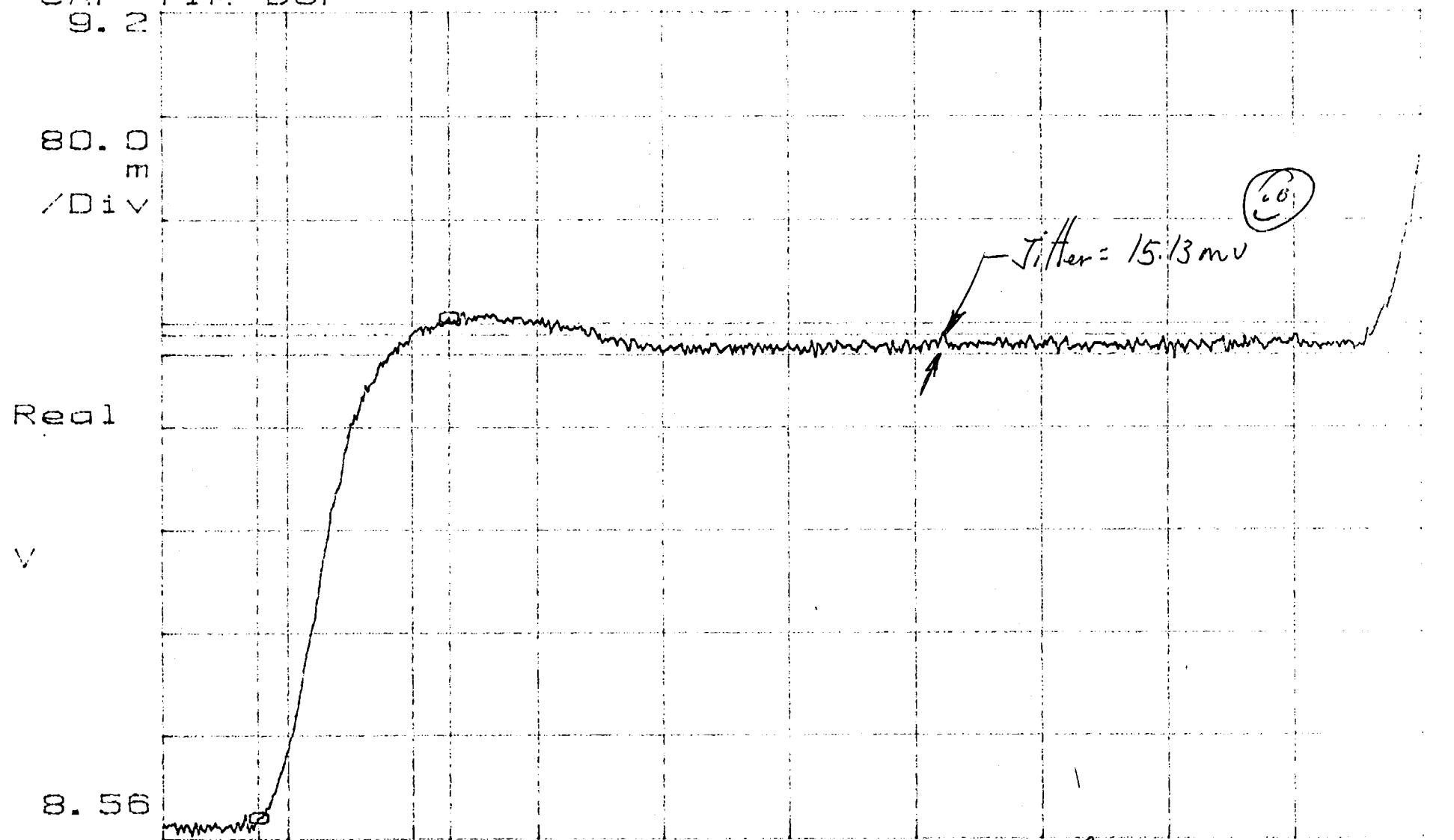
B54

$\Delta V = 16.68\text{mV}$



X=4.019 S $\Delta X=35.16\text{mS}$ Y=8.95098 $\Delta Y=15.13\text{mV}$
Y_d=8.57621 $\Delta Y_d=387.6\text{mV}$

CAP TIM BUF
9.2



Fxd X 4.0 AI-2 Step 21
S/N: 136613
P/N: 133M20-2-1T SN: 105

Sec
Test Eng: Patterson Date: 6/16/98
Qualif: QA, JUN 15 1998

B55

X=4.221 S $\Delta X=35.16\text{mS}$ Y=9.32373 $\Delta Y=12.8\text{mV}$
Y_d=8.9476 $\Delta Y_d=387.6\text{mV}$

CAP TIM BUF
9.52

80.0
m
/Div

Real

V

8.88

Fixd X 4.2 AI-2 Step 22

SO: 136613

3.44.5

AN: 1331720-2-1T SN: 105

Sec

Test Eng: Paynter

Quality: JUN 15 1998 (24)
1998

Date: 6-15-98

Jitter = 12.8 mV

B56

X=4.423 S
Y₀=9.319

ΔX=35.16mS
ΔY₀=397.3mV

Y=9.70395

ΔY=14.74mV

CAP TIM BUF
9. 92



Fxd X 4.4

AI-2

Step 23

Sl: 436613

3.445

P/N: 1331720-2-1T SN: 105

Sec

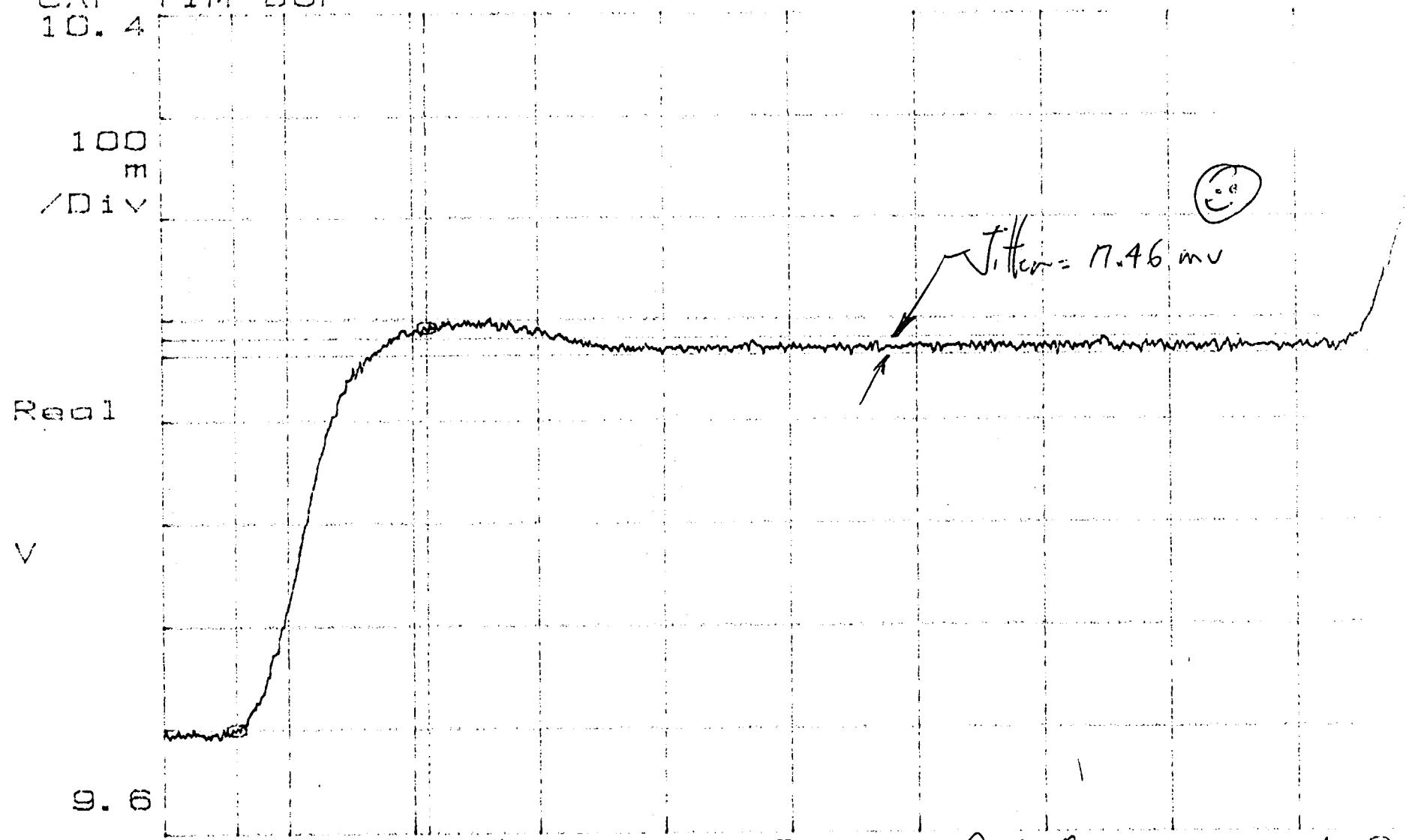
Test Eng: Paynter Date: 6-10-98

Quality: JUN 15 1998

B57

X=4.626 S AX=35.16mS Y=10.0815 ΔY=17.46mV
Yd=9.69851 ΔYd=392.5mV

CAP TIM BUF
10.4



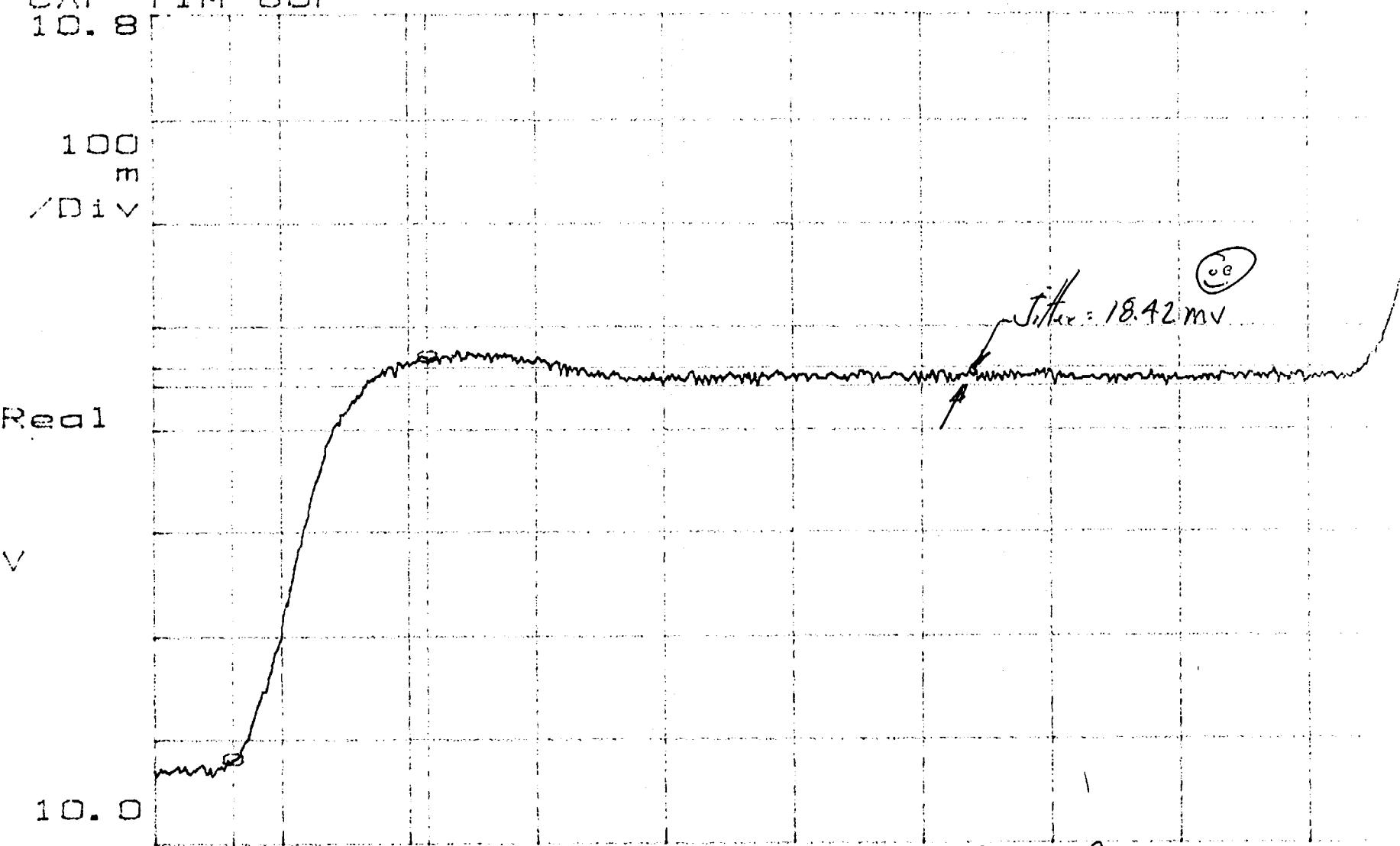
Fxd X 4.61 AI-2 Step 24
S/N: 436613 3.4.4.5
P/N: 1331720-2-1T SN: 105

Test Eng: P. J. H. H. G. Date: 6-12-98
Quality: JUN 15 1998 QA
100

B58

X=4.83 S $\Delta X=35.16\text{mS}$ Y=10.4601 $\Delta Y=18.42\text{mV}$
Yd=10.0813 $\Delta Yd=389.2\text{mV}$

CAP TIM BUF
10. 8



Fxd X 4.82 A1-2 Step 25

S/N: 136613

P/N: 1331720-2-1T SN: 105

Sec 5.05
Test Eng: Payberg Date: 6-12-78
Quality: 24 JUN 15 1998 B59

X=5.03 S $\Delta X=35.16 \text{mS}$ Y=10.8319 $\Delta Y=17.94 \text{mV}$
Yd=10.4494 $\Delta Y_d=387.6 \text{mV}$

CAP TIM BUF

11.1

100
m

/Div



Jitter = 17.94 mV

Real

V

10.3

Fxd X 5.01

AI-2 Step 26

Sl#: 436613

3.4.4.5

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: Ray Hergenrother

5.0

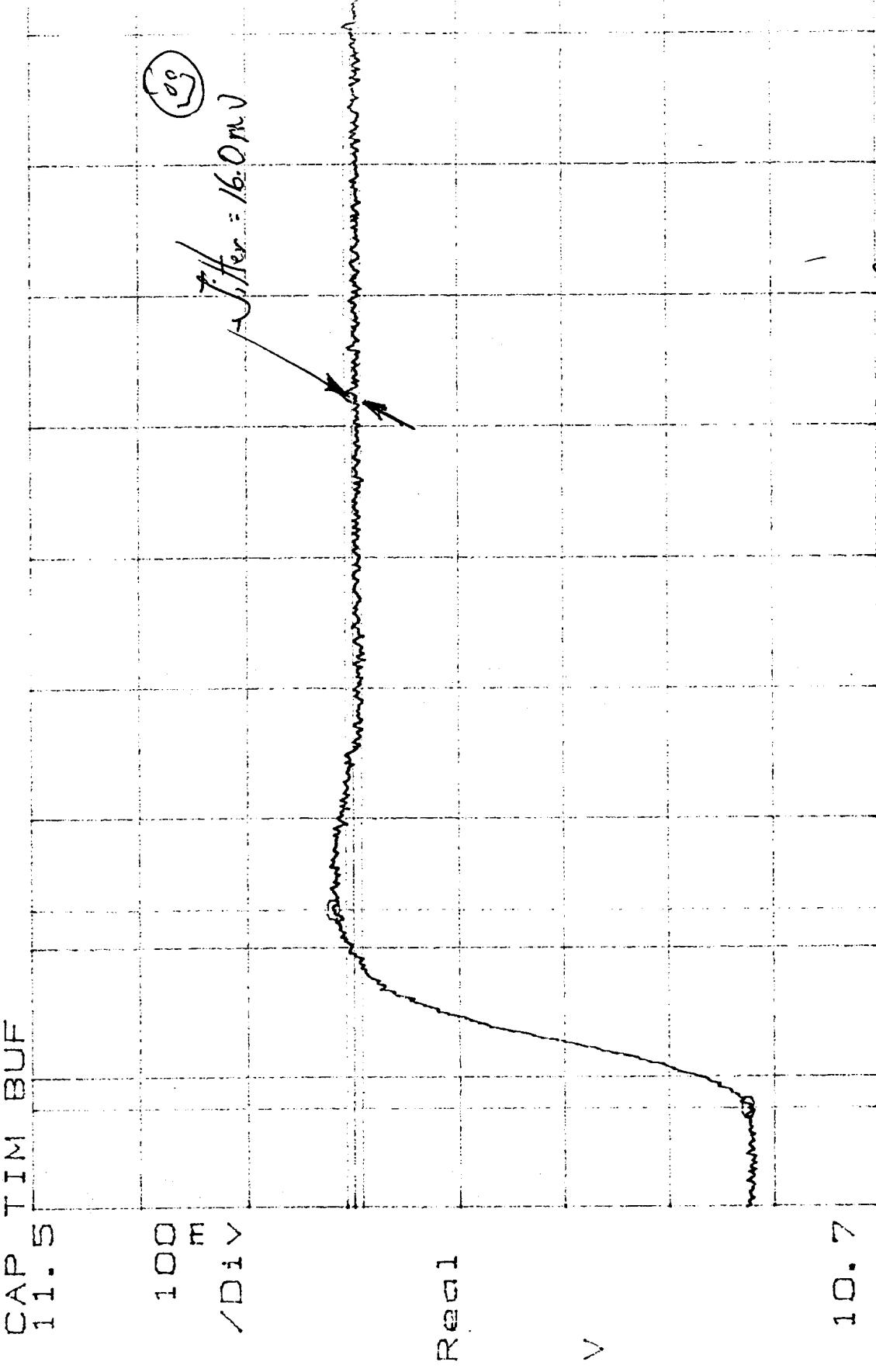
Qualit: JUN 15 1008 ^{7A} ₍₁₉₀₎

Date: 6/12/98

B60

X=5.234 S Y=35.16mS
Y_a=10.8241 A Y_a=394.1mV
CAP TIM BUF

Y=11. 2067 ΔY=16. 0mV



Fixd X 5. 22 Step 27
S6: 436613 3.4.5

P/N: 1331720-2-1T SN: 105

Sec Test Eng: jaydubhag 5. 22 1998

Quality: $\frac{A}{190}$ JUN 15 1998

Block

5. 22 1998

Date: 6/16/98

X=5.437 S AX=35.16mS Y=11.5789 ΔY=17.94mV
Yd=11.1971 ΔYd=397.3mV

CAP TIM BUF

11.8

100
m
/Div

Real

V

11.0

Fxd X 5.41

AI-2

Sec 28

SL: 436613

3.4.1.5

P/N: 1331720-2-1T SN: 105

Sec

Test Eng: Ray Hargan

Quality: JUN 15 1998

7A
190

5.6

Date: 6/15/98

B62

Jitter = 17.94 mV



X=5.64 S 33 A Y=35.16 mS
Y₀=11.57 S 33 A Y₀=39.90 mS
CAP TIN BUF
12.2

Y=11.961

$\Delta Y = 1.03 \cdot 422 \text{mV}$

100
m
D i V

$$V_{eff} = 18.42 \text{ mV}$$

(0.60)

Recal

V

11.4

Fxd X 5.62 Al-2 Ste 29
S/N: 133720-2-17 SN: 105

Sao

3.4.5

Test Eng: *John May*

Date: 06-16-98

Qualif: *TA*

190

JUN 15 1998

5.0

100

150

200

250

300

350

400

450

500

550

600

650

700

750

800

850

900

950

1000

1050

1100

1150

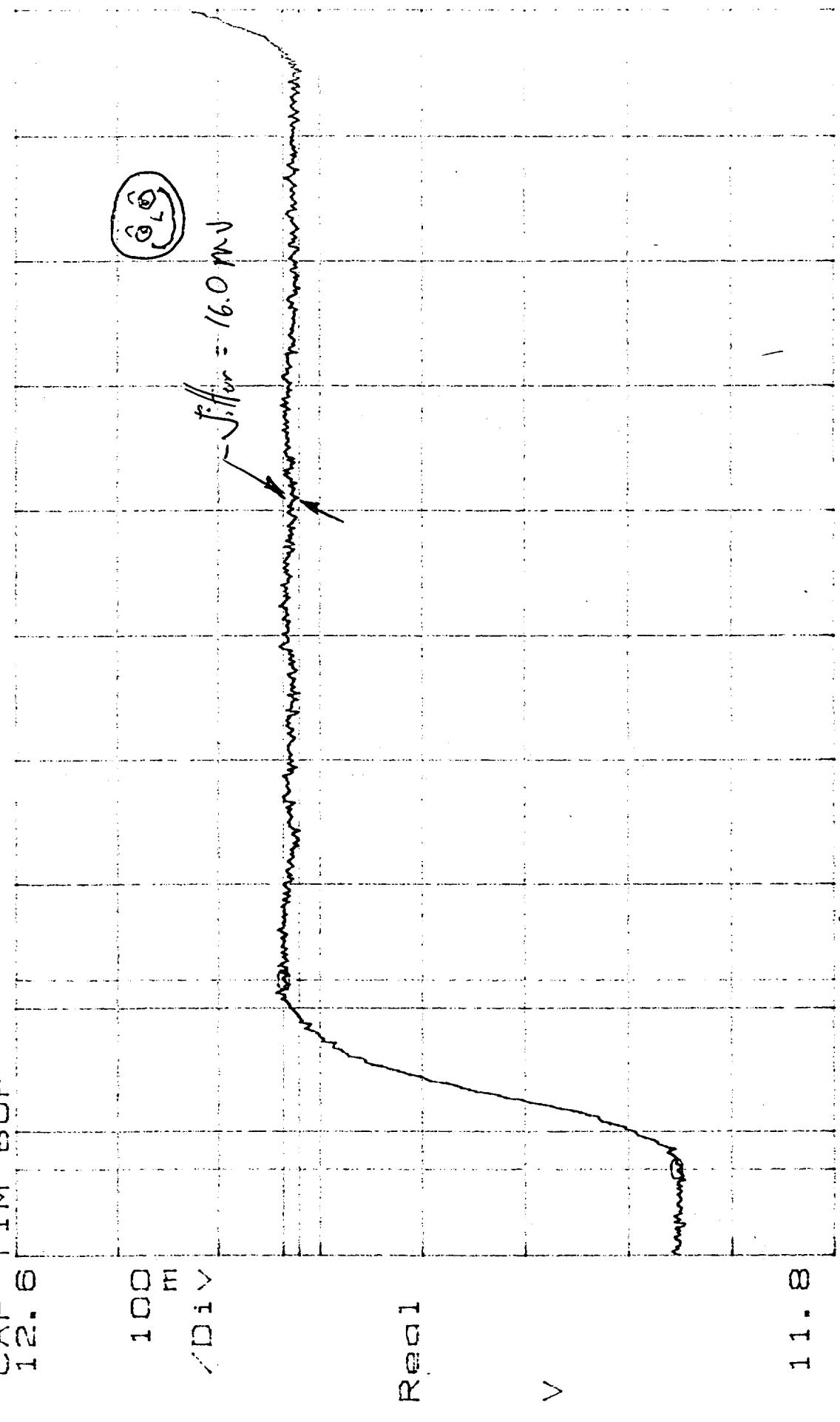
1200

B63

Quality: *John May*
Date: 06-16-98
JUN 15 1998

X=5.84 S $\Delta X=35.16 \text{mS}$
Y=11.9528 $\Delta Y_c=38.1.1 \text{mV}$
CAP TIM BUF
12.6

$\Delta Y=16.0 \text{mV}$



S/N: 1331720-2-1T SN: 105
P/N: 36613

3.4.4.5

Test Eng: John H. Date: Jun 15 1998 ^{7A} ₁₉₀
Quality: B64

X=6.044 S A X=200.4 mS ✓ Y=16.2899

A Y=34.91 mV

CAP TIM BUF
18.4

800
m
✓ DIV

③
Tiff: 34.91 mV

Reo 1

V

12.00

Fixd X 6.04

AI-2 Step Cal

Sec

6.05

S/No: 436613

3.4.4.5

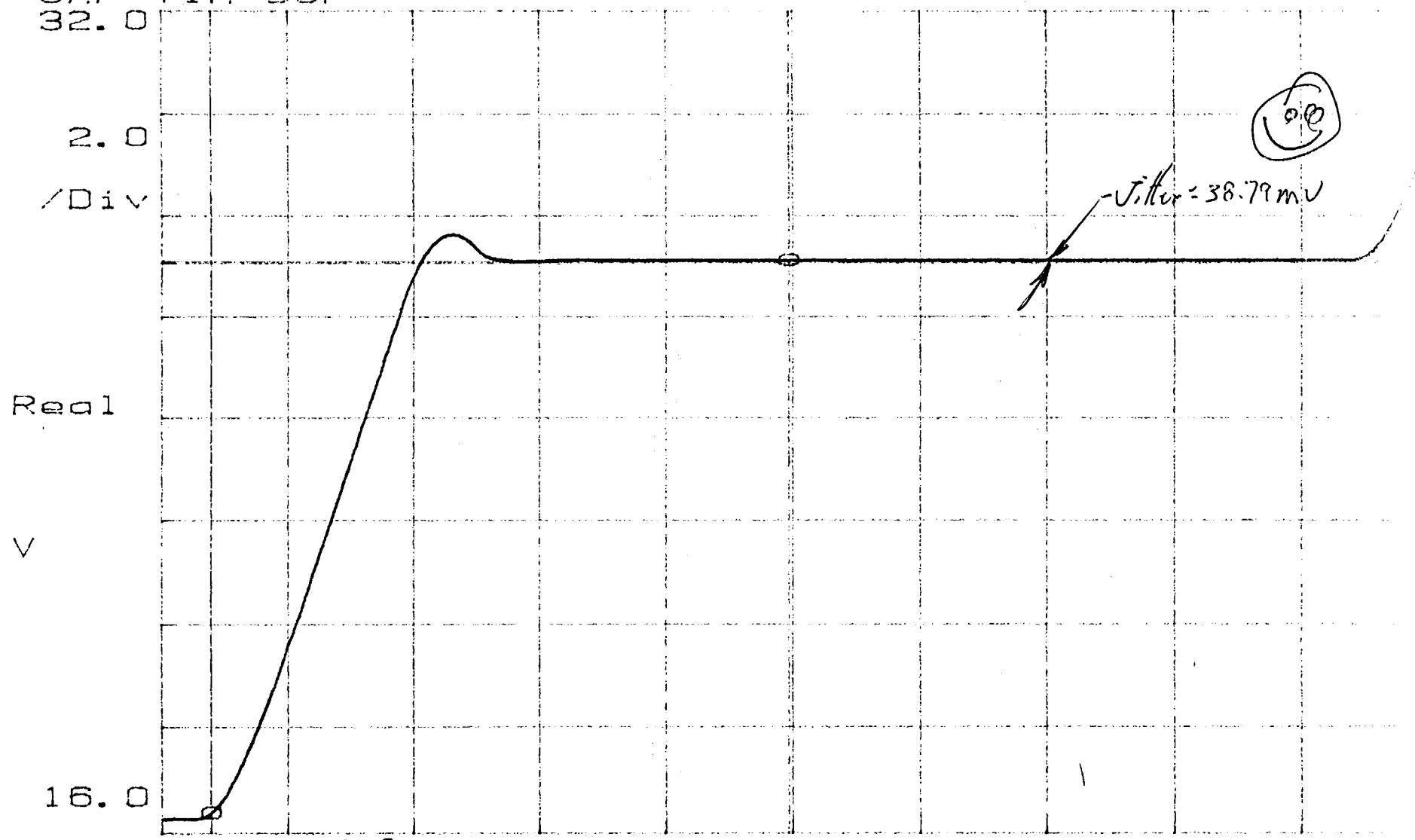
Test Eng: Subhash Kumar Date: 6-12-96

Qualif: 190 JUN 15 1994

Blrs

X=6.67 S $\Delta X=401.2 \text{mS}$ Y=27.0933 $\Delta Y=38.79 \text{mV}$
Y_a=16.3756 $\Delta Y_a=10.74 \text{ V}$

CAP TIM BUF
32.0



Sl: 136613

P/N: 1331720-2-17 SN: 105

Test Eng: Paythong Date: 6-12-98
Quality: JUN 15 1998 (100) B66

12 Feb 98

SHEET 81 OF 82
E&B NO. 1828TEST DATA SHEET 7 (Sheet 1 Of 4)
Scan Motion and Jitter Test (A1-1) (Paragraph 3.4.4.5)

Test Setup Verified:

[Signature]
SignatureShop Order No. 436613

Step No.	Description	Requirement	Test Result	Pass/Fail
7	--	Stepping Slewing <8 sec period per Figure 6	< 8.0 Sec	P
9	Scene 1-2 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
10	Scene 2-3 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
11	Scene 3-4 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
12	Scene 4-5 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
13	Scene 5-6 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
14	Scene 6-7 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
15	Scene 7-8 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
16	Scene 8-9 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P

Pass = P
Fail = F

TEST DATA SHEET 7 (Sheet 2 Of 4)

Scan Motion and Jitter Test (A1-1)

Step No.	Description	Requirement	Test Result	Pass/Fail
17	Scene 9-10 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
18	Scene 10-11 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
19	Scene 11-12 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
20	Scene 12-13 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
21	Scene 13-14 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
22	Scene 14-15 3.33° step	<35 msec rise time per Figure 7	<u>R.H. 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
23	Scene 15-16 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P
24	Scene 16-17 3.33° step	<35 msec rise time per Figure 7	<u>< 35 msec</u>	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	<u>< ±5%</u> <u>< 3%</u>	P

Pass = P
Fail = F

B67B

SHEET 3 OF 4
TEST NO. 1828TEST DATA SHEET 7 (Sheet 3 Of 4)
Scan Motion and Jitter Test (A1-1)

Step No.	Description	Requirement	Test Result	Pass/Fail
25	Scene 17-18 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
26	Scene 18-19 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
27	Scene 19-20 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
28	Scene 20-21 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
29	Scene 21-22 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
30	Scene 22-23 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
31	Scene 23-24 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
32	Scene 24-25 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P

Pass = P
Fail = F

TEST DATA SHEET 7 (Sheet 4 Of 4)
Scan Motion and Jitter Test (A1-1)

Step No.	Description	Requirement	Test Result	Pass/Fail
33	Scene 25-26 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
34	Scene 26-27 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
35	Scene 27-28 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
36	Scene 28-29 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
37	Scene 29-30 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
38	Scene 30 Cold Cal 35.0° slew	<0.21 sec slew time per Figure 10	< 0.21 sec	P
		< ±0.165° jitter per Figure 11	< ±0.165°	P
39	Cold Cal - Warm Cal 96.67° slew	<0.40 sec slew time per Figure 12	< 0.40 sec	P
		< ±0.165° jitter per Figure 13	< ±0.165°	P

Pass = P
Fail = F

Unit: AMSU METSAT A1

Serial No.: 105

Date: 6-12-98

Test Engineer:

Quality Assurance:

Customer Representative:

JUN 1998

MAY 16 1998

B67 D

Supplimental Data to Test Data Sheet 7
METSAT A1-1 S/N: 105

Scene Number	Rise Time to Scene	Overshoot %	Jitter ± %
1	N/A	N/A	NDJ
2	25.0	NDO	0.7
3	25.4	NDO	0.5
4	27.7	NDO	1.0
5	25.8	NDO	1.1
6	25.8	NDO	1.3
7	24.6	NDO	1.3
8	25.8	NDO	NDJ
9	25.0	0.8	1.5
10	26.6	NDO	0.8
11	25.8	NDO	0.9
12	26.2	NDO	0.8
13	26.6	NDO	0.9
14	26.2	NDO	0.8
15	25.4	NDO	1.3
16	27.3	NDO	NDJ

Scene Number	Rise Time to Scene	Overshoot %	Jitter ± %
17	25.8	NDO	NDJ
18	25.4	NDO	0.8
19	26.2	NDO	1.0
20	28.5	NDO	0.9
21	25.0	NDO	0.6
22	28.1	NDO	0.5
23	25.4	NDO	1.1
24	24.2	NDO	1.9
25	27.3	NDO	NDJ
26	25.4	NDO	NDJ
27	23.9	NDO	3.0
28	22.3	NDO	NDJ
29	24.6	NDO	NDJ
30	26.2	NDO	0.5
CC	69.1	N/A	2.08
WC	142.6	N/A	1.03

Rise Time measured in ms.

"NDO" - No Discernible Overshoot

"NDJ" - No Discernible Jitter

Test Engineer : Tom H. Smith

Data retrieved from disk file: 7AP_FS51

B67-E

TEST DATA SHEET 8 (Sheet 1 Of 4)
Scan Motion and Jitter Test (A1-2) (Paragraph 3.4.4.5)

Test Setup Verified:

Ray Hennig
SignatureShop Order No. 436613

Step No.	Description	Requirement	Test Result	Pass/Fail
44	--	Stepping Slewing <8 sec period per Figure 6	< 8.0 Sec	P
9	Scene 1-2 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
10	Scene 2-3 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
11	Scene 3-4 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
12	Scene 4-5 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
13	Scene 5-6 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
14	Scene 6-7 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
15	Scene 7-8 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
16	Scene 8-9 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P

Pass = P
Fail = F

SHEET 86 OF 1823

TEST DATA SHEET 8 (Sheet 2 Of 4)
Scan Motion and Jitter Test (A1-2)

Step No.	Description	Requirement	Test Result	Pass/Fail
17	Scene 9-10 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
18	Scene 10-11 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
19	Scene 11-12 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
20	Scene 12-13 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
21	Scene 13-14 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
22	Scene 14-15 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
23	Scene 15-16 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
24	Scene 16-17 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P

Pass = P
Fail = F

B68 B

TEST DATA SHEET 8 (Sheet 3 Of 4)
Scan Motion and Jitter Test (A1-2)

Step No.	Description	Requirement	Test Result	Pass/Fail
25	Scene 17-18 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
26	Scene 18-19 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
27	Scene 19-20 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
28	Scene 20-21 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
29	Scene 21-22 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
30	Scene 22-23 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
31	Scene 23-24 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
32	Scene 24-25 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P

Pass = P
Fail = F

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AE-26002/1D
12 Feb 98

TEST DATA SHEET 8 (Sheet 4 Of 4)
Scan Motion and Jitter Test (A1-2)

Step No.	Description	Requirement	Test Result	Pass/Fail
33	Scene 25-26 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
34	Scene 26-27 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
35	Scene 27-28 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
36	Scene 28-29 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
37	Scene 29-30 3.33° step	<35 msec rise time per Figure 7	< 35 msec	P
		< ±5% jitter per Figure 7 < 3% overshoot for 10 msec	< ±5% < 3%	P
38	Scene 30 Cold Cal 35.0° slew	<0.21 sec slew time per Figure 10	< 0.21 sec	P
		< ±0.165° jitter per Figure 11	< ±0.165°	P
39	Cold Cal - Warm Cal 96.67° slew	<0.40 sec slew time per Figure 12	< 0.40 sec	P
		< ±0.165° jitter per Figure 13	< ±0.165°	P

Pass = P
Fail = F

Unit: AAS118 MEWSAT A1

Test Engineer: Ray Bergman Jr

MAY 6 1998

Serial No.: 105

Quality Assurance: 741 June

Date: 6-12-98

Customer Representative: R. Dunn Shultz

B68D

Supplimental Data to Test Data Sheet 8
METSAT A1-2 S/N: 105

Scene Number	Rise Time to Scene	Overshoot %	Jitter ± %
1	N/A	N/A	NDJ
2	25.4	NDO	0.4
3	28.5	NDO	2.3
4	27.3	NDO	0.9
5	25.0	NDO	0.6
6	25.8	NDO	0.8
7	26.2	NDO	0.7
8	23.8	NDO	NDJ
9	25.8	NDO	1.1
10	26.6	NDO	1.0
11	26.9	NDO	0.7
12	25.8	NDO	0.9
13	25.0	NDO	0.7
14	25.4	NDO	0.6
15	25.4	NDO	0.6
16	26.2	NDO	1.1

Scene Number	Rise Time to Scene	Overshoot %	Jitter ± %
17	25.8	NDO	0.6
18	26.1	NDO	0.7
19	27.3	NDO	0.7
20	26.5	NDO	0.5
21	24.6	NDO	0.6
22	25.8	NDO	NDJ
23	25.4	NDO	0.9
24	25.4	NDO	NDJ
25	25.8	NDO	NDJ
26	26.6	NDO	0.7
27	25.4	NDO	NDJ
28	25.8	NDO	NDJ
29	25.0	NDO	1.0
30	27.3	NDO	0.9
CC	69.5	N/A	0.65
WC	150.4	N/A	NDJ

Rise Time measured in ms.

"NDO" - No Discernible Overshoot

"NDJ" - No Discernible Jitter

Test Engineer: 

Data retrieved from disk file: 44AP_FS5

B68-E

APPENDIX C

***PULSE LOAD CURRENT WAVEFORM
AND TEST DATA SHEET***

$\gamma = -690.91 \mu$ $\Delta \gamma = 49.84 \text{ mV}$

CAP TIM BUF

m

10.0
m

10.0
m

100ma/div

R_{DET} ≤ 1.0 A

$$19.8 \text{ div} \times 200 \text{ ma/div} = \underline{\underline{996 \text{ mA}}}$$

(10)



Road 1

V

-10.0
m

10.0
m

4PLB-C

Sec

WARM CAL

8.0

Test Eng: Jay Gauthier

Shots: 6-15-98

Nr: 13317202-1T SN: 105

3.4.4.6

436613

7A

1 JUN 15 1998

C1

12 Feb 98

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SCR NO. 1828

TEST DATA SHEET 9

28V Bus Peak Current and Rise Time Test (Paragraph 3.4.4.6)

Test Setup Verified:

Ray Hurlberg
SignatureShop Order No. 436613

Step No.	Requirement	Test Result	Pass/Fail
4	< 1 A peak any place in the scan	996 mA	P
5	> 35 μ sec rise time, 3.33° step	1.172 msec	P
6	> 35 μ sec rise time, start of WC slew	1.172 msec	P
6	> 35 μ sec rise time, end of WC slew	5.469 msec	P

Pass = P
Fail = FUnit: AMSL METSAT A1Serial No.: 105Test Engineer: *Ray Hurlberg* JUNEQuality Assurance: *Ray Hurlberg* MAY 16 19987A
190Date: 6-15-98

APPENDIX D

***GAIN AND PHASE MARGIN PLOTS
AND TEST DATA SHEETS***

X=54.481 Hz
Yd=-13.091 dB

M: FREQ RESP
10.0

dB

-90.0

FxdXY 999.99m
Yb=-179.89 Deg

M: FREQ RESP
90.0

Phase

Deg

-720

Fxd Y 999.99m

-157.923 u dB

13.091 dB GAIN MARGIN



Log Hz

-115.29 deg + 180 = 64.71 deg PHASE MARGIN



1k

IIGP_B12

A-1

Log Hz

1k

3.4.4.B

Test Eng: P. H. Berg
D. 14: (24) (190) 24.98

Date: 6-16-98

436613

1821720-2-1T 511 105

D1

X=54.481 Hz
Yd=-13.079 dB

M: FREQ RESP

10.0

dB

-90.0

FxdXY 999.99m
Yb=-179.95 Deg

M: FREQ RESP

90.0

Phase

Deg

-720

Fxd Y 999.99m

13GP_B21 A1

Log Hz

1k

136613

3.4.4.8

Test Eng: Ray Hughey
Modif:

7A
190

MM 24 98

Date: 6-16-98

1331720-2-1T SN: 105

D2

27.167 mDB

13.079 dB GAIN MARGIN

90

Log Hz

1k

F=115.24 deg + 180 = 64.76 deg PHASE MARGIN

90

X=54.481 Hz
Y_a=-13.075 dB

M: FREQ RESP
10.0

dB

-90.0

FxdXY 999.99m

Y_b=-179.97 Deg

M: FREQ RESP

90.0

Phase

Deg

-720

Fxd Y 999.99m

13GP_B31 A1-1

344.8

-16.553 dB

13.075 dB GAIN MARGIN

Log Hz

1k

$-115.49 \text{ deg} + 180 = 64.51 \text{ deg}$ PHASE MARGIN



Log Hz

1k

Ref: 136613

Test Eng: Paybuphey

Date: 6-16-99

TA 2498

D3

X=56.396 Hz
Yd=-12.785 dB

M: FREQ RESP
10. 0

dB

-90. 0

FxdXY 999.99m
Yb=-180.67 Deg
M: FREQ RESP

90. 0

Phase

Deg

-720

Fxd Y 999.99m

11GP_B13 A1-2

Log Hz

1k

21.989 dB

12.785 dB GAIN MARGIN



S10: 436613

3.4.7.8

Test Eng: *Layton H. Berg*
D. I. T.

TA
190
JUN 24 1998

Date: 6-16-98

1021773-2-1T 01:105

D4

X=56.396 Hz
Y_a=-12.735 dB

M: FREQ RESP
10.0

dB

-90.0

FxdXY 999.99m
Y_b=-180.75 Deg

M: FREQ RESP
90.0

Phase

Deg

-720

Fxd Y 999.99m

13GP-B22

A1-2

LOG Hz

1k

9.2897 dB

-12.735 dB GAIN MARGIN

OK

S/N: 436613

3.4.4.8

Test Eng: Ray Haffey

Date: 6-16-98

REV: 1331720-2-1T SN: 105

Qualitx:

TA
190
JUN 24 98

D5

-115.8 deg. + 180 = 64.20 deg PHASE MARGIN

OK

X=56.396 Hz
Ydb=-12.811 dB



M: FREQ RESP

10.0

dB

-90.0

FxdXY 999.99m
Ydb=-180.82 Deg



M: FREQ RESP

90.0

Phase

Deg

-720

Fxd Y 999.99m

13GP-B32

A1-2 LOG Hz

1K

S/N: 136613

P/N: 1331720-2-1T SN: 105

3.4.4.8

Test End: Kay Huyberg
Date: 6-16-98
JUN 24 1998
190

Quality:

D6

8.5610m dB

12.811 dB GAIN MARGIN

TEST DATA SHEET 10
Gain/Phase Margin (A1-1) (Paragraph 3.4.4.8)

Test Setup Verified:

Ray Hertberg
SignatureShop Order No. 436613Temperature: 71.5 °F

Requirement	Test Result		Pass/Fail
9.2 dB minimum	1	13.095 dB	P
	2	13.079 dB	P
	3	13.075 dB	P
	4		
	5		
25 degrees minimum	1	64.71 deg	P
	2	64.76 deg	P
	3	64.51 deg	P
	4		
	5		

Deleted Per
Customer Request
Ray Hertberg
02/21/98

Pass = P
Fail = FUnit: ANSI MTSAT A1Serial No.: 105Date: 6-16-98Test Engineer: Ray HertbergQuality Assurance: JW 2/21/98Customer Representative: R. Durrell 2/19/98

12 Feb 98

SHEET 91 OF
ECR NO. 18250TEST DATA SHEET 11
Gain/Phase Margin (A1-2) (Paragraph 3.4.4.8)

Test Setup Verified:

Ray Herffberg
Signature

Shop Order No. 136613

Temperature: 71.4 °C

Requirement	Test Result		Pass/Fail
9.2 dB minimum	1	12.785 dB	P
	2	12.735 dB	P
	3	12.811 dB	P
	4		
	5		
25 degrees minimum	1	64.09 deg	P
	2	64.20 deg	P
	3	64.15 deg	P
	4		
	5		

*- Deleted Per
Customer Request**R. Herffberg*
1-21-98
DOE
DOEPass = P
Fail = F

Unit: AMSU METSAT A1

Serial No.: 105

Date: 6-16-98

Test Engineer: *Ray Herffberg*Quality Assurance: *7A
190*Customer Representative: *R. Herffberg 8/19/98*

APPENDIX E

***OPERATIONAL GAIN MARGIN POWER SPECTRUM
PLOTS AND TEST DATA SHEETS***

X=161.97 Hz
Yg=-39.275 dBVrms

POWER SPEC2
-10f

6Avg D%Cv1P Unif

10.0

/Div

dB

rms
v2

-90.0

Fwd Y 250m

120F_PII

A1-1

Hz

312.75

No: 136613

3.4.4.9

101 1331720-2-1T SN: 105

Rrot = 35.926 K_L

GAIN = 8.986 dB

RQMT \geq 8 dB



Test Eng: Ray H. H. H.

Date: 6-16-98

P.11

(74)
190 JUN 24 98

E1

Y=172.5296 Hz

POWER SPEC2
=10

3Avg 0%Ov1P Unif
0%Ov2

$$R_{\text{pot}} = 38.901 \text{ k}\Omega$$

$$R_{\text{S8}} = 17.0 \text{ k}\Omega$$

$$G_{\text{AV}} = 9.440 \text{ dB}$$

$$R_{\text{QANT}} \geq 8 \text{ dB}$$

/Div

10.0

-4B

rms
 $\sqrt{2}$

-90.0

Freq Y 250m 120F - P/2 A/2 Hz

3.4.4.9

S/N: 436613

AA: 133172.5-7-1T ch: 105

H2

312.75

Date: 6/7/98

E2

7A
IM 2A

100

3.4.4.9

TEST DATA SHEET 12
Operational Gain Margin (A1-1) (Paragraph 3.4.4.9)Test Setup Verified: Ray Hertberg
SignatureShop Order No. 436613Temperature: 71.4 °C

Step No.	Requirement	Test Result		Pass/Fail
11	R58 Resistance (kohms)	1	35.926 K Ω	P
	Test Pot Resistance (kohms)	2	37.34 K Ω	
		3	37.394 K Ω	
12	Oscillation Frequency (Hz)	1	161.97 Hz	P
		2	160.41 Hz	
		3	160.41 Hz	
16	Gain Margin, 8 dB minimum	1	8.986 dB	P
		2	9.205 dB	
		3	9.213 dB	

Pass = P
Fail = FUnit: AKSA METSAT A1
Serial No.: 105Test Engineer: Ray Hertberg
Quality Assurance: 2A 190 JUN 24 98Date: 6-17-98

E3

12 Feb 98

SHEET 93 OF 1828
ECR NO. 1828

TEST DATA SHEET 13
Operational Gain Margin (A1-2) (Paragraph 3.4.4.9)

Test Setup Verified: Ray Hertberg Shop Order No. 436613
Signature

Temperature: 76.4 °C

Step No.	Requirement	Test Result		Pass/Fail
11	R58 Resistance (kohms)	1	38.901 KΩ	P
	Test Pot Resistance (kohms)	2	37.56 KΩ	
		3	37.61 KΩ	
12	Oscillation Frequency (Hz)	1	172.52 Hz	P
		2	172.52 Hz	
		3	172.12 Hz	
16	Gain Margin, 8 dB minimum	1	9.44 dB	P
		2	9.238 dB	
		3	9.246 dB	

Pass = P
Fail = F

Unit: AMSL NETSAT A1
Serial No.: 105

Test Engineer: Ray HertbergQuality Assurance: 7A 190 JUN 98Date: 6-17-98

FORMS

 National Aeronautics and Space Administration			
Report Documentation Page			
1. Report No. ---	2. Government Accession No. ---	3. Recipient's Catalog No. ---	
4. Title and Subtitle Integrated Advanced Microwave Sounding Unit-A (AMSU-A), Performance Verification Report		5. Report Date September 1998	
		6. Performing Organization Code ---	
7. Author(s) A. Nieto		8. Performing Organization Report No. 11220	
		10. Work Unit No. ---	
9. Performing Organization Name and Address Aerojet 1100 W. Hollyvale Azusa, CA 91702		11. Contract or Grant No. NAS 5-32314	
		13. Type of Report and Period Covered Final	
12. Sponsoring Agency Name and Address NASA Goddard Space Flight Center Greenbelt, Maryland 20771		14. Sponsoring Agency Code ---	
15. Supplementary Notes ---			
16. ABSTRACT (Maximum 200 words) This is the Performance Verification Report, Subassembly and Complete Instrument Assembly, AMSU-A1 Antenna Drive Subsystem, P/N 1331720-2, S/N 105 For The EOS/AMSU-A1 for the Integrated Advanced Microwave Sounding Unit-A (AMSU-A).			
17. Key Words (Suggested by Author(s)) EOS Microwave System		18. Distribution Statement Unclassified --- Unlimited	
19. Security Classif. (of this report) Unclassified	20. Security Classif. (of this page) Unclassified	21. No. of pages	22. Price ---

NASA FORM 1626 OCT 86

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1. AGENCY USE ONLY (Leave blank)	2. REPORT DATE	3. REPORT TYPE AND DATES COVERED	
4. TITLE AND SUBTITLE Integrated Advanced Microwave Sounding Unit-A (AMSU-A), Performance Verification Report		5. FUNDING NUMBERS NAS 5-32314	
6. AUTHOR(S) A. Nieto			
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Aerojet 1100 W. Hollyvale Azusa, CA 91702		8. PERFORMING ORGANIZATION REPORT NUMBER 11220 September 1998	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) NASA Goddard Space Flight Center Greenbelt, Maryland 20771		10. SPONSORING/MONITORING AGENCY REPORT NUMBER ---	
11. SUPPLEMENTARY NOTES ---			
12a. DISTRIBUTION/AVAILABILITY STATEMENT ---		12b. DISTRIBUTION CODE ---	
13. ABSTRACT (Maximum 200 words) This is the Performance Verification Report, Subassembly and Complete Instrument Assembly, AMSU-A1 Antenna Drive Subsystem, P/N 1331720-2, S/N 105 For The EOS/AMSU-A1 for the Integrated Advanced Microwave Sounding Unit-A (AMSU-A).			
14. SUBJECT TERMS EOS Microwave System			15. NUMBER OF PAGES
			16. PRICE CODE ---
17. SECURITY CLASSIFICATION OF REPORT Unclassified	18. SECURITY CLASSIFICATION OF THIS PAGE Unclassified	19. SECURITY CLASSIFICATION OF ABSTRACT Unclassified	20. LIMITATION OF ABSTRACT SAR

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